

# TOSHIBA

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**T300MV2<sup>®</sup>/MTX<sup>®</sup>/MTX2<sup>®</sup>**

MEDIUM VOLTAGE 

**ADJUSTABLE SPEED MOTOR DRIVE**

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## INSTRUCTION MANUAL

**TOSHIBA INTERNATIONAL CORPORATION**

Document Number: IF08CZ10  
Rev 8 April 2021

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Printed in U.S.A.

## Important Notice

The instructions contained in this manual are not intended to cover all details or variations in equipment types, nor may it provide for every possible contingency concerning the installation, operation, or maintenance of this equipment. Should additional information be required contact your Toshiba representative.

The contents of this manual shall not become a part of or modify any prior or existing agreement, commitment, or relationship. The sales contract contains the entire obligation of Toshiba International Corporation. The warranty contained in the contract between the parties is the sole warranty of Toshiba International Corporation and any statements contained herein do not create new warranties or modify the existing warranty.

**Any electrical or mechanical modifications to this equipment without prior written consent of Toshiba International Corporation will void all warranties and may void the UL/CUL listing or other safety certifications. Unauthorized modifications may also result in a safety hazard or equipment damage.**

**Misuse of this equipment could result in injury and equipment damage. In no event will Toshiba Corporation be responsible or liable for either indirect or consequential damage or injury that may result from the misuse of this equipment.**

### TOSHIBA INTERNATIONAL CORPORATION

#### Adjustable Speed Drive

Please complete the Warranty Card supplied with the ASD and return it to Toshiba by prepaid mail. This will activate the 12 month warranty from the date of installation; but, shall not exceed 18 months from the date of purchase.

Complete the following information about the drive and retain it for your records.

Model Number: \_\_\_\_\_

Serial Number: \_\_\_\_\_

Project Number (if applicable): \_\_\_\_\_

Date of Installation: \_\_\_\_\_

Inspected By: \_\_\_\_\_

Name of Application: \_\_\_\_\_

## Manual's Purpose and Scope

This manual provides information on how to safely install, operate, and maintain your TIC power electronics product. This manual includes a section of general safety instructions that describes the warning labels and symbols that are used throughout the manual. Read the manual completely before installing, operating, or performing maintenance on this equipment.

This manual and the accompanying drawings should be considered a permanent part of the equipment and should be readily available for reference and review. Dimensions shown in the manual are in metric and/or the English equivalent.

Toshiba International Corporation reserves the right, without prior notice, to update information, make product changes, or to discontinue any product or service identified in this publication.

TOSHIBA is a registered trademark of the Toshiba Corporation. All other product or trade references appearing in this manual are registered trademarks of their respective owners.

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## Contacting Toshiba's Customer Support Center

Toshiba's Customer Support Center can be contacted to obtain help in resolving any **Adjustable Speed Drive** system problem that you may experience or to provide application information.

The center is open from 8 a.m. to 5 p.m. (CST), Monday through Friday. The Support Center's toll free number is US (800) 231-1412/Fax (713) 466-8773 — Canada (800) 527-1204.

You may also contact Toshiba by writing to:

Toshiba International Corporation  
13131 West Little York Road  
Houston, Texas 77041-9990  
Attn: CASD Product Manager.

For further information on Toshiba's products and services, please visit our website at [www.toshiba.com/tic](http://www.toshiba.com/tic).

## General Safety Instructions

**DO NOT** attempt to install, operate, maintain or dispose of this equipment until you have read and understood all of the product safety information and directions that are contained in this manual.

### Safety Alert Symbol

The **Safety Alert Symbol** indicates that a potential personal injury hazard exists. The symbol is comprised of an equilateral triangle enclosing an exclamation mark.



### Signal Words

Listed below are the signal words that are used throughout this manual followed by their descriptions and associated symbols. When the words **DANGER**, **WARNING** and **CAUTION** are used in this manual they will be followed by important safety information that must be adhered to.

The word **DANGER** preceded by the safety alert symbol indicates that an imminently hazardous situation exists that, if not avoided, will result in death or serious injury to personnel.



**DANGER**

The word **WARNING** preceded by the safety alert symbol indicates that a potentially hazardous situation exists that, if not avoided, could result in death or serious injury to personnel.



**WARNING**

The word **CAUTION** preceded by the safety alert symbol indicates that a potentially hazardous situation exists which, if not avoided, may result in minor or moderate injury.



**CAUTION**

The word **CAUTION** without the safety alert symbol indicates a potentially hazardous situation exists which, if not avoided, may result in equipment and property damage.

**CAUTION**

## Special Symbols

To identify special hazards, other symbols may appear in conjunction with the **DANGER**, **WARNING** and **CAUTION** signal words. These symbols indicate areas that require special and/or strict adherence to the procedures to prevent serious injury to personnel or death.

### Electrical Hazard Symbol

A symbol which indicates a hazard of injury from electrical shock or burn. It is comprised of an equilateral triangle enclosing a lightning bolt.



### Explosion Hazard Symbol

A symbol which indicates a hazard of injury from exploding parts. It is comprised of an equilateral triangle enclosing an explosion image.



### Arc Flash Hazard Symbol

A symbol which indicates a hazard of injury from arc flash. It is comprised of an equilateral triangle enclosing an arc flash image.



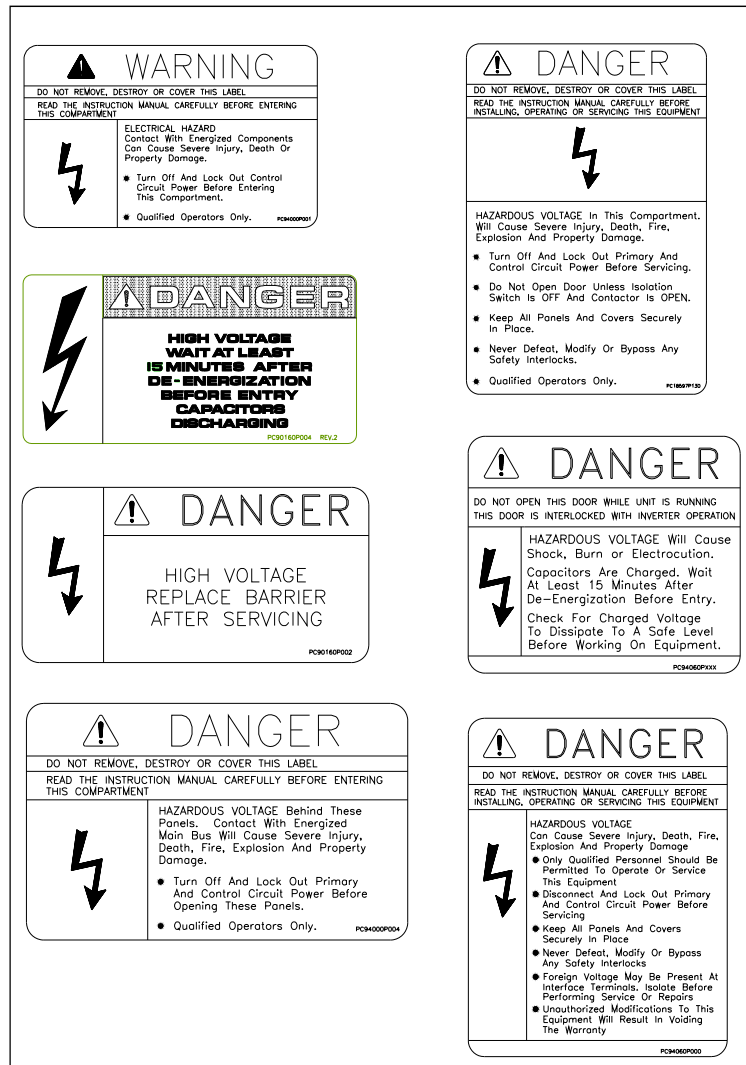
## Equipment Labels (Safety, Rating, Information)

**DO NOT** attempt to install, operate, perform maintenance, or dispose of this equipment until you have read and understood all of the product labels and user directions that are contained in this manual.

Shown below are examples of safety labels that may be found attached to the equipment. **DO NOT** remove or cover any of the labels. If the labels are damaged or if additional labels are required, contact your Toshiba representative for additional labels.

Labels attached to the equipment are there to provide useful information or to indicate an imminently hazardous situation that may result in serious injury, severe property and equipment damage, or death if the instructions are not followed.

**SAFETY labels that will be found on the equipment are shown below:**



Additional SAFETY labels that will be found on the equipment or in the manual that has the CE mark applied are shown below:



Electrical hazard.



Electrical hazard with a minimum discharge time listed below.

xxx MIN



Electrical hazard with the system rated voltage listed below.

xxxxx V



Do not remove covers or panels when energized.



Burn hazard from high surface temperatures.



Use and follow lock out tag out procedures



Read the manual.

Some additional SAFETY labels that may be found on the equipment are shown below:

|  |   |  |
|--|---|--|
|  | DANGER  | <b>WARNING</b><br>MULTIPLE SOURCES OF ELECTRICAL SUPPLY PRESENT.<br>DE-ENERGIZE ALL ELECTRICAL SUPPLIES BEFORE SERVICING<br><small>PC94060P290</small> |
| DO NOT REMOVE, DESTROY OR COVER THIS LABEL                             |   |  |
| READ THE INSTRUCTION MANUAL CAREFULLY BEFORE ENTERING THIS COMPARTMENT |   |  |
|  | <p>This Equipment Does Not Provide Isolation</p> <p>Separate Isolation Means Required</p> <p>HAZARDOUS VOLTAGE Behind This Panel. Contact With Energized Parts Will Cause Severe Injury, Death, Fire, Explosion And Property Damage</p> <p>See The Input Section Data Label And Drawing Number I508KW03 For Specific Requirements</p> <p style="text-align: right; font-size: 8pt;">PC94060P290</p> |  |



RATING labels that will be found on the equipment are shown below:

**TOSHIBA INTERNATIONAL CORPORATION**  
**INPUT SECTION FOR MV ADJUSTABLE SPEED MOTOR DRIVE**

Controller Type: \_\_\_\_\_ Mfg. Date: \_\_\_\_\_  
 JK SERIES NEMA CLASS \_\_\_\_\_  
U.S. PATENT NO. 5,481,075  
 (2.4-8.9kV INPUT)  
 FUSED LOAD BREAK SWITCH/CONTACTOR  
(7.2-13.8kV INPUT)  
 NON FUSED LOAD BREAK SWITCH/CONTACTOR  
(7.2-13.8kV INPUT)  
 EXTERNAL INPUT CONTROLLER

Controller Interrupting Capacity: \_\_\_\_\_ A RMS Sym.  
 Contactor Interrupting Capacity: \_\_\_\_\_ A RMS Sym.  
 Impulse Test Voltage (BIL): \_\_\_\_\_ kV

This Controller Equipped For:  
 Utilization Voltage: \_\_\_\_\_ V Freq: \_\_\_\_\_ Hz  
 Max. Short Circuit Capacity: \_\_\_\_\_ MVA \_\_\_\_\_ Phase  
 Transformer Capacity: \_\_\_\_\_ kVA  
 Full Load A: \_\_\_\_\_ Overload: \_\_\_\_\_

This Controller Configured As Follows:  
 Power Fuse Type: \_\_\_\_\_  
 Power Fuse Current Rating: \_\_\_\_\_ Max. Volt: \_\_\_\_\_ kV  
 CT Type: \_\_\_\_\_ Ratio: \_\_\_\_\_ Amps  
 Control Voltage: \_\_\_\_\_ V Freq: \_\_\_\_\_ Hz  
 Contactor Type: \_\_\_\_\_  
 CPT-1 Size: \_\_\_\_\_ kVA Pri/Sec. Volt: \_\_\_\_\_  
 CPT-2 Size: \_\_\_\_\_ kVA Pri/Sec. Volt: \_\_\_\_\_

Schematic Diagram: \_\_\_\_\_  
 Optional Features: \_\_\_\_\_  
 \_\_\_\_\_  
 \_\_\_\_\_

Unit No. \_\_\_\_\_  
 Job No. \_\_\_\_\_

PC94060P116

Input Controller Rating Label

Note: If no input controller is supplied, this label will indicate the required fuses and the minimum acceptable ratings for the external controller.

PROJ#/DWG#: \_\_\_\_\_  
 TYPE FORM: \_\_\_\_\_

CAPACITY: \_\_\_\_\_ kVA \_\_\_\_\_ kW \_\_\_\_\_ HP  
 INPUT: \_\_\_\_\_ kV \_\_\_\_\_ A \_\_\_\_\_ Hz \_\_\_\_\_  $\phi$   
 OUTPUT: \_\_\_\_\_ kV \_\_\_\_\_ A \_\_\_\_\_ Hz \_\_\_\_\_  $\phi$   
 CONTROL: \_\_\_\_\_ V \_\_\_\_\_ A \_\_\_\_\_ Hz \_\_\_\_\_  $\phi$   
 SERIAL #: \_\_\_\_\_ MFD. DATE: \_\_\_\_\_

Suitable For Use On a Circuit Capable of Delivering Not More Than \_\_\_\_\_ RMS Sym. Amperes \_\_\_\_\_ kV Maximum.

IMPULSE TEST VOLTAGE (BIL): \_\_\_\_\_ kV

TOSHIBA INTERNATIONAL CORPORATION  
 13131 W. LITTLE YORK RD., HOUSTON, TEXAS  
 TELEPHONE (713)466-0277 PC94060P024

Adjustable Speed Drive Rating Label

TYPE-FORM : \_\_\_\_\_  
 RATING : \_\_\_\_\_  
 MFG. DATE : \_\_\_\_\_  
 SERIAL NO. : \_\_\_\_\_

**TOSHIBA INTERNATIONAL CORPORATION**

Inverter Power Module Rating Label

Note:

The above labels are shown blank. The labels affixed to the equipment will be filled in with rating data specific to the actual unit(s) furnished. Complete rating data is also provided on the rating sheet included in the supplementary drawing packet. Ensure that all rating data matches the power system and the driven load connected to the equipment.

INFORMATION labels that may be found on the equipment are shown below:

| TORQUE VALUES<br>VALEURS DE COUPLES           |                             |                              |
|---|-----------------------------|------------------------------|
| HARDWARE<br>SIZE<br>TAILLE DE<br>L'ÉQUIPEMENT | TORQUE<br>COUPLE<br>(ft-lb) | TORQUE<br>COUPLE<br>(kgf-cm) |
| 1/4-20  | 4~6                         | 55~83                        |
| 5/16-18                                       | 10~15                       | 138~207                      |
| 3/8-16  | 20~30                       | 276~415                      |
| 1/2-13  | 40~50                       | 553~691                      |

USE ONLY 75°C COPPER CONDUCTORS  
N'UTILISER QUE DES CONDUCTEURS EN CUIVRE 75°C

Torque Label

TO OBTAIN PARTS  
OR SERVICE FOR YOUR  
TOSHIBA PRODUCT  
CALL 800-231-1412  
OR 713-466-0277

ASK FOR FIELD SERVICE  
HAVE THE FOLLOWING READY:

*TYPE OF EQUIPMENT  
INSTALLATION DATE  
JOB NUMBER  
MODEL NUMBER  
SERIAL NUMBER  
APPLICATION  
QUESTION OR PROBLEM  
TEST OR OPERATION DATA*

Service Label

  
c UL US  
LISTED  
MEDIUM VOLTAGE  
POWER CONVERSION  
EQUIPMENT  
4ZA1

UL Label  
(for UL Listed drives)



CE Label  
(for drives designed  
for use in the  
European Union)

## Qualified Personnel

Installation, operation, and maintenance shall be performed by **Qualified Personnel Only**. A **Qualified Person** is one that has the skills and knowledge relating to the construction, installation, operation, and maintenance of the electrical equipment and has received safety training on the hazards involved. In the U.S., refer to the latest edition of NFPA 70E for additional safety requirements. Outside the U.S., follow all applicable national and local safety practices.

**Qualified Personnel** shall:

- Have read the entire operation manual.
- Be familiar with the construction and function of the ASD, the equipment being driven, and the hazards involved.
- Able to recognize and properly address hazards associated with the application of motor-driven equipment.
- Be trained and authorized to safely energize, de-energize, ground, lockout/tagout circuits and equipment, and clear faults in accordance with established safety practices.
- Be trained in the proper care and use of protective equipment such as safety shoes, rubber gloves, hard hats, safety glasses, face shields, flash clothing, etc., in accordance with established safety practices.
- Be trained in rendering first aid.

For further information on workplace safety in the U.S. visit [www.osha.gov](http://www.osha.gov). Outside the U.S., refer to your existing plant safety regulations.

## Equipment Inspection

- Upon receipt of the equipment inspect the packaging and equipment for shipping damage.
- Carefully unpack the equipment and check for parts that were damaged from shipping, missing parts, or concealed damage. If any discrepancies are discovered, it should be noted with the carrier prior to accepting the shipment, if possible. File a claim with the carrier if necessary and immediately notify your Toshiba representative.
- **DO NOT** install or energize equipment that has been damaged. Damaged equipment may fail during operation resulting in further equipment damage or personal injury.
- Check to see that the rated capacity and the model number specified on the nameplate conform to the order specifications.
- Modification of this equipment is dangerous and must not be performed except by factory trained representatives. When modifications are required contact your Toshiba representative.
- Inspections may be required before and after moving installed equipment.
- Keep the equipment in an upright position as indicated on the shipping carton.
- Contact your Toshiba representative for assistance if required.

## Handling and Storage

- Use proper lifting techniques when moving the ASD; including properly sizing up the load, getting assistance, and using a forklift if required.
- Store in a well-ventilated covered location and preferably in the original carton if the equipment will not be used upon receipt.
- Store in a cool, clean, and dry location. Avoid storage locations with extreme temperatures, rapid temperature changes, high humidity, moisture, dust, corrosive gases, or metal or conductive particles.
- Do not store the unit in places that are exposed to outside weather conditions (i.e., wind, rain, snow, etc.).
- Store in an upright position as indicated on the shipping carton.
- Include any other product-specific requirements.

## Disposal

Never dispose of electrical components via incineration. Contact your state environmental agency for details on disposal of electrical components and packaging in your area.

## Installation Precautions

### Location and Ambient Requirements

- Adequate personnel working space and adequate illumination must be provided for adjustment, inspection, and maintenance of the equipment. In the U.S., refer to NEC Article 110-34 for requirements. Outside the U.S., follow applicable local electrical code requirements.
- Avoid installation in areas where vibration, heat, humidity, dust, fibers, metal or conductive particles, explosive/ corrosive mists or gases, or sources of electrical noise are present.
- Do not install the ASD where it may be exposed to flammable chemicals or gasses, water, solvents, or other fluids.
- The installation location shall not be exposed to direct sun light .
- MTX drives are designed for outdoor use with exposure to rain and direct sunlight.
- Allow proper clearance spaces for installation. Do not obstruct the ventilation openings. Refer to the recommended minimum installation dimensions as shown on the enclosure outline drawings.
- The ambient operating temperature shall be between 0 and 40 °C (32 and 105 °F), unless stated otherwise.

### Mounting Requirements

- Only **Qualified Personnel** should install this equipment.
- Install the unit in a secure upright position in a well-ventilated area.
- A noncombustible insulating floor or mat should be provided in the area immediately surrounding the electrical system at the place where maintenance operations are to be performed.
- Equipment should be installed according to all applicable national, regional, and industry codes and standards. In the U.S., installation of the equipment should conform to NEC Article 110 Requirements For Electrical Installations and to OSHA requirements.
- In the U.S., installation practices should conform to the latest revision of NFPA 70E Electrical Safety Requirements for Employee Workplaces. Outside the U.S., applicable national and local installation safety practices should be followed. In the EU refer to section 6.5 of HD 637 and its sub clauses.

## Conductor Routing and Grounding

- Use separate metal conduits for routing the input power, output power, and control circuits.
- A separate ground cable should be run inside the conduit with the input power, output power, and control circuits.
- **DO NOT** connect control terminal strip return marked LG to earth ground.
- Always ground the unit to prevent electrical shock and to help reduce electrical noise.
- It is the responsibility of the person installing the ASD or the electrical maintenance personnel to provide proper grounding and branch circuit protection in accordance with all applicable national and local electrical codes (in the U.S. refer to the current version of NEC).



**WARNING**



**The Metal Of Conduit Is Not An Acceptable Ground.**

## Connections



**WARNING**



**Contact With Energized Wiring Will Cause Severe Injury Or Death.**

- Turn off, lockout, and tagout all power sources before proceeding to connect the power wiring to the equipment.
- After ensuring that all power sources are turned off and isolated in accordance with established lockout/tagout procedures, connect three-phase power source wiring of the correct voltage to the correct input terminals and connect the output terminals to a motor of the correct voltage and type for the application. In the U.S., refer to NEC Article 300 – Wiring Methods and Article 310 – Conductors For General Wiring and size the branch circuit conductors in accordance with NEC Table 310.16. Outside the U.S., follow your national and local electrical codes.
- If multiple conductors that are smaller than the recommended sizes are used in parallel for the input or output power, each branch of the parallel set shall have its own conduit and not share its conduit with other parallel sets (i.e., place U1, V1, and W1 in one conduit and U2, V2, and W2 in another) (refer to NEC Article 300.20 and Article 310.4 for U.S. requirements). National and local electrical codes should be referenced if three or more power conductors are run in the same conduit (in the U.S. refer to 2002 NEC Article 310 adjustment factors on page 70-142). Outside the U.S., consult your national and local electrical codes for additional requirements for running multiple conductors.
- Ensure that the 3 phase input power is **Not** connected to the output of the ASD. This will damage the ASD and may cause injury to personnel.
- Do not install the ASD if it is damaged or if it is missing any component(s).
- Turn the power on only after attaching and/or securing the front cover.
- Ensure the correct phase sequence and the desired direction of motor rotation in the **Bypass** mode (if applicable).

## Protection

- Ensure that primary protection exists for the input wiring to the equipment. This protection must be able to interrupt the available fault current from the power line. The equipment may or may not be equipped with an input disconnect (option).

When sizing and installing the upstream cabling and protection equipment:

- Consult the Manufacturer's Nameplate for Equipment Voltage and Current Requirements.
  - The equipment must be installed to meet the National Electrical Code rules of the country where installed as a branch circuit protector.
  - The equipment must bear a safety mark accepted by the country where installed.
  - The equipment must be installed by a qualified electrician.
- All cable entry openings must be sealed to reduce the risk of entry, by vermin, and to allow for maximum cooling efficiency.
  - Follow all warnings and precautions, and do not exceed equipment ratings.
  - If using multiple motors, provide separate overload protection, for each motor, and use V/f control.
  - External dynamic braking resistors, if supplied, must be thermally protected.
  - It is the responsibility of the person installing the ASD or the electrical maintenance personnel to setup the **Emergency Off** braking system of the ASD. The function of the **Emergency Off** braking function is to remove output power, from the drive, in the event of an emergency. A supplemental braking system may also be engaged in the event of an emergency.  
*Note: A supplemental emergency stopping system should be used with the ASD.  
Emergency stopping should not be a task of the ASD alone.*

## System Integration Precautions

The following precautions are provided as general guidelines for the setup of the ASD within the system.

- The Toshiba ASD is a general-purpose product. It is a system component only and the system design should take this into consideration. Please contact Toshiba for application-specific information and for training support.
- The Toshiba ASD is part of a larger system and the safe operation of the device will depend on observing certain precautions and performing proper system integration.
- A detailed system analysis and job safety analysis should be performed by the systems designer and/or systems integrator, before the installation of the ASD component. Contact Toshiba for options availability and for application-specific system integration information, if required.

## Personnel Protection

- Installation, operation, and maintenance shall be performed by **Qualified Personnel Only**.
- A thorough understanding of the ASD will be required before the installation, operation, or maintenance of the ASD.



**WARNING**



- Rotating machinery and live conductors can be hazardous and shall not come into contact with humans. Personnel should be protected from all rotating machinery and electrical hazards at all times.
- Insulators, machine guards, and electrical safeguards may fail or be defeated by the purposeful or inadvertent actions of workers. Insulators, machine guards, and electrical safeguards are to be inspected (and tested where possible) at installation and periodically after installation for potential hazardous conditions.
- Do not allow personnel near rotating machinery. Warning signs to this effect shall be posted at or near the machinery.
- Do not allow personnel near electrical conductors. Human contact with electrical conductors can be fatal. Warning signs to this effect shall be posted at or near the hazard.
- Personal protection equipment shall be provided and used to protect employees from any hazards inherent to system operation.



## System Setup Requirements

- When using the ASD as an integral part of a larger system, it is the responsibility of the ASD installer or maintenance personnel to ensure that there is a fail-safe in place, i.e., an arrangement designed to switch the system to a safe condition if there is a fault or failure.
- System safety features should be employed and designed into the integrated system in a manner such that system operation, even in the event of system failure, will not cause harm or result in personnel injury or system damage (i.e., E-Off, Auto-Restart settings, System Interlocks, etc.).
- The programming setup and system configuration of the ASD may allow it to start the motor unexpectedly. A familiarity with the Auto-restart settings is a requirement to use this product.
- Improperly designed or improperly installed system interlocks may render the motor unable to start or stop on command.
- The failure of external or ancillary components may cause intermittent system operation, i.e.; the system may start the motor without warning.
- There may be thermal or physical properties, or ancillary devices integrated into the overall system that may allow for the ASD to start the motor without warning. Signs at the equipment installation must be posted to this effect.
- If a secondary magnetic contactor (MC) is used between the ASD and the load, it should be interlocked to halt the ASD before the secondary contact opens. If the output contactor is used for bypass operation, it must be interlocked such that commercial power is never applied to the ASD output terminals (U, V, and W).
- Power factor improvement capacitors or surge absorbers must not be installed on the output of the ASD.
- Use of the built-in system protective features is highly recommended (i.e., E-Off, Overload Protection, etc.).
- The operating controls and system status indicators should be clearly readable and positioned where the operator can see them without obstruction.
- Additional warnings and notifications shall be posted at the equipment installation location as deemed required by **Qualified Personnel**.

## Operational and Maintenance Precautions



### WARNING



- Turn off, lockout, and tagout the main power, the control power, and instrumentation connections before inspecting or servicing the drive, or opening the door of the enclosure.
- Turn off, lockout, and tagout the main power, the control power, and instrumentation connections before proceeding to disconnect or connect the power wiring to the equipment.
- The capacitors of the ASD maintain a residual charge for a period of time after turning the ASD off. The required time for each ASD typeform is indicated with a cabinet label and a **Charge LED**. Wait for at least the minimum time indicated on the label and ensure that the **Charge LED** has gone out before opening the door of the ASD once the ASD power has been turned off.
- **Do Not** attempt to disassemble, modify, or repair the ASD. Call your Toshiba sales representative for repair information.
- Do not place any objects inside of the ASD.
- Turn the power on only after attaching (or closing) the front cover and **Do Not** remove the front cover of the ASD when the power is on.
- If the ASD should emit smoke or an unusual odor or sound, turn the power off immediately.
- The heat sinks, magnetics, and other components may become extremely hot to the touch. Allow the unit to cool before coming in contact with these items.
- Remove power from the ASD during extended periods of non-use.
- The system should be inspected periodically for damaged or improperly functioning parts, cleanliness, and to ensure that the connectors are tightened securely.
- Ensure that the **Run** functions (**F**, **R**, **Preset Speed**, etc.) of the ASD are off before performing a **Reset**. The post-reset settings may allow the ASD to start unexpectedly.
- In the event of a power failure, the motor may restart after power is restored.
- **Retry** or **Reset** settings may allow the motor to start unexpectedly. Warnings to this effect should be clearly posted near the ASD and motor.

**DO NOT** install, operate, perform maintenance, or dispose of this equipment until you have read and understood all of the product warnings and user directions. Failure to do so may result in equipment damage, operator injury, or loss of life.

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## INTRODUCTION

Thank you for purchasing the T300MV2, MTX, or MTX2 Medium Voltage ASD. This adjustable frequency, solid-state AC drive features a 3 $\phi$  input isolation transformer with a 24/36-pulse converter design, a 32-bit CPU, and a three-unit power module inverter section providing a 7 level output for 6600V drives, a 5 level output for 4160/3300V drives and 3 level output for 2400V drives. These drives also feature as standard, an 8 key Control Panel with a LCD screen and 2 discrete LED lamps to indicate Ready, Run, Local, Remote and Alarm/Fault.

On most power systems, this drive will meet IEEE-519-1992 harmonic regulation guidelines without installing additional harmonic filters. The input power factor is typically 0.95. The multi-level output produces a more sinusoidal voltage and reduces stress on the motor winding insulation. This drive uses high capacity 3300V IGBTs to improve reliability, reduce switching losses, and improve control performance. The PP7 control processor and 6-layer control board achieves high integration and reliability.

## INITIAL COMMISSIONING



### CAUTION

The drive should be commissioned by qualified personnel only. Below are some general steps required for commissioning.

## Confirmation of Wiring



### CAUTION

Make the following final checks before applying power to the unit:

- 1) Confirm that source power is connected to terminals L1, L2, L3 (R, S, T). **Connection of incoming source power to any other terminals will damage the drive. Other control voltages may be required. Consult your custom equipment diagrams shipped with the drive for any other requirements.**
- 2) Verify that the power modules are properly installed and that there was no damage during shipping or handling.
- 3) Verify that there are no loose connections or wires and that all of the required shipping split connections have been made.
- 4) Verify all external control circuit wiring is complete and properly connected.
- 5) The 3-phase source power should be within the correct voltage and frequency tolerances.
- 6) The motor leads must be connected to terminals T1, T2, T3 (U, V, W).
- 7) Make sure there are no short circuits or inadvertent grounds and tighten any loose connector terminal screws.

## Start-Up and Test



### CAUTION

**Prior to releasing the drive system for regular operation after installation, the system must be adjusted and tested by qualified personnel.** This assures correct operation, of the equipment, for reasons with reliability and safety performance. It is important to make arrangements for such a check and that sufficient time is allowed for it.



## Cautions on Changing Setting Parameters



## CAUTION

The setting data of the drive is saved in an EEPROM, non-volatile memory. When the micro controller initializes at power-up, it reads the EEPROM data and copies it to the RAM (Random Access Memory). From then on, the micro controller controls the drive using the values in the RAM.

When the setting parameters are changed, by the display-keypad or personal computer ("support tool"), only the execution parameters in RAM are changed. If they need to be stored, they must be manually written to the EEPROM. Without this operation, the next initialization or power up will cause them to be replaced by the old data.

When a write to the EEPROM is performed, write processing may take 30 seconds. Turning off the control power supply during write processing will make both the RAM and EEPROM data abnormal. When the power is turned on again, this abnormal data will result in an error ("CHECK ERROR") preventing the drive from running. If such an error occurs, the settings must be reloaded from a saved file. If no setting file exists, the drive must be re-commissioned.

**Do not turn off the control power supply, under any circumstances, while writing data to the EEPROM.**

## INSPECTIONS AND MAINTENANCE



**CAUTION**



**DANGER**



Maintenance and inspection is a particularly effective means to help prevent failures and reduce down time. Creating equipment specific inspection and maintenance check sheets can help in performing maintenance and inspection effectively. Detailed inspections and regular maintenance should be carried out, in short cycles initially, until a schedule, reflecting the site-specific conditions, can be determined.

For items that are too high to reach, use a step ladder to gain access. Do not attempt to climb on the equipment.

### Daily Inspections

Daily inspections consist mainly of **visual** inspections on the following items. These observations should be made with all cubicle doors closed and safety covers installed. Any abnormalities discovered should immediately be repaired.

- 1) Check the temperature, the humidity, the presence of corrosive or explosive gases, and the presence of dust in the area.
- 2) Check for any abnormal sound or vibration originating from the reactor, transformer, or cooling fans.
- 3) Check for abnormal odors such as the smell of burning insulating materials.

### Regular Inspections



**CAUTION**



**DANGER**



Carry out regular inspections **with the power off, locked out, and with confirmation that the bus voltage is completely discharged**. Use proper power **lockout/tagout procedure** on the disconnecting means in accordance with applicable local electrical codes (in the U.S., see 2002 NEC Article 430-101) before performing any drive maintenance.

The first thing to do in maintenance and inspection is cleaning. Cleaning should be carried out according to the conditions of the equipment. Before starting cleaning, turn off the power supply and check that the main circuit voltage is reduced to 0. Clean dust with a vacuum, dry compressed air, and clean dry cloths. Note that excessive air pressure when blowing out equipment may damage parts and wiring. **Do not use solvents to clean the drive**. Substances stuck to the circuits, which cannot be removed by blowing, should be wiped away using a cloth. As a basic rule, cleaning should start from the upper parts and end at the lower parts. Cleaning of the lower parts last will allow proper removal of substances that could drop from the upper parts.

## INSPECTIONS AND MAINTENANCE (cont'd)



**CAUTION**



### Main Components

- 1) Cooling fan - Check to see if there is any abnormality with airflow, increased fan noise, etc.
  
- 2) Air filter - Visually check if the air filter is clogged. Gently tap it outside the room to remove loose dust. To remove caked on dirt use water and a gentle detergent, rinse it with clean water and dry it. Otherwise replace it with a new one. **Cleaning with solvents is not recommended.**
  
- 3) Main circuit parts and entire cubicle - Check to see if dust is stuck to the cubicle interior or if there is any discoloration, heat generation, abnormal sound, leakage, odor or damage with the reactor, transformer, contactors, cables and connections, fuses, capacitors, lightening arrestors, and resistors. Check to see that no wires or mounted parts are broken, disconnected, loose or damaged. High voltage standoffs, insulators, and cable can be cleaned with isopropyl alcohol.
  
- 4) Printed Wiring Boards - The boards, which are made up of ICs and electronic components, must be protected from dust, corrosive gases and extreme temperatures. Pay attention to the installation environment of the equipment. Regular inspections, the proper cleaning, and maintenance in an optimal environment is essential for circuit boards. Since most of the components and parts are small and vulnerable to external forces, when cleaning them, use a brush to carefully wipe off dust. Inspect the boards for signs of component damage, heating, and corrosion.

### Cautions on Handling Printed Wiring Boards

- a) All maintenance work on the board should be carried out at least 15 minutes after all power supplies are turned off to allow the capacitors on the boards to discharge.
  
- b) When removing the board, disconnect all the connectors and wires and remove the mounting screws from the upper part of the board first. At this time, be careful not to drop the boards or screws. When setting the board down, place it on a static free surface. Be careful not to damage any components.
  
- c) When attaching the board, do so in the order opposite to the removing procedure. Be sure that all of the connectors and wires are connected correctly.
  
- d) New boards are shipped in an anti-static bag. Use this bag to store them.

**Note that the anti-static coating is only on the inner side of the bag.**

- 5) Check the protection functions for proper operation (Door switches, OH, E-stop...)
  
- 6) Check the insulation resistance of the medium voltage circuits.

## INSPECTIONS AND MAINTENANCE (cont'd)



## CAUTION

### Recommended Parts to be Regularly Renewed

To use the drive for a maximum period of time, it is necessary to regularly renew (replace) components whose characteristics have deteriorated. The table below shows the parts used for the inverter equipment whose regular renewal is recommended for critical applications and their recommended renewal period. We always recommend that spares be on hand to reduce down time.

| Product name  | Recommended renewal period | Remarks  |
|---|----------------------------|--|
| Cooling fan   | 7 years                    | Sooner if dust or dirt damages bearings          |
| Air filter  | 6 months                   | Can also be cleaned.                             |
| Aluminum Electrolytic Capacitors<br>On Circuit Boards | 7 years                    | Contact Toshiba for replacement of these devices |
| Oil-filled capacitor<br>Main circuit                  | 20 years                   |  |
| Control power supply                                  | 7 years                    |  |
| Fuse  | Main circuit               | 7 years  |
|   | Control circuit            | 7 years  |

## Recommended Spare Parts

Spare parts are an important part of downtime reduction. When parts in the drive have failed, on-hand spare parts are necessary to shorten the mean time to repair (MTTR). Since replacement of discrete components is time consuming, it is recommended that entire assemblies be replaced. Recommended spare parts common to all drives are shown in the following tables. The recommended spare rate and minimum amount can serve as references for the minimum number of spare parts relative to the total number of drives on site. It is recommended that the quantity be determined in accordance with the number drives on site. Many other parts are job specific. It is up to the end user to determine what other parts may be needed.

### Recommended Common Spare Parts \*\*

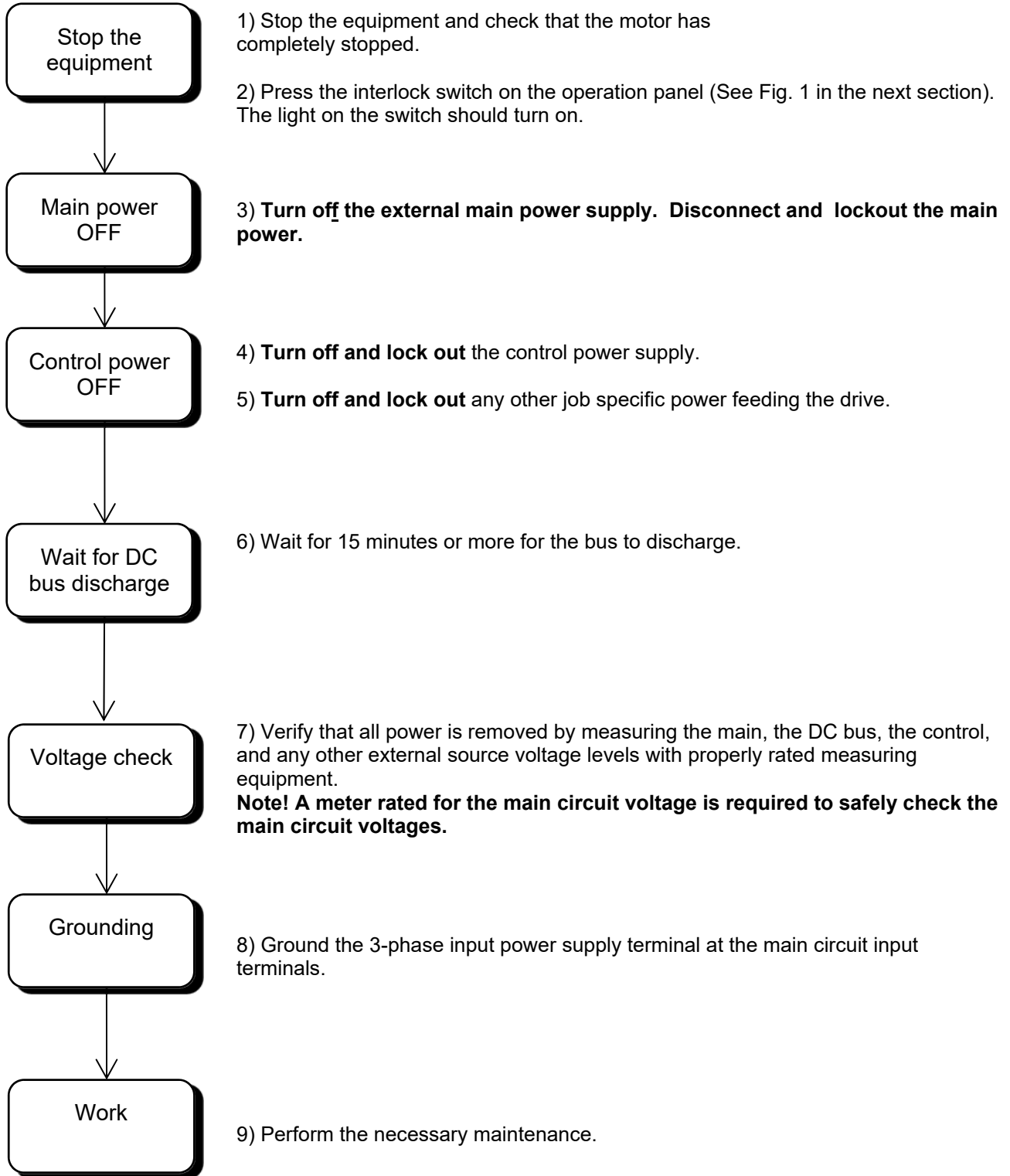
| Product name     | Model/Rating                   |              | Number of parts per drive | Recommended spare parts |                      |
|------------------|--------------------------------|--------------|---------------------------|-------------------------|----------------------|
|                  |                                |              | 4160V/2300V               | Spare rate              | Recommended Min Q'ty |
| CTR              | Control board                  | ARND-4044(*) | 1 each                    | 10%                     | 1                    |
| GSD              | Gate signal distribution board | PC61910P203A | 1 each                    | 10%                     | 1                    |
| XIO              | External input/output board    | ARND-4045(*) | 1 each                    | 10%                     | 1                    |
| EXIO             | External input/output board    | PC61910P205B | 1 each                    | 10%                     | 1                    |
| IFBK             | Current feedback board         | PC61910P207* | 1 each                    | 10%                     | 1                    |
| EXIF             | External Interface board       | PC61910P206A | 1 each                    | 10%                     | 1                    |
| IPAD             | Keypad interface board         | PC61910P204A | 1 each                    | 10%                     | 1                    |
| DISP             | Display/keypad                 | PC61910P216  | 1 each                    | 10%                     | 1                    |
| PS1              | Control power supply           | GCI6722G282  | 1 each                    | 10%                     | 1                    |
| GDI              | Earth fault detection          | PC61910P135A | 1 each                    | 10%                     | 1                    |
| PDM              | Phase detection module         | PC61910P107A | 1 each                    | 10%                     | 1                    |
| Control Fuses    | *                              | *            | 2 each                    | 10%                     | 2                    |
| Main Fuses       | *                              | *            | 3 each                    | 10%                     | 3                    |
| Pt fuses         | *                              | *            | 4 each                    | 10%                     | 4                    |
| Rectifier fuses  | *                              | *            | 36/12                     | 10%                     | 3                    |
| Power modules*** | *                              | *            | 3                         | 10%                     | 1                    |
| Cooling Fans     | *                              | *            | *                         | 10%                     | 1                    |

\* This data is job/inverter specific. Check the drawings for the specific inverter for this information.

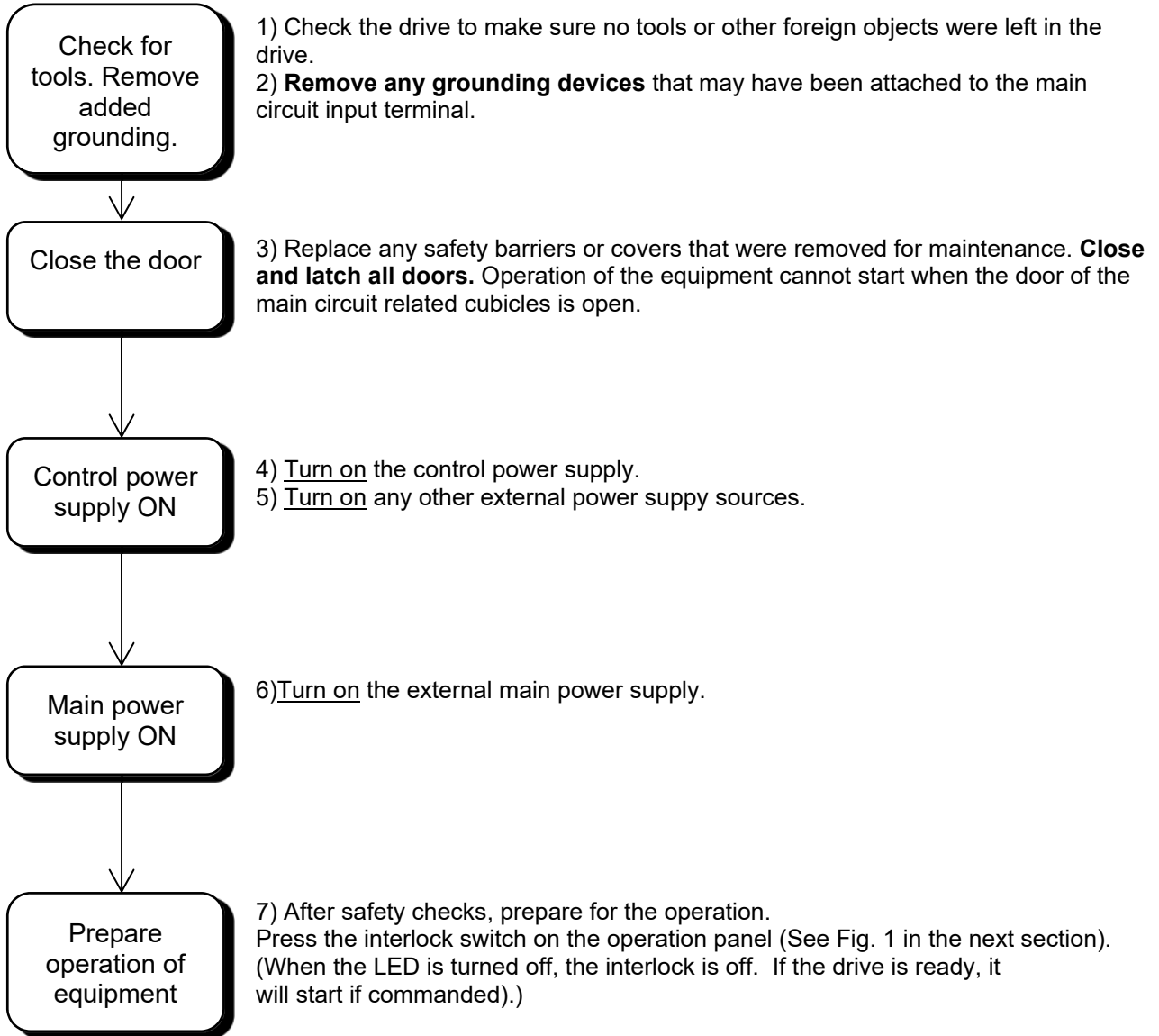
\*\* This is a general list of spares. Check the specific job drawings for other components that may need to be spared.

\*\*\* It is recommended that failed power modules be replaced as a unit and that the failed modules be returned to Toshiba for repair and testing. (T300MV2 & MTX2). For Twin drives, there are 6 modules. For 6600V drives there 3x2400V modules and 3x4160V modules. MTX drives require field repair of the module by factory trained personnel.

## Preparations for Inspection and Maintenance of Equipment (Powering-Off)



## Recovery after Inspection and Maintenance of Equipment (Powering-On)



## OVERVIEW

### Display/Keypad (EOI)

The following figure shows the display/keypad of the equipment. Refer to the keypad operation manual for more details on its use.

#### EOI Diagram

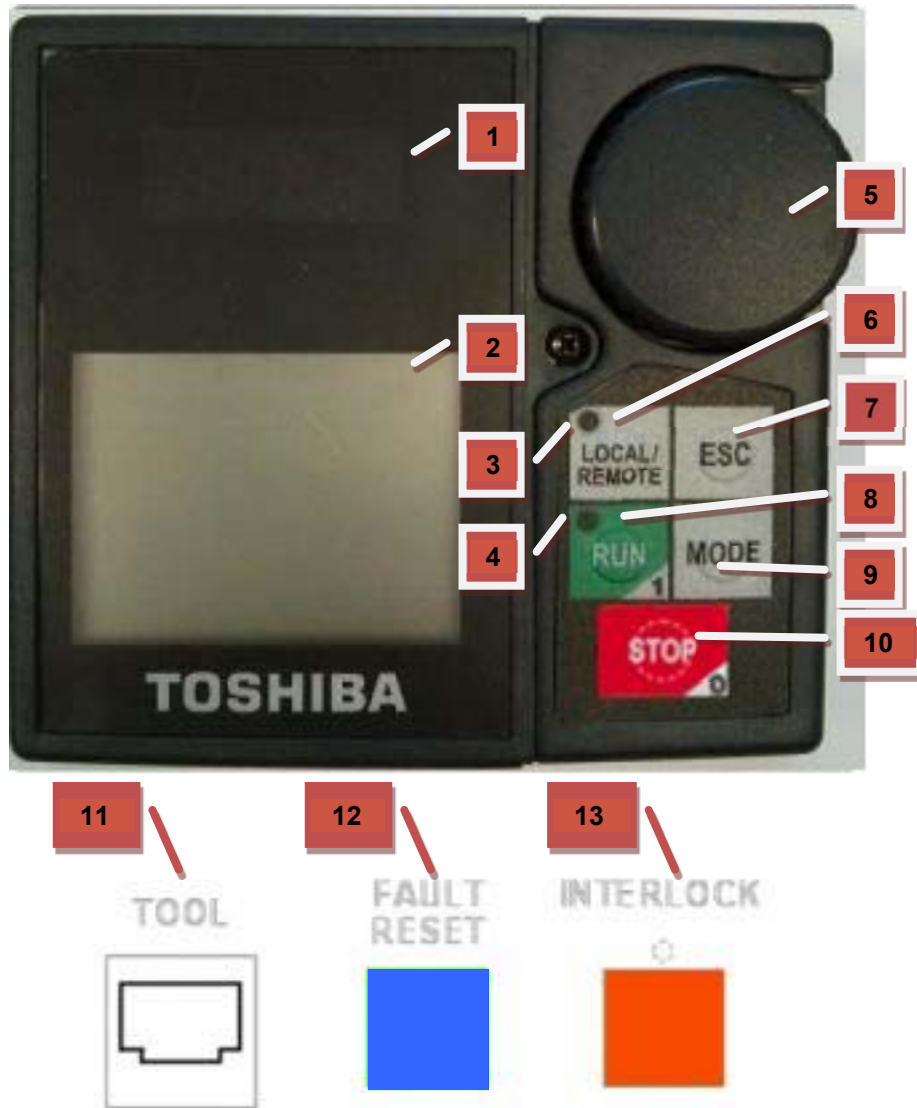


Figure 1.



1. 4 Digit 7 Segment Display – Brightly displays the frequency when connected to V/Hz, Vector and SM drive types. Displays feedback (%) when connected to a Static Var. Controller.
2. Graphical LCD – Displays user information in text and numerical form.
3. Green Local/Remote LED – The green LED is lit when in local mode and off during remote mode.
4. Green and Red Status LED's:
  - Not ready and not running – Both Red and Green off.
  - Ready and not running – Green LED only
  - Ready and running – Red LED only.
  - Fault – Fast blinking Red LED. (0.5Hz).
  - Alarm – Slow blinking red if running or green if not running. (1.5Hz).
  - Test mode – Alternating red and green regardless of condition. (0.5Hz).
5. Encoder – This is a multi-function device. If pushed, it will function as an Enter/select button\*. If turned clockwise, it will scroll down a menu listing and increments a selected field's parameter data. If turned counter clockwise, it will scroll up a menu listing and decrement a selected field's parameter data. (\*Enter action – Selects a menu item to be changed or accepts and writes the changed data of a selected field. This key, when in the Main tab and held for more than 2 seconds will toggle the direction of the motor. This function only works if the drive is not running.)
6. Local/Remote key – Toggles between Local and Remote mode's while in the Main screen and the drive is not running. To toggle modes the key must be held for at least 2 seconds.
7. Escape key – Multi function key. It returns to the previous level of the menu tree. It cycles through the tabs (see figure 2).
8. Run key – Will run the drive when in local mode. (Note: If the drive does not have a reference speed it will display forward direction even though it may be in reverse direction. When a reference speed is given it will display the correct direction.)
9. Mode key – This key will cycle through the tabs (see figure 2). This key will also initialize the selection of individual digits by position in conjunction with the encoder when changing the values of parameters.
10. Stop key – This key will stop the drive from running when in local mode and works from all screens. (Please refer to Section 4.1 to change the effect of the STOP key when in Local or Remote Mode.)
11. Commissioning Tool Port – Ethernet port used for communication to the commissioning and support tool. A cross over cable may be required to establish a direct connection to a PC.
12. RESET Pushbutton – This pushbutton is used to clear inverter faults and alarms displayed on the LCD.
13. INTERLOCK Pushbutton – This pushbutton is used to disable the inverter via a hard-wired circuit. The pushbutton is illuminated while the inverter is interlocked, and extinguished for normal operation. Operating the INTERLOCK pushbutton will result in an inverter gate block and free-run deceleration of the load.

## How to Handle Faults

In the event of a fault, the following measures should be taken:

- (1) Record the fault message shown on the display on the operation panel.
- (2) Collect the trace back data, if the commissioning software package was purchased.
- (3) See the Fault and Recovery section.

## Description of Terminology

This section describes the special terms used in this manual.

### Description of Terminology

| Term           | Meaning  |
|----------------|--|
| Power module   | A single-phase DC-fed inverter module using IGBTs.   |
| IGD board      | IGBT Gate Driver Board. Converts gate signals sent in optical signal form to electric signals.   |
| OLB board      | Optical Link Board. Converts gate signals from electric to optical signals for isolation.  |
| VDET board     | Voltage Detection Board. Board that measures analog voltage signals and converts them to optical signals.  |
| GSD board      | Gate Signal Distributor. Board that distributes gate signals to each output phase.   |
| CTR board      | Inverter main control board  |
| TEX board      | Twin Expansion Board. Distributes the gate signals to the power modules for twin drives.   |
| EEPROM         | Electrical Erasable Programmable Read Only Memory  |
| IGBT           | Insulated Gate Bipolar Transistor  |
| LCD            | Liquid Crystal Display   |
| LED            | Light Emitting Diode   |
| MCCB           | Molded Case Circuit Breaker  |
| PP7            | Power electronics Processor for Various Inverter control Integration (VII=7). Toshiba dedicated power electronics control 32-bit micro-controller. |
| PSM            | Switching power supply that providing $\pm 15$ VDC and +5 VDC for boards.  |
| RAM            | Random Access Memory   |
| Initialize     | Act of initialization. When the control power switch is turned from OFF to ON the inverter equipment initializes data and circuits.                |
| Interface      | Means by which this equipment transfers signals to/from external devices.  |
| Inverter       | Inverse converter that converts DC power to AC power.<br>(DC $\rightarrow$ AC conversion)  |
| Overload       | Operation at a current output that exceeds the continuous rating of the equipment.   |
| Display-keypad | Operational panel installed on the cubicle surface that is used for data display and basic operations.   |
| Load           | Refers to a motor that receives power from this equipment.   |

## General Specifications (Structure)

The general specifications (structure) of the equipment are shown in the following table.

### General Specifications (Structure)

| Item   |                            | Standard specification   | Additional optional specification                     | Remarks  |
|--|----------------------------|--|---|--|
| Applicable standard  |                            | UL, NEMA   |   |  |
| Ambient conditions   | Temperature                | 0 to +40°C for T300MV2   | 50C operation for T300MV2 with a derate.              | Low temperature for MTX2 is with externally powered heaters.   |
|  |                            | -20 to +50°C for MTX series  |   |  |
|  | Humidity                   | -45 to +50°C for MTX2 series   |   | At no time should the drive be subjected to conditions that would allow condensation to form on the components.                  |
|  |                            | -20 to +60°C for storage   |   |  |
|  | Altitude                   | 1000 m Max. above sea level  | Higher altitudes with a derate and special magnetics. |  |
|  | Installation location      | Indoors<br>Outdoors for MTX series                                       |   |  |
| Vibration  | 10 to 60 Hz, 0.5 G or less |  |   |  |
| Corrosive factors  |                            | Hydrogen Sulfide (H <sub>2</sub> S) ≤ 0.001 PPM                          |   | This is a list of corrosive agents know to attack the drive components. Other agents may also have adverse effects on the drive. |
|  |                            | Sulfur Dioxide (SO <sub>2</sub> ) ≤ 0.05 PPM                             |   |  |
|  |                            | Chlorine gas (Cl <sub>2</sub> ) ≤ 0.1 PPM                                |   |  |
|  |                            | Ammonia gas (NH <sub>3</sub> ) ≤ 0.1 PPM                                 |   |  |
|  |                            | Nitrogen Dioxide (NO <sub>2</sub> ) ≤ 0.02 PPM                           |   |  |
|  |                            | Nitrogen Oxide (NO <sub>x</sub> ) ≤ 0.02 PPM                             |   |  |
|  |                            | Ozone (O <sub>3</sub> ) ≤ 0.002 PPM                                      |   |  |
| Hydrochloric acid mist (HCl <sub>1</sub> ) ≤ 0.1 mg/m <sup>3</sup> |                            |  |   |  |
| Paint color  | Cubicle surface            | ANSI 61 Gray (T300MV2)   | Consult factory for optional colors                   |  |
|  |                            | White (MTX series)   |   |  |
| Cubicle structure  |                            | Front maintenance (T300MV2)<br>MTX requires front, back, and side access |   |  |
| Cubicle protective structure                                       |                            | Type 1, Forced ventilated (T300MV2)                                      | Type 4 or 4X for MTX2-15                              |  |
|  |                            | Type 3R (MTX series)   |   |  |
|  |                            | With channel base  |   |  |
| Air filter   |                            | Front mounted (T300MV2)  |   |  |

## Altitude and Temperature De-rating

Altitude Derate Chart

| Altitude | % Amp Output Derate |
|----------|---------------------|
| 3,300'   | 0.0%                |
| 4,000'   | 2.0%                |
| 4,500'   | 3.3%                |
| 5,000'   | 4.7%                |

Temperature Derate Chart

| Ambient Temperature | % Amp Output Derate |
|---------------------|---------------------|
| 40 °C               | 0.0%                |
| 45 °C               | 7.5%                |
| 50 °C               | 15.0%               |

## Motor Cable Length

Below are cable length guidelines for use with most standard industrial motors.

### Suggested Maximum Output Cable Distances

| AC Motor Voltage  | Drive Output Voltage | Max lead length without filter |
|-------------------|----------------------|--------------------------------|
| 2300              | 2400                 | 0-1000 ft                      |
| 2300/4000         | 2400                 | 0-1000 ft                      |
| 4000 or 2300/4000 | 4160                 | 0-1000 ft                      |
| 6600              | 6600                 | 0-1000 ft                      |
| 6900              | 6900                 | 0-1000 ft                      |



## CAUTION

(1) Older motors, or motors with marginal insulation systems, may require filters to help reduce the stress on the insulation system. Consult Toshiba application engineering.

(2) Exceeding the peak voltage and allowable voltage rise time of the motor insulation system will reduce motor life expectancy. To insure good insulation life, consult with the motor supplier to determine motor insulation ratings and allowable maximum output lead distance. Long lead lengths between the motor and drive may require that filters be added to the drive output.

## General Specifications (Electrical)

The general (electrical) specifications of the equipment are shown in the following table.

### General (Electrical) Specifications

| Item                           |   | Standard specification  | Standard Optional Specification   | Additional Optional Specification  | Remarks   |
|--------------------------------|---|---|---|------------------------------------|---|
| Frame Sizes                    |   | 2400V   | 0, A2, 1, B2, 3, D2, 4  |                                    | See ratings table for specific kVA ratings available                  |
|                                |   | 4160V   | 0, A4 $\mu$ , A4, A4R, B4, B4R, C4, 1, 2, 3, 4, G4P, H4P, MTX15, MTX30, MTX2-15, MTX2-60              |                                    |   |
|                                |   | 6600V   | A6S, B6S, C6S, D6S, F6S, F6S+   |                                    |   |
|                                |   | 6900V   | F7  |                                    |   |
| Motor driven by this equipment |   | Squirrel-cage induction motor   | Synchronous motor   | PM motor                           |   |
| Main power supply              | Input supply voltage and range of fluctuation                           | Rated Voltage $\pm 10\%$ (+5%/-10% for 6.9kV)<br>Rated Frequency $\pm 5\%$                                |   |                                    |   |
|                                | Output voltage  | 0 ~ Rated Voltage   |   |                                    |   |
| Control power supply           | Supply voltage frequency  | Internally supplied 480V, 60 Hz T300MV2, MTX 30. and MTX2.<br><br>Internally supplied 240 V, 60 Hz MTX15. | Internally supplied 480V, 50 Hz T300MV2, MTX30, & MTX2.<br><br>Internally supplied 240V, 50 Hz MTX15. | External supply as an option.      | All MTX series drives require externally supplied space heater power. |
| Main circuit                   | PWM frequency   | 1024Hz 2400V<br>2048Hz 4160V<br>1024Hz 6600V  |   |                                    |   |
|                                | Regeneration system   | None  | PWM   |                                    | Regen is available on select frames only                              |
| Others                         | Overload capacity   | 100% - continuous<br>110-115% - 60 sec (Depends upon frame size and drive rating)                         |   | 125%, 150%, 175%, 200%, 225%, 250% | The higher OL ratings require a reduction in continuous capacity.     |
|                                | Ground protection   | Yes   |   |                                    |   |
|                                | Receptacle  | No  |   | Yes                                |   |
|                                | Motor cooling fan control   | No  |   | Yes                                |   |
|                                | Cabinet space heater  | No (indoor), Yes (outdoor)  |   | Yes                                | Space heaters must be externally powered.                             |
|                                | Cabinet internal light  | No  |   |                                    |   |
|                                | Typical operating sound levels measured at a distance of 1m x 1.5m high | Indoor & MTX-15 <80dBA<br>F7 <85dBA<br>MTX-30 & MTX2-15 <90dBA  |   |                                    |   |

## General Specifications (Control)

The general (control) specifications are shown in the following table.

### General Control Specifications

| Item                           | Standard specification                   | Option  | Remarks   |  |         |         |                          |
|--------------------------------|--|---|---|--|---------|---------|--------------------------|
| Maximum output frequency       | 75Hz<br>(66Hz for sync- transfer drives) | 90Hz all non synch-transfer drives<br>120Hz for most 4160V drives and 6900V drives.   | 90Hz max with sine wave filter, for H4P, G4P, 2400V & 6600V drives.   |  |         |         |                          |
| Speed sensor (PG pulse output) | No                                       | Yes   |   |  |         |         |                          |
| Basic control performance      | Basic control system                     | Induction Motor Volts/Hertz   | Induction Motor Sensor & Sensorless Vector<br>Synchronous Motor Sensor & Sensorless<br>PM Motor Sensor Type | Sensor type vector control uses a 1x resolver or a PG. The maximum PG freq. is 100kHz. |         |         |                          |
|                                |  | Operation control range   |   |  | 3%-100% | 1%-100% | Limited by motor heating |
|                                |  | Field weakening control   |   |  | 1:1.5   | 1:5     | Vector Control           |
|                                | Speed accuracy                           | ±0.5%   | ±0.01%  |  |         |         |                          |
|                                | Speed resolution                         | 1/25000<br>(Digital setting)  | Analog setting<br>1/1000. Isolation transducer recommended.   |  |         |         |                          |
|                                | Acceleration/deceleration time           | 0.1 – 3276.7 sec,<br>acceleration/deceleration independent setting  |   | Most drives cannot regenerate.   |         |         |                          |
| Operation specification        | Restart after instantaneous interruption | Possible<br>(more than 5 cycles interruption causes shut down)  |   | Under-voltage trip at 75% level  |         |         |                          |
| Communications                 | Serial interface                         | None  | MODBUS<br>DEVICE_NET<br>PROFIBUS<br>TL-S20  | Requires optional board.   |         |         |                          |
|                                | Commissioning/Maintenance Tool           | Ethernet (with modular jack attached to keypad)   |   |  |         |         |                          |
| Cubicle display/operation      | LED 1 lamp                               | READY: Operation preparation completed(Green)<br>RUN: Inverter in operation(Red)<br>ALARM/FAULT:<br>Alarm slow flashing/Fault fast flashing | READY and RUN light colors can be reversed by changing an EOI parameter                                     |  |         |         |                          |
|                                | LED 2 lamp                               | ON - Keypad control<br>OFF - Other than keypad control  |   |  |         |         |                          |
|                                | LCD display                              | 128x64 Pixel Graphical LCD display  |   |  |         |         |                          |
|                                | Operation apparatus                      | Backlit type interlock switch: 1<br>Unlit reset switch: 1<br>Operation via 8 key keypad and a 15pulse/30detent incremental encoder          |   |  |         |         |                          |
|                                | Connector                                | Personal computer connection Ethernet modular jack  |   |  |         |         |                          |

## General Control Specifications Continued:

### General Control Specifications

| Item                               | Standard specification  | Option                                      | Remarks  |
|------------------------------------|---|---|--|
| Analog signal output               | ± 10VDC x 2 programmable channels on EXIO brd.<br>± 10VDC x 1 Fixed on XIO brd.<br>± 10VDC x 5 programmable channels on EXIF brd.   |   | Connected measuring equipment must be isolated from ground     |
| Analog signal input                | ± 10VDC x 3 channels on EXIO brd.<br>± 10VDC x 1 channels on XIO brd.   |   | Connected source equipment must be isolated from ground        |
| Digital input                      | 6 Programmable on EXIO brd.<br>Photo coupler 50mA 5-24Vdc<br>7 Fixed on EXIO brd.<br>Dry contact 30Vdc 250Vac<br>8 Fixed on EXIF brd.<br>Photo coupler 50mA 5-24Vdc<br>4 Programmable on XIO brd.<br>Photo coupler 50mA 5-24Vdc<br>2 Fixed(UVS1 & UVS2) on XIO brd.<br>Photo coupler 50mA 5-24Vdc |   | Fixed contact is always used for interlocking control function |
| Digital output                     | 11 Programmable on EXIO brd.<br>6 dry contact 30Vdc 250Vac<br>5 photo coupler 50mA 5-24Vdc<br>2 Fixed on EXIO brd.<br>Dry contact 30Vdc 250Vac<br>6 Fixed on XIO brd.<br>4 photo coupler 50mA 5-24Vdc<br>2 dry contact 30Vdc 250Vac<br>4 Programmable on XIO brd.<br>Photo coupler 50mA 5-24Vdc   |   | 24V contact always used for internal control functions         |
| Commissioning and Maintenance Tool | TIC MVD Tool  | Parameter setting, fault data display, etc. | Optional Software Package                                      |

## Rating Specifications

**Type 1 Standard Ratings Table (T300MV2)**

| Standard Model  | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame | Output Voltage & Frequency |
|-----------------|---------------|----------|-----------|------------|---------------------|---------------------------------|-------|----------------------------|
| M40AN22030AAA0  | 2400 V        | 300      | 233       | 268        | 64                  | 74                              | 0     | 0~2400 V<br>0~75 Hz        |
| M40AN22035AAA0  |               | 350      | 272       | 313        | 75                  | 86                              | 0     |                            |
| M40AN22040AAA0  |               | 400      | 311       | 357        | 86                  | 99                              | 0     |                            |
| M40AN22045AAA0  |               | 450      | 350       | 402        | 97                  | 111                             | 0     |                            |
| M40AN22050AAA0  |               | 500      | 389       | 447        | 107                 | 124                             | 0     |                            |
| M4AAN22030AAA0  |               | 300      | 233       | 268        | 64                  | 74                              | A2    |                            |
| M4AAN22035 AAA0 |               | 350      | 272       | 313        | 75                  | 86                              | A2    |                            |
| M4AAN22040 AAA0 |               | 400      | 311       | 357        | 86                  | 99                              | A2    |                            |
| M4AAN22045 AAA0 |               | 450      | 350       | 402        | 97                  | 111                             | A2    |                            |
| M4AAN22050 AAA0 |               | 500      | 389       | 447        | 107                 | 124                             | A2    |                            |
| M41AN22060 AAA0 |               | 600      | 466       | 536        | 129                 | 148                             | 1     |                            |
| M41AN22070 AAA0 |               | 700      | 544       | 625        | 150                 | 173                             | 1     |                            |
| M41AN22080 AAA0 |               | 800      | 622       | 715        | 172                 | 198                             | 1     |                            |
| M41AN22090 AAA0 |               | 900      | 699       | 804        | 193                 | 222                             | 1     |                            |
| M41AN22100 AAA0 |               | 1000     | 777       | 893        | 215                 | 247                             | 1     |                            |
| M4BAN22060 AAA0 |               | 600      | 466       | 536        | 129                 | 148                             | B2    |                            |
| M4BAN22070 AAA0 |               | 700      | 544       | 625        | 150                 | 173                             | B2    |                            |
| M4BAN22080 AAA0 |               | 800      | 622       | 715        | 172                 | 198                             | B2    |                            |
| M4BAN22090 AAA0 |               | 900      | 699       | 804        | 193                 | 222                             | B2    |                            |
| M4BAN22100 AAA0 |               | 1000     | 777       | 893        | 215                 | 247                             | B2    |                            |
| M43AN22125 AAA0 |               | 1250     | 971       | 1116       | 269                 | 309                             | 3     |                            |
| M43AN22150 AAA0 |               | 1500     | 1166      | 1340       | 322                 | 371                             | 3     |                            |
| M43AN22175 AAA0 |               | 1750     | 1360      | 1563       | 376                 | 432                             | 3     |                            |
| M43AN22200 AAA0 |               | 2000     | 1554      | 1786       | 430                 | 494                             | 3     |                            |
| M4DAN22125 AAA0 |               | 1250     | 971       | 1116       | 269                 | 309                             | D2    |                            |
| M4DAN22150 AAA0 |               | 1500     | 1166      | 1340       | 322                 | 371                             | D2    |                            |
| M4DAN22175 AAA0 |               | 1750     | 1360      | 1563       | 376                 | 432                             | D2    |                            |
| M4DAN22200 AAA0 |               | 2000     | 1554      | 1786       | 430                 | 494                             | D2    |                            |
| M44AN2225 AAA0  |               | 2250     | 1748      | 2010       | 483                 | 556                             | 4     |                            |
| M44AN22250 AAA0 |               | 2500     | 1943      | 2233       | 537                 | 618                             | 4     |                            |
| M44AN22300 AAA0 | 3000          | 2331     | 2680      | 645        | 741                 | 4                               |       |                            |

*Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.*



## Type 1 Standard Ratings Table (T300MV2) Continued

| Standard Model  | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame | Output Voltage & Frequency |
|-----------------|---------------|----------|-----------|------------|---------------------|---------------------------------|-------|----------------------------|
| M40AN44030 AAA0 | 4160 V        | 300      | 233       | 268        | 37                  | 43                              | 0     | 0~4160 V<br>0~75 Hz        |
| M40AN44035 AAA0 |               | 350      | 272       | 313        | 43                  | 50                              | 0     |                            |
| M40AN44040 AAA0 |               | 400      | 311       | 357        | 50                  | 57                              | 0     |                            |
| M40AN44045 AAA0 |               | 450      | 350       | 402        | 56                  | 64                              | 0     |                            |
| M40AN44050 AAA0 |               | 500      | 389       | 447        | 62                  | 71                              | 0     |                            |
| M40AN44060 AAA0 |               | 600      | 466       | 536        | 74                  | 86                              | 0     |                            |
| M4AAN44030 AAA0 |               | 300      | 233       | 268        | 37                  | 43                              | A4μ   |                            |
| M4AAN44035 AAA0 |               | 350      | 272       | 313        | 43                  | 50                              | A4μ   |                            |
| M4AAN44040 AAA0 |               | 400      | 311       | 357        | 50                  | 57                              | A4μ   |                            |
| M4AAN44045 AAA0 |               | 450      | 350       | 402        | 56                  | 64                              | A4μ   |                            |
| M4AAN44050 AAA0 |               | 500      | 389       | 447        | 62                  | 71                              | A4μ   |                            |
| M4AAN44060 AAA0 |               | 600      | 466       | 536        | 74                  | 86                              | A4μ   |                            |
| M40AN44070 AAA0 |               | 700      | 544       | 625        | 87                  | 100                             | 0     |                            |
| M40AN44080 AAA0 |               | 800      | 622       | 715        | 99                  | 114                             | 0     |                            |
| M40AN44090 AAA0 |               | 900      | 699       | 804        | 112                 | 128                             | 0     |                            |
| M40AN44100 AAA0 |               | 1000     | 777       | 893        | 124                 | 136                             | 0     |                            |
| M4AAN44070 AAA0 |               | 700      | 544       | 625        | 87                  | 100                             | A4    |                            |
| M4AAN44080 AAA0 |               | 800      | 622       | 715        | 99                  | 114                             | A4    |                            |
| M4AAN44090 AAA0 |               | 900      | 699       | 804        | 112                 | 128                             | A4    |                            |
| M4AAN44100 AAA0 |               | 1000     | 777       | 893        | 124                 | 136                             | A4    |                            |
| M41AN44100 AAA0 | 1000          | 777      | 893       | 124        | 143                 | 1                               |       |                            |
| M41AN44125 AAA0 | 1250          | 971      | 1116      | 155        | 178                 | 1                               |       |                            |
| M41AN44150 AAA0 | 1500          | 1166     | 1340      | 186        | 214                 | 1                               |       |                            |
| M41AN44175 AAA0 | 1750          | 1360     | 1563      | 217        | 249                 | 1                               |       |                            |
| M41AN44200 AAA0 | 2000          | 1554     | 1786      | 248        | 273                 | 1                               |       |                            |
| M4BAN44100 AAA0 | 1000          | 777      | 893       | 124        | 143                 | B4                              |       |                            |
| M4BAN44125 AAA0 | 1250          | 971      | 1116      | 155        | 178                 | B4                              |       |                            |
| M4BAN44150 AAA0 | 1500          | 1166     | 1340      | 186        | 214                 | B4                              |       |                            |
| M4BAN44175 AAA0 | 1750          | 1360     | 1563      | 217        | 249                 | B4                              |       |                            |
| M4BAN44200 AAA0 | 2000          | 1554     | 1786      | 248        | 273                 | B4                              |       |                            |
| M42AN44225 AAA0 | 2250          | 1748     | 2010      | 279        | 321                 | 2                               |       |                            |
| M42AN44250 AAA0 | 2500          | 1943     | 2233      | 310        | 356                 | 2                               |       |                            |
| M42AN44300 AAA0 | 3000          | 2331     | 2680      | 372        | 409                 | 2                               |       |                            |
| M4CAN44225 AAA0 | 2250          | 1748     | 2010      | 279        | 321                 | C4                              |       |                            |
| M4CAN44250 AAA0 | 2500          | 1943     | 2233      | 310        | 356                 | C4                              |       |                            |
| M4CAN44300 AAA0 | 3000          | 2331     | 2680      | 372        | 409                 | C4                              |       |                            |
| M43AN44300 AAA0 | 3000          | 2331     | 2680      | 372        | 428                 | 3                               |       |                            |
| M43AN44350 AAA0 | 3500          | 2720     | 3126      | 434        | 499                 | 3                               |       |                            |
| M43AN44400 AAA0 | 4000          | 3108     | 3573      | 496        | 546                 | 3                               |       |                            |
| M44AN44400 AAA0 | 4000          | 3108     | 3573      | 496        | 570                 | 4                               |       |                            |
| M44AN44450 AAA0 | 4500          | 3497     | 4019      | 558        | 642                 | 4                               |       |                            |
| M44AN44500 AAA0 | 5000          | 3885     | 4466      | 620        | 713                 | 4                               |       |                            |
| M44AN44550 AAA0 | 5500          | 4274     | 4913      | 682        | 784                 | 4                               |       |                            |
| M44AN44600 AAA0 | 6000          | 4663     | 5359      | 744        | 818                 | 4                               |       |                            |
| M4GAN44700 AAA0 | 7000          | 5440     | 6252      | 868        | 998                 | G4P                             |       |                            |
| M4GAN44800 AAA0 | 8000          | 6217     | 7146      | 992        | 1091                | G4P                             |       |                            |
| M4HAN44800 AAA0 | 8000          | 6217     | 7146      | 992        | 1141                | H4P                             |       |                            |
| M4HAN44900 AAA0 | 9000          | 6994     | 8039      | 1116       | 1283                | H4P                             |       |                            |
| M4HAN4410K AAA0 | 10000         | 7771     | 8932      | 1240       | 1426                | H4P                             |       |                            |

Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.

## Type 1 Standard Ratings Table (T300MV2) Continued

| Standard Model | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame | Output Voltage & Frequency |
|----------------|---------------|----------|-----------|------------|---------------------|---------------------------------|-------|----------------------------|
| M4BAN66175AAA0 | 6600 V        | 1750     | 1360      | 1563       | 137                 | 158                             | B6S   | 0~6600 V<br>0~75 Hz        |
| M4BAN66200AAA0 |               | 2000     | 1554      | 1786       | 156                 | 179                             | B6S   |                            |
| M4BAN66225AAA0 |               | 2250     | 1748      | 2010       | 176                 | 202                             | B6S   |                            |
| M4BAN66250AAA0 |               | 2500     | 1943      | 2233       | 195                 | 224                             | B6S   |                            |
| M4BAN66300AAA0 |               | 3000     | 2331      | 2680       | 234                 | 269                             | B6S   |                            |
| M4CAN66350AAA0 |               | 3500     | 2720      | 3126       | 273                 | 314                             | C6S   |                            |
| M4CAN66400AAA0 |               | 4000     | 3108      | 3573       | 313                 | 360                             | C6S   |                            |
| M4DAN66450AAA0 |               | 4500     | 3497      | 4019       | 352                 | 405                             | D6S   |                            |
| M4DAN66500AAA0 |               | 5000     | 3885      | 4466       | 391                 | 450                             | D6S   |                            |
| M4FAN66550AAA0 |               | 5500     | 4274      | 4913       | 430                 | 495                             | F6S   |                            |
| M4FAN66600AAA0 |               | 6000     | 4663      | 5359       | 469                 | 539                             | F6S   |                            |
| M4FAN66700AAA0 |               | 7000     | 5440      | 6252       | 547                 | 629                             | F6S   |                            |
| M4FAN66800AAA0 |               | 8000     | 6217      | 7146       | 625                 | 719                             | F6S+  |                            |
| M4FAN66900AAA0 |               | 9000     | 6994      | 8039       | 703                 | 808                             | F6S+  |                            |
| M4FAN77700AAA0 | 6900V         | 7000     | 5440      | 6252       | 523                 | 601                             | F7    | 0~6900 V<br>0~75 Hz        |
| M4FAN77800AAA0 |               | 8000     | 6217      | 7146       | 598                 | 677                             | F7    |                            |
| M4FAN77900AAA0 |               | 9000     | 6994      | 8039       | 673                 | 774                             | F7    |                            |
| M4FAN7710KAAA0 |               | 10000    | 7771      | 8932       | 747                 | 822                             | F7    |                            |

Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.

## Type 3R Standard Ratings Table (MTX)

| Standard Model | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame | Output Voltage & Frequency |
|----------------|---------------|----------|-----------|------------|---------------------|---------------------------------|-------|----------------------------|
| MX40AN44050AAA | 4160 V        | 500      | 389       | 447        | 62                  | 71                              | MTX15 | 0~4160 V<br>0~75 Hz        |
| MX40AN44100AAA |               | 1000     | 777       | 893        | 124                 | 136                             | MTX15 |                            |
| MX40AN44150AAA |               | 1500     | 1166      | 1340       | 186                 | 214                             | MTX15 |                            |
| MX42AN44200AAA |               | 2000     | 1554      | 1786       | 248                 | 273                             | MTX30 |                            |
| MX42AN44250AAA |               | 2500     | 1943      | 2233       | 310                 | 356                             | MTX30 |                            |
| MX42AN44300AAA |               | 3000     | 2331      | 2680       | 372                 | 428                             | MTX30 |                            |

Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.

## Type 3R Standard Ratings Table (MTX2)

| Standard Model | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame   | Output Voltage & Frequency |
|----------------|---------------|----------|-----------|------------|---------------------|---------------------------------|---------|----------------------------|
| MX45AN44050AAA | 4160 V        | 500      | 389       | 447        | 62                  | 71                              | MTX2-15 | 0~4160 V<br>0~75 Hz        |
| MX45AN44100AAA |               | 1000     | 777       | 893        | 124                 | 136                             | MTX2-15 |                            |
| MX45AN44125AAA |               | 1250     | 971       | 1116       | 155                 | 178                             | MTX2-15 |                            |
| MX45AN44150AAA |               | 1500     | 1166      | 1340       | 186                 | 214                             | MTX2-15 |                            |
| MX44AN44350AAA |               | 3500     | 2720      | 3126       | 434                 | 499                             | MTX2-60 |                            |
| MX44AN44400AAA |               | 4000     | 3108      | 3573       | 496                 | 570                             | MTX2-60 |                            |
| MX44AN44450AAA |               | 4500     | 3497      | 4019       | 558                 | 642                             | MTX2-60 |                            |
| MX44AN44500AAA |               | 5000     | 3885      | 4466       | 620                 | 713                             | MTX2-60 |                            |
| MX44AN44550AAA |               | 5500     | 4274      | 4913       | 682                 | 784                             | MTX2-60 |                            |
| MX44AN44600AAA |               | 6000     | 4663      | 5359       | 744                 | 818                             | MTX2-60 |                            |

Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.

### Type 4 or 4X Standard Ratings Table (MTX2)

| Standard Model                   | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame   | Output Voltage & Frequency |
|----------------------------------|---------------|----------|-----------|------------|---------------------|---------------------------------|---------|----------------------------|
| MX45AN44050AAC<br>MX45AN44050AAD | 4160 V        | 500      | 389       | 447        | 62                  | 71                              | MTX2-15 | 0~4160 V<br>0~75 Hz        |
| MX45AN44100AAC<br>MX45AN44100AAD |               | 1000     | 777       | 893        | 124                 | 136                             | MTX2-15 |                            |
| MX45AN44125AAC<br>MX45AN44125AAD |               | 1250     | 971       | 1116       | 155                 | 178                             | MTX2-15 |                            |
| MX45AN44150AAC<br>MX45AN44150AAD |               | 1500     | 1166      | 1340       | 186                 | 214                             | MTX2-15 |                            |

Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.

### Type 1 Regen Standard Ratings Table (T300MV2)

| Standard Model  | Input Voltage | Motor Hp | Output kW | Output KVA | Output Current 100% | Overload Current 110~115%-60 s. | Frame | Output Voltage & Frequency |
|-----------------|---------------|----------|-----------|------------|---------------------|---------------------------------|-------|----------------------------|
| M4AAR44070 AAA0 | 4160 V        | 700      | 544       | 625        | 87                  | 100                             | A4R   | 0~4160 V<br>0~75 Hz        |
| M4AAR44080 AAA0 |               | 800      | 622       | 715        | 99                  | 114                             | A4R   |                            |
| M4AAR44090 AAA0 |               | 900      | 699       | 804        | 112                 | 128                             | A4R   |                            |
| M4AAR44100 AAA0 |               | 1000     | 777       | 893        | 124                 | 136                             | A4R   |                            |
| M4BAR44100 AAA0 |               | 1000     | 777       | 893        | 124                 | 143                             | B4R   |                            |
| M4BAR44125 AAA0 |               | 1250     | 971       | 1116       | 155                 | 178                             | B4R   |                            |
| M4BAR44150 AAA0 |               | 1500     | 1166      | 1340       | 186                 | 214                             | B4R   |                            |
| M4BAR44175 AAA0 |               | 1750     | 1360      | 1563       | 217                 | 249                             | B4R   |                            |
| M4BAR44200 AAA0 |               | 2000     | 1554      | 1786       | 248                 | 273                             | B4R   |                            |

Specifications subject to change without notice. Inverter performance data is based on a typical 4 pole motor operating at 0.87 pf and 0.96 efficiency.

## Protective Functions

The main protective functions are shown in the following table. For other faults or more details, refer to the troubleshooting and EOI manuals.

Protective Function Table

| Item  | Abbreviation                             | Hardware Detection | Software Detection | Heavy Fault   |            | Medium Fault | Light Fault | Start Interlock |
|---|--|--------------------|--------------------|---------------|------------|--------------|-------------|-----------------|
|   |  |                    |                    | Coast to stop | Decel stop | Stop request | Alarm       |                 |
| Input main switch open                            | AC_MCCB                                  |                    | ○                  | ○             |            |              |             |                 |
| No load connected                                 | NO_LOAD                                  |                    | ○                  | ○             |            |              |             |                 |
| Output main switch closed without signal (Welded) | ACSW_C                                   |                    |                    |               |            |              |             | ○               |
| Output main switch opened during operation        | ACSW_F                                   |                    | ○                  | ○             |            |              |             |                 |
| Output main switch open timer                     | ACSW_T                                   |                    | ○                  |               |            |              |             | ○               |
| Brake healthy                                     | B_HLTY                                   |                    | ○                  | ○             |            |              |             |                 |
| External trip from input breaker                  | BLA                                      |                    | ○                  | ○             |            |              |             |                 |
| Electromagnetic brake energizing circuit fault    | BR_F                                     |                    | ○                  |               | ○          |              |             |                 |
| Equipment ventilation fan stop                    | C_FN                                     |                    | ○                  |               |            | ○            | ○           |                 |
| Equipment ventilation fan stop timer              | C_FN_T                                   |                    | ○                  | ○             |            |              |             |                 |
| Current limit timer                               | CL_T                                     |                    | ○                  | ○             |            |              |             |                 |
| Current limit alarm                               | CL_TA                                    |                    | ○                  |               |            | ○            |             |                 |
| Control power supply loss                         | CPSF                                     |                    | ○                  | ○*            |            |              |             |                 |
| P15 or N15 volts Power Supply Fault               | PN15_F                                   |                    | ○                  | ○*            |            |              |             |                 |
| Control Power from UPS Loss                       | UPS_ERR                                  |                    | ○                  | ○*            |            |              |             |                 |
| CPU error   | CPU_A or M                               | ○                  |                    | ○*            |            |              |             |                 |
| GSD brd. clock fault                              | GSD_CLK_DWN                              | ○                  |                    | ○*            |            |              |             |                 |
| GSD brd. voltage supply/programmable device error | GSD_ERR                                  | ○                  |                    | ○*            |            |              |             |                 |
| U or V or W phase feedback error                  | CUR_U or V or W                          |                    | ○                  | ○*            |            |              |             |                 |
| Current Unbalance Between A and B Bank            | CUR_DIFF                                 |                    |                    |               |            |              | ○           |                 |
| Undercurrent Alarm                                | UL_A                                     |                    | ○                  |               |            |              | ○           |                 |
| Undercurrent Time Delayed Fault                   | UL_T                                     |                    | ○                  | ○*            |            |              |             |                 |
| Door open   | DS_T                                     |                    | ○                  | ○*            |            |              |             |                 |
| Rectifier fuse fault                              | FUSE_xP<br>FUSE_xN                       |                    | ○                  | ○*            |            |              |             |                 |
| Ground fault alarm                                | GR_A                                     |                    | ○                  |               |            | ○            | ○           |                 |
| Ground fault trip                                 | GR_T                                     |                    | ○                  | ○             |            |              |             |                 |
| External interlock                                | IL                                       |                    | ○                  | ○             |            |              |             |                 |
| Motor cooling fan stop timer                      | M_FN_T                                   |                    | ○                  |               | ○          |              |             |                 |
| Motor cooling fan stop                            | M_FN                                     |                    | ○                  |               |            | ○            | ○           | ○               |
| Motor overheat                                    | M_OH                                     |                    | ○                  | ○             |            | ○            | ○           |                 |
| Motor overheat alarm                              | M_OH_A                                   |                    | ○                  |               |            | ○            | ○           |                 |
| Main power supply loss                            | MPSF                                     |                    | ○                  | ○*            |            |              |             |                 |
| Motor temperature sensor error                    | MTMP_S                                   |                    | ○                  |               |            | ○            | ○           |                 |
| AC over-current                                   | OCA, OCA_B,<br>OCA_CNV                   |                    | ○                  | ○*            |            |              |             |                 |
| Power Module IGBT over-current                    | OCD_xA1<br>OCD_xA4<br>OCD_xB1<br>OCD_xB4 | ○                  |                    | ○*            |            |              |             |                 |
| Power Module overheat                             | OH_T_x                                   |                    | ○                  | ○*            |            |              |             |                 |
| Input Rectifier Overheat                          | OH_REC                                   |                    | ○                  | ○*            |            |              |             |                 |
| Transformer over heat                             | OH_TR                                    |                    | ○                  | ○*            |            |              |             |                 |
| AC Link Reactor Overheat                          | OH_ACL_T                                 |                    | ○                  | ○*            |            |              |             |                 |

| Item  | Abbreviation   | Hardware Detection | Software Detection | Heavy Fault   |            | Medium Fault | Light Fault | Start Interlock |
|---|----------------|--------------------|--------------------|---------------|------------|--------------|-------------|-----------------|
|   |                |                    |                    | Coast to stop | Decel stop | Stop request | Alarm       |                 |
| Overload alarm                                      | OL_A,OL_A_B    |                    |                    |               |            | O            | O           |                 |
| Overload (5 minutes)                                | OL5, OL5_B     |                    | O                  | O             |            |              |             |                 |
| Overload (20 minutes)                               | OL20, OL20_B   |                    | O                  | O             |            |              |             |                 |
| Over speed  | OSS            |                    | O                  | O*            |            |              |             |                 |
| Output frequency high                               | OSS_F0         |                    | O                  | O*            |            |              |             |                 |
| DC bus over-voltage positive/negative               | OV_xP<br>OV_xN |                    | O                  | O*            |            |              |             |                 |
| Panel safety switch                                 | P_SW           | O                  |                    | O             |            |              |             |                 |
| Emergency Stop by Keypad                            | DSP_ESTP       | O                  |                    | O             |            |              |             |                 |
| Parameter setting error                             | PARA_ERR       |                    | O                  | O             |            |              |             |                 |
| PLL phase error                                     | PHASE_ERR      |                    | O                  | O             |            |              |             |                 |
| PLD error   | PLD_ERR        |                    | O                  | O*            |            |              |             |                 |
| Pre-charge CTT trip                                 | PRE_CTT        |                    | O                  | O             |            |              |             |                 |
| Pre-charge CTT alarm                                | PRE_CTT_F      |                    |                    |               |            | O            | O           | O               |
| DC Bus Charging Failure                             | REC_F          |                    | O                  | O             |            |              |             |                 |
| Rectifier failure                                   | FUSE           |                    | O                  | O*            |            |              |             |                 |
| Reverse rotation failure                            | REV_ROT_F      |                    | O                  | O*            |            |              |             |                 |
| Rotation/start failure                              | ROT_F          |                    | O                  | O*            |            |              |             |                 |
| Soft stall  | SOFT_STL       |                    |                    |               |            |              | O           |                 |
| Analog Input Fault                                  | AIN_FAULT      |                    | O                  | O*            |            |              | O           |                 |
| Speed feedback error                                | SP_ERR         |                    | O                  | O*            |            |              |             |                 |
| Speed feedback error2                               | SP_ERR2        |                    | O                  | O*            |            |              |             |                 |
| Speed reference lost                                | SP_LOST        |                    | O                  | O             | O          |              |             |                 |
| Speed reference lost alarm                          | SP_LST_A       |                    |                    |               |            | O            | O           | O               |
| Motor turning start interlock                       | SP_SIL         |                    |                    |               |            |              |             | O               |
| Spare input 1-4                                     | SPA1-4         |                    | O                  | O*            | O          | O            |             |                 |
| Spare input 1-4 timer                               | SPA1-4_T       |                    | O                  | O*            | O          | O            |             |                 |
| System configuration error                          | SYS_ERR        |                    | O                  |               | O          |              |             |                 |
| Communication error 1-4                             | TL_F1-4        |                    | O                  | O             | O          |              |             |                 |
| Main under-voltage                                  | UV_MPSF        |                    | O                  | O             |            |              |             |                 |
| AC main voltage drop                                | UVA_SIL        |                    |                    |               |            |              |             |                 |
| DC under-voltage start interlock                    | UV_SIL         |                    | O                  | O             |            |              |             | O               |
| DC under-voltage trip                               | UVD, UVD_B     |                    | O                  | O             |            |              |             |                 |
| External equipment electrical ready condition       | UVA_EX         |                    | O                  | O             |            |              |             |                 |
| External safety switch                              | UVS            | O                  |                    | O             |            |              |             |                 |
| Input voltage phase loss                            | VAC_PH_LOSS    |                    | O                  | O             |            |              |             |                 |
| Input Voltage Phase Rotation Error                  | VAC_ROT_F      |                    | O                  | O             |            |              |             |                 |
| Converter Input Phase Lost                          | VCNV_PH_LOSS   |                    | O                  | O             |            |              |             |                 |
| Output current phase loss                           | VINV_PH_LOSS   |                    | O                  | O             |            |              |             |                 |
| Inverter output voltage PLL error                   | VPLL_ERR_      |                    | O                  | O             |            |              |             |                 |
| Transfer Failure                                    | XFR_FAIL       |                    | O                  | O             |            |              |             |                 |
| Transfer Incomplete Sequence                        | XFR_INCMP      |                    |                    |               |            |              | O           |                 |
| Capture Failure                                     | CPT_FAIL       |                    |                    |               |            |              | O           |                 |
| Stator Over Voltage                                 | OV_S           |                    | O                  | O*            |            |              |             |                 |
| Field Current Limit Timer                           | FCL_T          |                    | O                  | O*            |            |              |             |                 |
| Field Current Limit Timer Alarm                     | FCL_TA_        |                    | O                  |               |            | O            |             |                 |
| Exciter Failure (Exciter Detection)                 | FL_FAULT_      |                    | O                  | O*            |            |              |             |                 |
| Instantaneous Field Overcurrent (Exciter Detection) | FOC            |                    | O                  | O*            |            |              |             |                 |
| Instantaneous Field Overcurrent                     | FOC_S          |                    | O                  | O*            |            |              |             |                 |
| Exciter Stopped while Running                       | FSTOP          |                    | O                  | O*            |            |              |             |                 |
| Field Current Lost                                  | LF             |                    | O                  | O*            |            |              |             |                 |
| Limit Fault Reset                                   | LMT_FRST       |                    | O                  | O*            |            |              |             |                 |

(Note 1) Hardware Detection: Items for which all IGBTs are directly turned off by hardware. Software Detection: Items for which the protective interlock operation is performed by detecting errors, via software.

(Note 2) "O" marks in the interlock operation fields can be selected by parameter setting.  
 "\*" indicates that the equipment outputs the trip signal to the input main circuit breaker.  
 "x" indicates the phase (U,V,W).

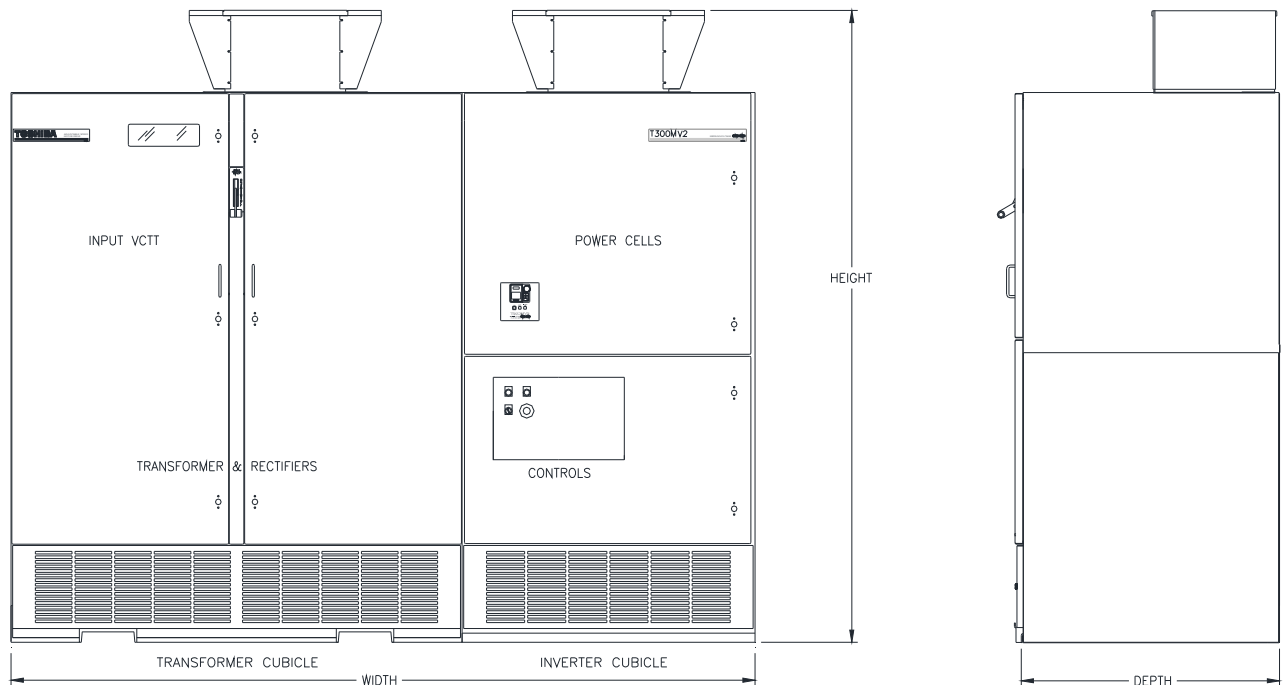
## General Cubicle Structure

The configuration and dimensions of the equipment are described below.

## Cubicle Structure and Dimensions

The equipment is made up of one or more cabinets containing the transformer, incoming terminals, converter section, and the inverter section. All components can all be accessed from the front.

This outline is for the standard Frame 1 model. For details of this and other ratings, see the outline drawing of each product.



### Dimensional Outline of 4160V- Frame 1 Cubicle (See the following page for dimensions)

#### General structure

- 1) Indoor cubicles have a structure that allows maintenance from the front. Rear maintenance access is not required. The cubicles may be placed within 1" of the rear wall. (T300MV2) Refer to the outline drawings for the MTX series as this varies with the frame size.
- 2) Provide a maintenance space of at least 72 inches (1829 mm) in front of the cubicles.
- 3) Provide a clearance of at least 24 inches (610 mm) above the exhaust fans. (T300MV2)
- 4) The following are not included in the dimensions on the next page:
  - a) Handle projections
  - b) Door mounted device projections
  - c) Fastener projections

## Dimensions and Weights of Equipment

### Dimensions of the complete drive, including the power modules

| Standard Model Number | Dimensions – inches (mm) |              |               |               |              |               |               |             |
|-----------------------|--------------------------|--------------|---------------|---------------|--------------|---------------|---------------|-------------|
|                       | H                        | W Input Sect | W Conv Sect 1 | W Conv Sect 2 | W Inv Sect   | W Output Sect | W total       | D           |
| M40AN22030-050AAA0    | 103.7 (2634)             | N/A          | 74 (1880)     | N/A           | *            | N/A           | 74 (1880)     | 43.4 (1102) |
| M4AAN22030-050AAA0    | 103.7 (2634)             | N/A          | 48 (1219)     | N/A           | *            | N/A           | 48 (1219)     | 48 (1219)   |
| M41AN22060-100AAA0    | 103.7 (2634)             | N/A          | 74 (880)      | N/A           | 48 (1219)    | N/A           | 122 (3099)    | 43.4 (1102) |
| M4BAN22060-100AAA0    | 103.7 (2634)             | N/A          | 74 (1880)     | N/A           | *            | N/A           | 74 (1880)     | 43.4 (1102) |
| M43AN22125-200AAA0    | 103.7 (2634)             | N/A          | 90 (2286)     | N/A           | 84 (2134)    | N/A           | 174 (4420)    | 49.5 (1257) |
| M4DAN22125-200AAA0    | 103.7 (2634)             | N/A          | 74 (880)      | N/A           | 48 (1219)    | N/A           | 122 (3099)    | 49.5 (1257) |
| M44AN22225-300AAA0    | 103.7 (2634)             | N/A          | 111 (2819)    | N/A           | 111 (2819)   | N/A           | 222 (5639)    | 49.5 (1257) |
| M40AN44030-100AAA0    | 103.7 (2634)             | N/A          | 74 (1880)     | N/A           | *            | N/A           | 74 (1880)     | 43.4 (1102) |
| M4AAN44030-60AAA0     | 103.7 (2634)             | N/A          | 48 (1219)     | N/A           | *            | N/A           | 48 (1219)     | 48 (1219)   |
| M4AAN44070-100AAA0    | 103.7 (2634)             | N/A          | 60 (1524)     | N/A           | *            | N/A           | 60 (1524)     | 48 (1219)   |
| M41AN44100-200AAA0    | 103.7 (2634)             | N/A          | 74 (1880)     | N/A           | 48 (1219)    | N/A           | 122 (3099)    | 43.4 (1102) |
| M4BAN44100-200AAA0    | 103.7 (2634)             | N/A          | 90 (2286)     | N/A           | *            | N/A           | 90 (2286)     | 48 (1219)   |
| M42AN44225-300AAA0    | 103.7 (2634)             | N/A          | 90 (2286)     | N/A           | 74 (1880)    | N/A           | 164 (4166)    | 49.5 (1257) |
| M4CAN44225-300AAA0    | 103.7 (2634)             | N/A          | 80 (2032)     | N/A           | 74 (1880)    | N/A           | 154 (3912)    | 49.5 (1257) |
| M43AN44300-400AAA0    | 103.7 (2634)             | N/A          | 90 (2286)     | N/A           | 84 (2134)    | N/A           | 174 (4420)    | 49.5 (1257) |
| M44AN44400-600AAA0    | 103.7 (2634)             | N/A          | 111 (2819)    | N/A           | 111 (2819)   | N/A           | 222 (5639)    | 49.5 (1257) |
| M4GAN44700-800AAA0    | 103.7 (2634)             | 51 (1295)    | 118.5 (3010)  | N/A           | 90 (2286)    | 48 (1219)     | 307.5 (7811)  | 60 (1524)   |
| M4HAN44800-10KAAA0    | 103.7 (2634)             | 51 (1295)    | 92.5 (2350)   | 100 (2540)    | 111 (2819)   | 48 (1219)     | 402.5 (10224) | 60 (1524)   |
| M4BAN66175-300AAA0    | 103.7 (2634)             | 30 (762)     | 74 (1880)     | N/A           | 48 (1219)    | 24 (610)      | 176 (4470)    | 48 (1219)   |
| M4CAN66350-400AAA0    | 103.7 (2634)             | 36 (914)     | 100 (2540)    | N/A           | 74 (1880)    | 24 (610)      | 234 (5944)    | 60 (1524)   |
| M4DAN66450-500AAA0    | 103.7 (2634)             | 36 (914)     | 100 (2540)    | N/A           | 90 (2286)    | 24 (610)      | 265 (6731)    | 60 (1524)   |
| M4FAN66550-700AAA0    | 103.7 (2634)             | 51 (1295)    | 118.5 (3010)  | N/A           | 111 (2819)   | 24 (610)      | 304.5 (7734)  | 60 (1524)   |
| M4FAN66800-900AAA0    | 103.7 (2634)             | 51 (1295)    | 92.5 (2350)   | 100 (2540)    | 111 (2819)   | 24 (610)      | 378.5 (9614)  | 60 (1524)   |
| M4FAN77800-10KAAA0    | 122.3 (3106)             | 51 (1295)    | 118.5 (3010)  | 48 (1219)     | 111 (2819)   | 48.1 (1222)   | 376.6 (9566)  | 60 (1524)   |
| MX40AN44050-150AAA    | 107.2 (2723)             | N/A          | 84 (2134)     | N/A           | 84 (2134)    | N/A           | 168 (4267)    | 63 (1600)   |
| MX42AN44200-300AAA    | 107.2 (2723)             | N/A          | 104 (2642)    | N/A           | 133.5 (3391) | N/A           | 237.5 (6033)  | 72 (1829)   |
| MX45AN44050-150AAA    | 107.8 (2738)             | N/A          | 109.5 (2781)  | *             | N/A          | N/A           | 109.5 (2781)  | 77 (1956)   |
| MX44AN44350-600AAA    | 110.1 (2797)             | 56.9 (1445)  | 128.1 (3254)  | 57(1448)***   | 143.9(3655)  | N/A           | 385.9 (9802)  | 73.2 (1859) |
| M4AAR44070-100 AAA0   | 103.7 (2634)             | N/A          | 60 (1524)     | N/A           | 36 (914)     | N/A           | 96 (2438)     | 48 (1219)   |
| M4BAR44100-100 AAA0   | 103.7 (2634)             | N/A          | 90 (2286)     | N/A           | 50 (1270)    | N/A           | 140 (3556)    | 48 (1219)   |

## Dimensions and weights of equipment (cont'd)

### Weights of the complete drive, including the power modules

| Standard Model Number | Weight Input lbs (kg) | Weight Conv1** lbs (kg) | Weight Conv2** lbs (kg) | Weight Inv** lbs (kg) | Weight Output** lbs (kg) |
|-----------------------|-----------------------|-------------------------|-------------------------|-----------------------|--------------------------|
| M40AN22030-050AAA0    | N/A                   | 6000 (2727)             | N/A                     | *                     | N/A                      |
| M4AAN22030-050AAA0    | N/A                   | 5500 (2500)             | N/A                     | *                     | N/A                      |
| M41AN22060-100AAA0    | N/A                   | 6500 (2949)             | N/A                     | 2500 (1134)           | N/A                      |
| M4BAN22060-100AAA0    | N/A                   | 8600 (3909)             | N/A                     | *                     | N/A                      |
| M43AN22125-200AAA0    | N/A                   | 10500 (4763)            | N/A                     | 4500 (2041)           | N/A                      |
| M4DAN22125-200AAA0    | N/A                   | 10000 (4545)            | N/A                     | 2800 (1273)           | N/A                      |
| M44AN22225-300AAA0    | N/A                   | 13000 (5897)            | N/A                     | 6000 (2722)           | N/A                      |
| M40AN44030-100AAA0    | N/A                   | 8000 (3636)             | N/A                     | *                     | N/A                      |
| M4AAN44030-60AAA0     | N/A                   | 6600 (3000)             | N/A                     | *                     | N/A                      |
| M4AAN44070-100AAA0    | N/A                   | 7600 (3447)             | N/A                     | *                     | N/A                      |
| M41AN44100-200AAA0    | N/A                   | 10500 (4763)            | N/A                     | 2500 (1134)           | N/A                      |
| M4BAN44100-200AAA0    | N/A                   | 12500 (5681)            | N/A                     | *                     | N/A                      |
| M42AN44225-300AAA0    | N/A                   | 12800 (5818)            | N/A                     | 4500 (2041)           | N/A                      |
| M4CAN44225-300AAA0    | N/A                   | 12800 (5818)            | N/A                     | 4500 (2041)           | N/A                      |
| M43AN44300-400AAA0    | N/A                   | 14300 (6500)            | N/A                     | 6000 (2722)           | N/A                      |
| M44AN44400-600AAA0    | N/A                   | 24000 (10909)           | N/A                     | 6300 (2858)           | N/A                      |
| M4GAN44700-800AAA0    | 3000 (1364)           | 25500 (11591)           | N/A                     | 8300 (3772)           | 3000 (1364)              |
| M4HAN44800-10KAAA0    | 3100 (1409)           | 20500 (9318)            | 20500 (9318)            | 9600 (4364)           | 3500 (1591)              |
| M4BAN66175-300AAA0    | 1400 (636)            | 12500 (5682)            | N/A                     | 3900 (1773)           | 1000 (455)               |
| M4CAN66350-400AAA0    | 1800 (818)            | 18000 (8182)            | N/A                     | 6000 (2727)           | 1500 (682)               |
| M4DAN66450-500AAA0    | 3000 (1364)           | 20000 (9090)            | N/A                     | 7500 (3409)           | 1700 (773)               |
| M4FAN66550-700AAA0    | 3000 (1364)           | 23000 (10545)           | N/A                     | 9500 (4318)           | 2000 (909)               |
| M4FAN66800-900AAA0    | 3000 (1364)           | 16000 (7273)            | 16000 (7273)            | 9500 (4318)           | 2000 (909)               |
| M4FAN77700-10KAAA0    | 2600 (1182)           | 29500 (13409)           | 2000 (909)****          | 8300 (3273)           | 2375 (1080)              |
| MX40AN44050-150AAA    | N/A                   | 10000 (4545)            | N/A                     | 5000 (2273)           | N/A                      |
| MX42AN44200-300AAA    | N/A                   | 18000 (8182)            | N/A                     | 6500 (2955)           | N/A                      |
| MX45AN44050-150AAA    | N/A                   | 16000 (7273)            | N/A                     | *                     | N/A                      |
| MX44AN44350-600AAA    | 3000 (1364)           | 28000 (12701)           | 3000 (1364)***          | 7500 (3402)           | N/A                      |
| M4AAR44070-100 AAA0   | N/A                   | 7340 (3336)             | N/A                     | 1900 (864)            | N/A                      |
| M4BAR44100-200 AAA0   | N/A                   | 12500 (5681)            | N/A                     | 2700 (1227)           | N/A                      |

“\*” Inverter and converter sections combined into one cubicle.

“\*\*\*” Maximum weight for the frame size with the standard transformer and no options. Consult the factory for weights for non-standard inverters, as they are job specific.

“\*\*\*\*” Rectifier and control section

“\*\*\*\*\*” Rectifier section



## Dimensions and weights of equipment (cont'd)

### Dimensions and weights of the inverter power modules for T300MV2 drives

| Drive Model Number | Module Voltage Class | Module Dimensions – inches (mm) |             |             | Weight lbs (kg) |
|--------------------|----------------------|---------------------------------|-------------|-------------|-----------------|
|                    |                      | Width                           | Depth       | Height      |                 |
| M40AN22030-050AAA0 | 2400                 | 9.6 (244)                       | 27.0 (686)  | 24.2 (615)  | 120 (54)        |
| M4AAN22030-050AAA0 | 2400                 | 6.6 (168)                       | 15.4 (391)  | 21.0 (533)  | 31 (14)         |
| M41AN22060-100AAA0 | 2400                 | 11.6 (295)                      | 30.2 (767)  | 31.6 (803)  | 235 (107)       |
| M4BAN22060-100AAA0 | 2400                 | 9.9 (251)                       | 26.8 (681)  | 11.1 (282)  | 71 (32)         |
| M43AN22125-200AAA0 | 2400                 | 24.0 (610)                      | 38.0 (965)  | 35.3 (897)  | 512 (232)       |
| M4DAN22125-200AAA0 | 2400                 | 13.3 (338)                      | 24.7 (627)  | 12.8 (325)  | 105 (48)        |
| M44AN22225-300AAA0 | 2400                 | 31.2 (792)                      | 35.4 (899)  | 38.6 (980)  | 650 (295)       |
| M40AN44030-100AAA0 | 4160                 | 9.6 (244)                       | 27.0 (686)  | 24.2 (615)  | 140 (64)        |
| M4AAN44030-60AAA0  | 4160                 | 7.1 (181)                       | 31.8 (808)  | 24.1 (613)  | 120 (55)        |
| M4AAN44070-100AAA0 | 4160                 | 9.6 (244)                       | 27.0 (686)  | 24.2 (615)  | 140 (64)        |
| M41AN44100-200AAA0 | 4160                 | 11.6 (295)                      | 30.2 (767)  | 31.6 (803)  | 260 (118)       |
| M4BAN44100-200AAA0 | 4160                 | 11.6 (295)                      | 30.2 (767)  | 31.6 (803)  | 260 (118)       |
| M42AN44225-300AAA0 | 4160                 | 16.7 (424)                      | 35.4 (899)  | 38.6 (980)  | 400 (181)       |
| M4CAN44225-300AAA0 | 4160                 | 16.7 (424)                      | 35.4 (899)  | 38.6 (980)  | 400 (181)       |
| M43AN44300-400AAA0 | 4160                 | 24.0 (610)                      | 38.0 (965)  | 35.3 (897)  | 580 (263)       |
| M44AN44400-600AAA0 | 4160                 | 31.2 (792)                      | 35.4 (899)  | 38.6 (980)  | 800 (363)       |
| M4GAN44700-800AAA0 | 4160                 | 24.0 (610)                      | 38.0 (965)  | 35.3 (897)  | 580 (263)       |
| M4HAN44800-10KAAA0 | 4160                 | 31.2 (792)                      | 35.4 (899)  | 38.6 (98)   | 800 (363)       |
| M4BAN66175-300AAA0 | 2400                 | 11.6 (295)                      | 31.4 (798)  | 31.6 (803)  | 265 (120)       |
|                    | 4160                 | 11.6 (295)                      | 33.0 (838)  | 31.6 (803)  | 290 (132)       |
| M4CAN66350-400AAA0 | 2400                 | 16.7 (424)                      | 35.4 (899)  | 38.6 (980)  | 280 (127)       |
|                    | 4160                 | 16.7 (424)                      | 35.4 (899)  | 38.6 (980)  | 400 (181)       |
| M4DAN66450-500AAA0 | 2400                 | 24.0 (610)                      | 38.0 (965)  | 35.3 (897)  | 512 (233)       |
|                    | 4160                 | 24.0 (610)                      | 38.0 (965)  | 35.3 (897)  | 580 (263)       |
| M4FAN66550-900AAA0 | 2400                 | 15.7 (399)                      | 35.4 (899)  | 38.6 (980)  | 329 (150)       |
|                    | 4160                 | 31.2 (792)                      | 35.4 (899)  | 38.6 (980)  | 800 (363)       |
| M4FAN77700-10KAAA0 | 6900                 | 30.7 (780)                      | 54.0 (1372) | 46.0 (1168) | 1250 (568)      |
| MX45AN44050-150AAA | 4160                 | 23.4 (594)                      | 47.7 (1212) | 23.8 (605)  | 400 (181)       |
| MX44AN44350-600AAA | 4160                 | 31.8 (808)                      | 35.1 (892)  | 78.1 (1984) | 1100 (499)      |
| M4AAR44070-100AAA0 | 4160                 | 9.6 (244)                       | 27.0 (686)  | 24.2 (615)  | 140 (64)        |
| M4BAR44100-200AAA0 | 4160                 | 11.6 (295)                      | 30.2 (767)  | 31.6 (803)  | 260 (118)       |

## INTERFACE

The interface between the drive system and external devices is divided into two categories: power supply system and control system.

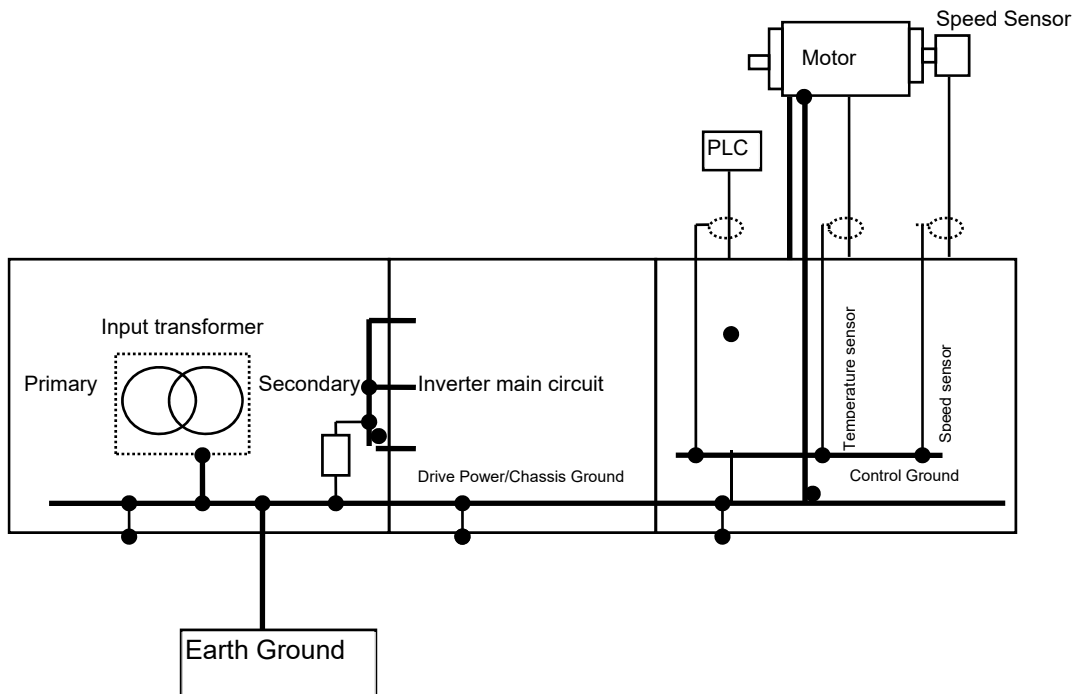
### Power Supply Interface and Ground

The standard power supplies required are the main circuit input of 2400/4160V 3 $\Phi$  and (optional) control power supplies of 120V 1 $\Phi$  and AC480V 3 $\Phi$ .

The following figure shows a recommended grounding circuit for the related equipment. Grounding is intended not only for safety but also to reduce noise problems. The control ground bus is mounted on insulated standoffs. It may be separated from the power ground and run separately to the earth ground with insulated cable if noise problems are encountered with auxiliary control devices.

**Grounding must follow local and national codes** by attaching a properly sized ground conductor to the drive equipment.

### Recommended Ground Circuit



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## INTERFACE (cont'd)

### Motor Interface

If armored and shielded cables are to be used, be sure to connect the shield drain or armor to the ground bus provided in the drive equipment near the output terminals (U, V, W). It is not recommended that both ends be grounded. Ensure that the motor is connected properly at the junction box and properly insulated to protect against accidental shorting or grounding.

### Speed Sensor Interface (Option)

In addition to open loop control, it is also possible to use a speed sensor to perform high precision speed control. Speed sensor selection explained below

### Resolver

The drive is capable of accepting both 1x and 4x resolver feedback. The excitation can be either 1 or 4kHz. For resolver feedback, the following parameters need to be set:

CS\_RES\_TYPE=1or4 (Set to match the resolver)  
CS\_PG\_OUT= Set to desired PG output count. (Minimum setting for resolver use is 64)  
(See parameter manual for exact settings)  
CS\_PG\_CNT=64  
FLG\_RES\_EX4= 0 for 1kHz, 1 for 4kHz

### PG (Pulse Generator)

This drive can read single ended or differential PG signals. The maximum frequency that the PG input can read is 10kHz for single ended and 100kHz for differential. The PG should be selected so that these limits are never exceeded. It is recommended that a 10% margin be allowed for overspeed. The following is an example of how to select your PG.

PG pulse count (PPR) = (maximum frequencyx0.9)/ (application top motor speed (min<sup>-1</sup>) / 60)

<Example> When 100% speed is 1800 min<sup>-1</sup>  
Max PG pulse count = (10000x0.9)/(1800/60) = 300 PPR  
Therefore, PG of 300 PPR or less is used.

The following settings should be used:  
CS\_RES\_TYPE=1  
CS\_PG\_OUT=0  
CS\_PGCNT = 256 (Set to the PPR of the PG.)

There are three PLG types, a differential type, a single-end totem pole type, and a single-end open collector type. The connections to the PLG, the jumper setting of XIO brd., and the parameter settings for each PLG are different.

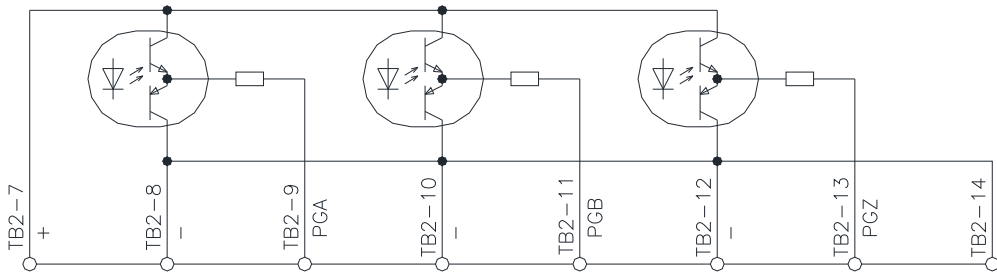
## INTERFACE (cont'd)

### Pulse Signal Output

If a speed sensor is used, speed feedback signals can be output as pulse signals. The PG pulse output circuit is shown in the following figure. The power supply for the pulses should be supplied from an outside source in a range of 12 V to 24 V. The max loading allowed is 25mA. The number of pulses per revolution output can be set using the parameter CS\_PGOUT when a resolver is used. See the parameter setting manual for exact settings. Otherwise, set to zero when using a PG. With a PG, the number of pulses out equals the number of pulses in.

The PG pulse output consists of two phases of PGA and PGB at 90° separation and PGZ when a PG with a marker pulse is used. These pulse signals, at the level of the power supplied from an outside source, are isolated from the control power supply of the drive, through photo-couplers.

### Pulse Output Circuit



## Digital Input

A total of 10 programmable digital inputs (DI1 to DI10) are provided. DI1-2 are capable of accepting an external voltage input (24VDC). DI3-10 are internally connected to the drive's internal 24VDC power supply and should only be connected to dry contacts. These input signals can be individually assigned to bits in the DI\_EX1~7 and DIEX9~11 words. The available input assignments are shown below. For more detail refer to the parameter setting manual.

Digital Input Options

| BIT | DI_EX1 | DI_EX2    | DI_EX3       | DI_EX4 | DI_EX5    |
|-----|--------|-----------|--------------|--------|-----------|
| F   | IL     | N.U.      | QSTOP        | N.U.   | JOG3      |
| E   | UVS    | N.U.      | UVS          | SPA0   | JOG2      |
| D   | EXT0   | N.U.      | EXT0         | FLD    | JOG1      |
| C   | SPA1   | SPA4      | CM_BUF1      | B      | JOG0      |
| B   | BRTST  | SPA3      | CM_BUF2      | SC_PPI | EX_LMT_I1 |
| A   | ST     | SPA2      | ST           | 2S     | EX_LMT_TR |
| 9   | F      | BLA       | F            | 3S     | SP_UP     |
| 8   | R      | M_FN      | R            | R_TEN  | SP_DN     |
| 7   | 3S     | OH_ACL_EX | 3S           | ST     | SEL_DI    |
| 6   | 2S     | E_DRIVE   | 2S           | LB     | DIR0      |
| 5   | B      | HOLD      | N.U.         | N.U.   | DIR1      |
| 4   | FLD    | QSTOP     | FLD          | BC     | START0    |
| 3   | BC     | F_LMT     | LATCH_PG_POS | N.U.   | START1    |
| 2   | SPA0   | R_LMT     | SPA0         | UVS    | STOP0     |
| 1   | EXRST  | B_HLTY    | EXRST        | EXT0   | STOP1     |
| 0   | R_TEN  | BA        | R_TEN        | EXRST  | EXT1      |

| BIT | DI_EX6    | DI_EX7 | DI_EX9       | DI_EX10    | DI_EX11      |
|-----|-----------|--------|--------------|------------|--------------|
| F   | N.U.      | N.U.   | MP_BE_TM_H1  | MP_BR01_CL | MP_OL_TM_A   |
| E   | N.U.      | N.U.   | MP_BE_TM_H2  | MP_BR02_CL | MP_OL_TM_TR  |
| D   | PR_ST     | N.U.   | MP_BE_TM_H3  | MP_BR03_CL | MP_WD_TM_A   |
| C   | RATE_CHG  | F      | MP_CF1_MR    | MP_BR04_CL | MP_WD_TM_TR  |
| B   | FL_FOC    | R      | MP_CF2_MR    | MP_BR05_CL | MP_OL_LVL_A  |
| A   | FL_READY  | N.U.   | MP_CF1_MCC_F | MP_BR06_CL | MP_OL_LVL_TR |
| 9   | FL_RNTD   | R_TEN  | MP_CF2_MCC_F | MP_BR07_CL | MP_PRD_A     |
| 8   | FL_FAULT  | N.U.   | MP_CWF_L1    | MP_BR08_CL | MP_PRD_TR    |
| 7   | CHG_2S    | EXRST  | MP_CW_TM_H1  | MP_BR09_CL | MP_BH_RL_A   |
| 6   | SEL_MRH   | 3S     | MP_OLU_LFD   | MP_BR10_CL | MP_BH_RL_TR  |
| 5   | ASD       | 2S     | MP_OLU_HFD   | MP_WLK1    | MP_GP_RL_TR  |
| 4   | IM_NUM_B1 | B      | MP_OLU_HPL_N | MP_CF_IL   | N.U.         |
| 3   | IM_NUM_B0 | EXT0   | MP_OLU_LPL_N | MP_SPH_IL  | N.U.         |
| 2   | XFR_CHK   | QSTOP  | MP_SPH_ON    | MP_OL_P_IL | N.U.         |
| 1   | CPT       | IL     | MP_SPH_MCC_F | N.U.       | N.U.         |
| 0   | XFR       | UVS    | MP_SW_TM_H   | N.U.       | N.U.         |

## INTERFACE (cont'd)

### Digital Input Descriptions \*\*

| Name      | Description                               |  |
|-----------|---|--|
| 2S        | 2-speed reference command                 | 1: 2-speed reference command   |
| 3S        | 3-speed reference command                 | 1: 3-speed reference command   |
| ASD       | Variable speed drive operation command    |  |
| B         | Brake command                             | 1: Brake release command   |
| BA        | Brake answer                              |  |
| BC_       | Brake close command                       | 0: Brake close   |
| BLA_      | AC Circuit breaker                        |  |
| BRTST     | Brake test                                | 1: Brake release (open)  |
| B_HLTY    | Brake normal (healthy)                    |  |
| CHG_2S    | E2P bank selection                        |  |
| CM_BUF1   | Command buffer bit 1                      |  |
| CM_BUF2   | Command buffer bit 2                      |  |
| CPT       | Capture command                           |  |
| DIR0      | Motor rotation direction command (Local)  | 0: Forward; 1: Reverse   |
| DIR1      | Motor rotation direction command (Remote) | 0: Forward; 1: Reverse   |
| E_DRIVE   | Emergency hard I/O operation              | For external signal input  |
| EXT       | Startup command                           | 1: Startup command   |
| EXT1      | Startup command (Remote)                  | 1: Startup command (SEL=1)   |
| EXRST     | External reset                            | 1: Reset request   |
| EX_LMT_I1 | Motor primary current limit selection     | 0: Internal; 1: External   |
| EX_LMT_TR | Torque limit selection                    | 0: Internal; 1: External   |
| F         | Forward jog run command                   | 1: Forward inching command   |
| F_LMT_    | Forward limit                             |  |
| FL_FAULT  | Field critical fault                      |  |
| FL_FOC    | Field over current                        |  |
| FL_READY  | Field ready                               |  |
| FL_RNTD   | Filed running                             | 1: Field exciter RUN I/F used  |
| FLD       | Field excitation command                  | 1: Field excitation command  |
| HOLD      | Emergency speed hold                      |  |
| IL        | External interlock                        | 0: Operation permitted   |
| IL_       | External interlock                        | 1: Operation permitted<br>Off while running; causes a deceleration stop. |
| IM_NUM_B0 | Motor unit count switch bit 0             |  |
| IM_NUM_B1 | Motor unit count switch bit 1             |  |

## INTERFACE (cont'd)

### Digital Input Descriptions \*\*

| Name          | Description                         |   |
|---------------|-------------------------------------|---|
| JOG0          | Jog speed reference selection bit 0 |   |
| JOG1          | Jog speed reference selection bit 1 |   |
| JOG2          | Jog speed reference selection bit 2 |   |
| JOG3          | Jog speed reference selection bit 3 |   |
| LATCH_PG_POS  | PG counter latch command            | Latch at rising and falling edges of this signal. |
| LB            | Load balance between stands         | Load balance control when 1                       |
| M_FN_         | Motor fan stopped                   |   |
| MP_BE_TM_H1_  | BearingTempHigh1                    | 0:Temperature High                                |
| MP_BE_TM_H2_  | BearingTempHigh2                    | 0:Temperature High                                |
| MP_BE_TM_H3_  | BearingTempHigh3                    | 0:Temperature High                                |
| MP_BH_RL_A_   | BuchholzRelayAlarm                  | 0:Alarm   |
| MP_BH_RL_TR_  | BuchholzRelayTrip                   | 0:Trip  |
| MP_BR01_CL    | MotorBreaker01Closed                | 1:Closed  |
| MP_BR02_CL    | MotorBreaker02Closed                | 1:Closed  |
| MP_BR03_CL    | MotorBreaker03Closed                | 1:Closed  |
| MP_BR04_CL    | MotorBreaker04Closed                | 1:Closed  |
| MP_BR05_CL    | MotorBreaker05Closed                | 1:Closed  |
| MP_BR06_CL    | MotorBreaker06Closed                | 1:Closed  |
| MP_BR07_CL    | MotorBreaker07Closed                | 1:Closed  |
| MP_BR08_CL    | MotorBreaker08Closed                | 1:Closed  |
| MP_BR09_CL    | MotorBreaker09Closed                | 1:Closed  |
| MP_BR10_CL    | MotorBreaker10Closed                | 1:Closed  |
| MP_CF_IL_     | CoolingFan I/L SW                   | 0:Interlocked                                     |
| MP_CF1_MCC_F_ | CoolingFan1MCC Fault                | 0:Fault   |
| MP_CF1_MR     | CoolingFan1MotorRun                 | 1:Running   |
| MP_CF2_MCC_F_ | CoolingFan2MCC Fault                | 0:Fault   |
| MP_CF2_MR     | CoolingFan2MotorRun                 | 1:Running   |
| MP_CW_TM_H1_  | CoolingWaterTempHi1                 | 0:Temperature High                                |
| MP_CWF_L1_    | CoolingWaterFlowLow1                | 0:Flow Low  |
| MP_GP_RL_TR_  | SuddenGasPressRyTrip                | 0:Trip  |
| MP_OL_LVL_A_  | OilLevelAlarm                       | 0:Alarm   |
| MP_OL_LVL_TR_ | OilLevelTrip                        | 0:Trip  |
| MP_OL_P_IL_   | OilLubPump I/L SW                   | 0:Interlocked                                     |
| MP_OL_TM_A_   | OilTemperatureAlarm                 | 0:Alarm   |
| MP_OL_TM_TR_  | OilTemperatureTrip                  | 0:Trip  |
| MP_OLU_HFD_   | OilLubricationUniHFD                | 0:Fault   |
| MP_OLU_HPL_N  | OilLubUHIPressLineN                 | 1:Normal  |
| MP_OLU_LFD_   | OilLubricationUniLFD                | 0:Alarm   |

## INTERFACE (cont'd)

### Digital Input Descriptions \*\*

| Name          | Description                               |   |
|---------------|---|---|
| MP_OLU_LPL_N  | OilLubULowPressLineN                      | 1:Normal  |
| MP_PRD_A_     | PressReliefDevAlarm                       | 0:Alarm   |
| MP_PRD_TR_    | PressReliefDevTrip                        | 0:Trip  |
| MP_SPH_IL_    | SpaceHeater I/L SW                        | 0:Interlocked   |
| MP_SPH_MCC_F_ | SpaceHeaterMCC Fault                      | 0:Fault   |
| MP_SPH_ON     | SpaceHeater On                            | 1:On  |
| MP_SW_TM_H_   | StatorWindTempHigh                        | 0:Temperature High  |
| MP_WD_TM_A_   | WindingTempAlarm                          | 0:Alarm   |
| MP_WD_TM_TR_  | WindingTempTrip                           | 0:Trip  |
| MP_WLK1_      | WaterLeakage1                             | 0:Leakage   |
| N.U.          | Not used                                  |   |
| OH_ACL_       | ACL overheating                           |   |
| PLC           | PLC Control                               | 1:PLC Control (Always set to 1)   |
| PR_ST         | PID control start                         |   |
| QSTOP         | Emergency stop                            | 1: Emergency stop command   |
| R             | Reverse jog run command                   | 1: Reverse inching command  |
| R_LMT_        | Reverse limit                             |   |
| R_TEN         | Reverse rotation command                  | 1: Reverse winding, 0: Forward winding (Torque direction when torque is controlled) |
| RATE_CHG      | Optional rate selection                   |   |
| SC_PPI        | Speed control P/PI switching              | P control when 1, PI control when 0   |
| SEL_DI        | Operation (Local/Remote) system selection | 0: Local 1: Remote  |
| SEL_MRH       | MRH Enable                                |   |
| SPA0          | Spare 0                                   |   |
| SPA1          | Spare 1                                   |   |
| SPA2          | Spare 2                                   |   |
| SPA3          | Spare 3                                   |   |
| SPA4          | Spare 4                                   |   |
| SP_DN         | Speed down                                | Slow down while on  |
| SP_UP         | Speed up                                  | Speed up while on   |
| ST            | Torque control selection                  | 1: Tension control, 0: speed control  |
| START0        | Start button (Local)                      | One shot to start (SEL=0)   |
| START1        | Start button (Remote)                     | One shot to start (SEL=1)   |
| STOP0         | Stop button (Local)                       | One shot to stop (SEL=0)  |
| STOP1         | Stop button (Remote)                      | One shot to stop (SEL=1)  |
| UVS           | External safety switch                    | Operation enabled when 1  |
| XFR           | Transfer command                          |   |
| XFR_CHK       | Synchronization relay input               | 1 when Synch check relay is satisfied   |

\*\*\* The function of many operation signals can be reversed via sign bit settings if needed.



## INTERFACE (cont'd)

### Digital Output

There are 10 programmable digital outputs (DO1-10). DO1-4 are photo-coupler outputs and must be used with 24Vdc. DO1-3 may be connected to an external 24V supply if desired. DO4 is connected the drive internal 24V supply. The other 6 outputs (DO5-10) are form C relay outputs. These relays can be programmed to any bit in any word in the drive. The most commonly used bits can be found in the SSEQ\_OUT1-4 words. The word assignment is made via DO1\_AS – DO10\_AS parameters.

### Analog Input

The drive has three general-purpose analog inputs (AIN1-3). They can be configured to any variable in the drive through assignment of AINn\_AS (where n = 1 to 3 ).

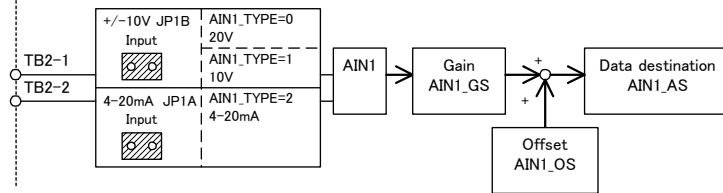
As a general-purpose analog input, the standard I/O circuit brd. (XIO) has one general-purpose analog input (AIN1). Expanded I/O brd. (EXIO) has two additional inputs (AIN2 and AIN3). AIN1 has an option for current input thru an internal resistor, but AIN2 and 3 are voltage input only.

Each analog input signal is converted to the digital value through a 12-bit A/D converter. A  $\pm 10$  Vdc input is converted to counts by software and is stored in the target data register. Since this signal is directly connected to the control circuit, it is recommended that an isolation transducer be used. The data register, the gain and the offset are set with the following parameters:

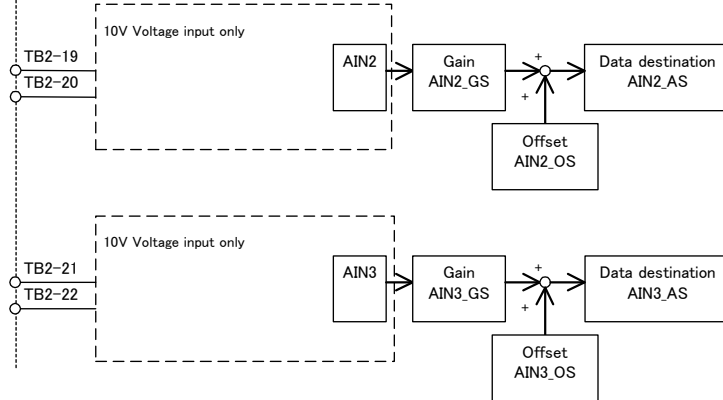
- AIN#\_AS      Target register – set by symbol name
- AIN#\_GS      Gain setting – defines the number of counts for 10V input
- AIN#\_OS      Offset setting – offsets the input

The "#" of each parameter name denotes the AD channel number. The following figure shows the input circuit:

XIO, ARND-4045



EXIF, PC61910P206A



**Analog Input Circuit**

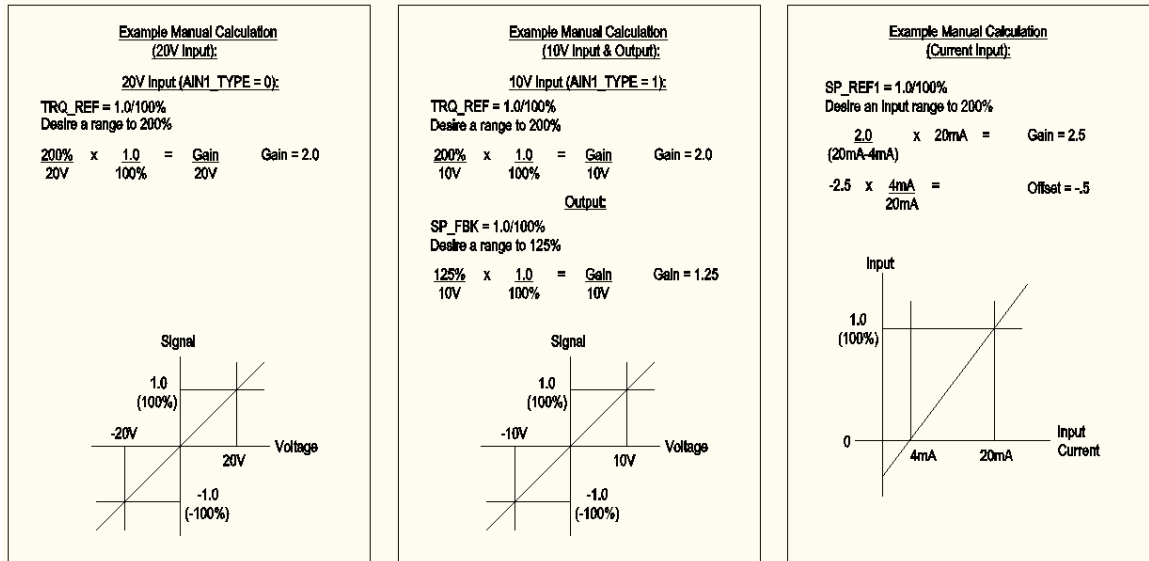
## INTERFACE (cont'd)

[Setting examples]

**Example 1:** Analog speed reference is input to AIN1.

Set 0 to 100% (0 to 1.0) speed reference signal at 0 to +10 V so that it is stored in SP\_REF1. Use a personal computer with the maintenance tool installed for setting the parameters. The input characteristic is shown in the following figure.

AIN1\_TYPE = 1  
 AIN1\_OS = 0  
 AIN1\_AS = SP\_REF\_AIN1  
 AIN1\_GS = (1.0 / 10 V) x 10 V  
 = 1.0



### Input Characteristic Example

**Example 2** When a 4~20 mA (0 to 100%) speed reference is input to AIN1, it is recommended that a 4-20 mA / 0-10 VDC transducer be used. If the source is isolated, an internal 510 Ohm burden resistor may also be used via a jumper on the brd.. This would give 2VDC at 4mA. In this case, an offset would need to be set in the drive as follows:

AIN1\_GS = 2 / (20mA - 4mA) x 20mA = 2.5  
 AIN1\_OS = -2.5 x 4mA / 20mA = -0.5  
 AIN1\_AS = SP\_REF\_AIN1  
 AIN1\_TYPE = 1

## INTERFACE (cont'd)

### Analog Output

#### General-purpose Analog Output

Three channels (AOUT1, 2, and 3) are provided as general-purpose, 10VDC analog output from the XIO brd.. These outputs are directly output from the control brd.. The device reading these signals must be isolated. To insure this, it is recommended that signal isolators be used. The output can be selected from a list shown in the parameter setting manual by using the parameters AOUT1-3\_CODE. They may also be set to any function in the drive by the use of the parameters AOUT1-3\_OP\_AS, AOUT1-3\_OP\_GS, and AOUT1-3\_OP\_OS. When using the optional settings, care must be taken to set the output up so that the output signal does not exceed 10VDC. Exceeding this value will cause overflow problems.

#### Additional Analog Outputs

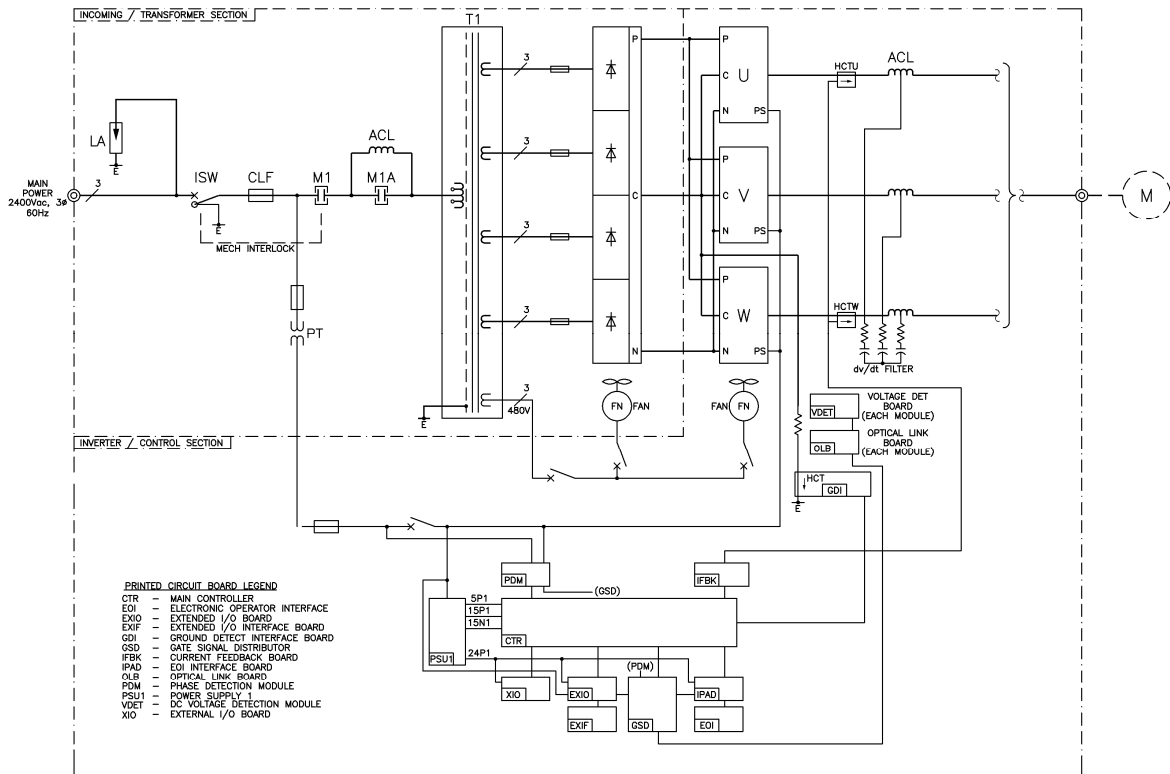
Six channels (D/A 1 to D/A 5 and Amp A) are provided as additional analog outputs. These outputs are wired out to terminal block TB-AO. Channel A provides direct current feedback from the U-phase Hall CT. The other five channels are programmable 10VDC outputs. The data to be output, the gain, and the offset, can be set from the display/keypad or a personal computer by use of parameters DA1-5\_AS (Analog Signal), DA1-5\_GS (Signal Gain), and DA1-5\_OS (Offset).

## CIRCUIT OPERATION

### Main Circuit Configuration

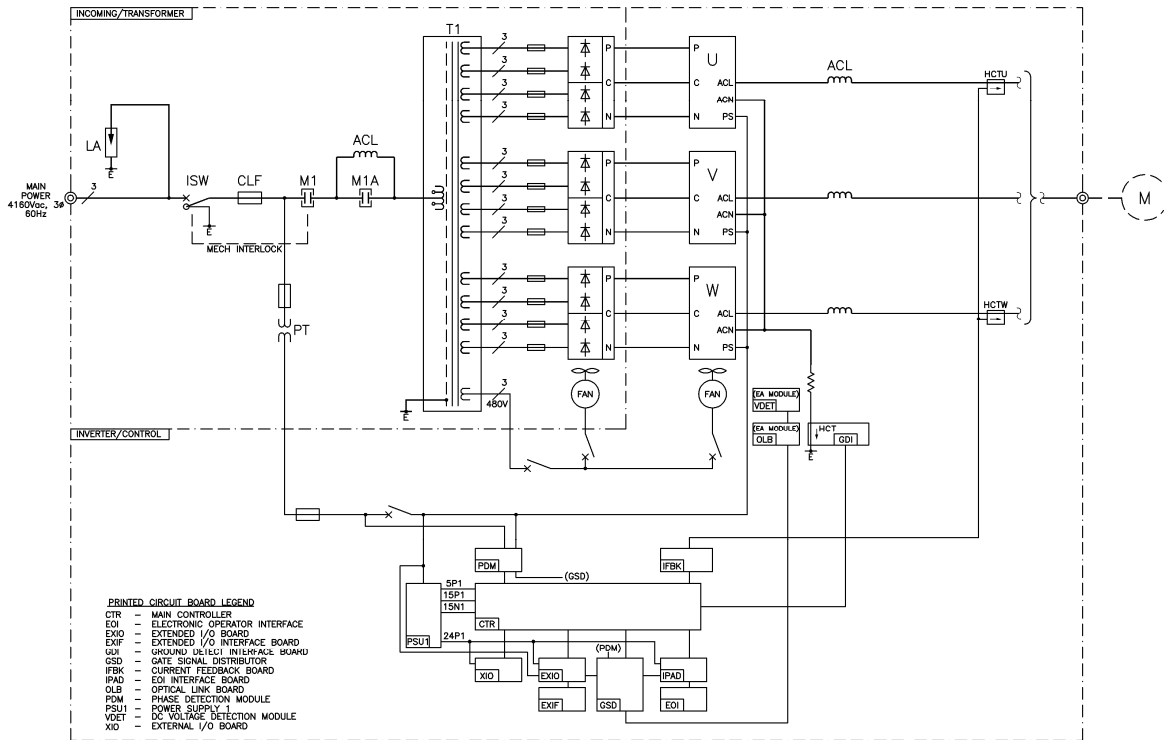
The following circuit shows some typical configurations of the drives. Input AC is supplied through an input controller to transformer T1. The transformer has multiple phase shifted secondaries connected to full wave diode rectifier bridges. The output of the rectifiers is connected to three inverter power modules that produce 3-phase AC power at the frequency and voltage required by the motor. For 6600V drives, a combination of three 2400V modules and three 4160V modules are used in series to produce 6600V.

### 2400V configuration

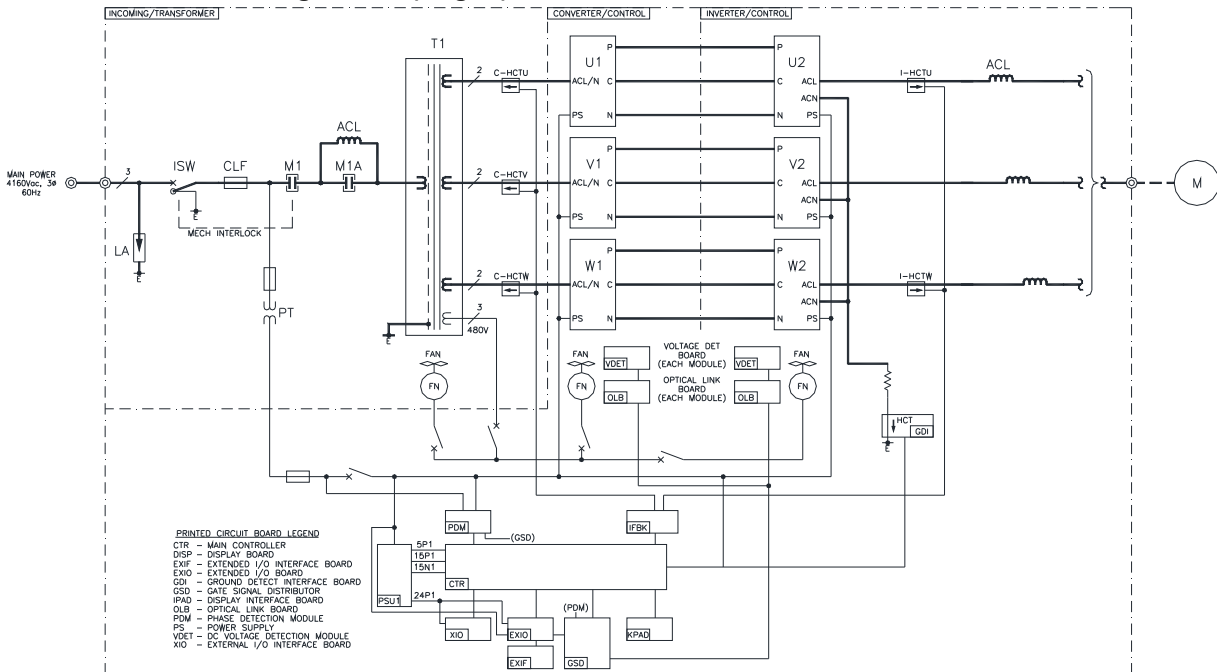


## CIRCUIT OPERATION (cont'd)

### 4160V & 6900V configuration (Non-regen)

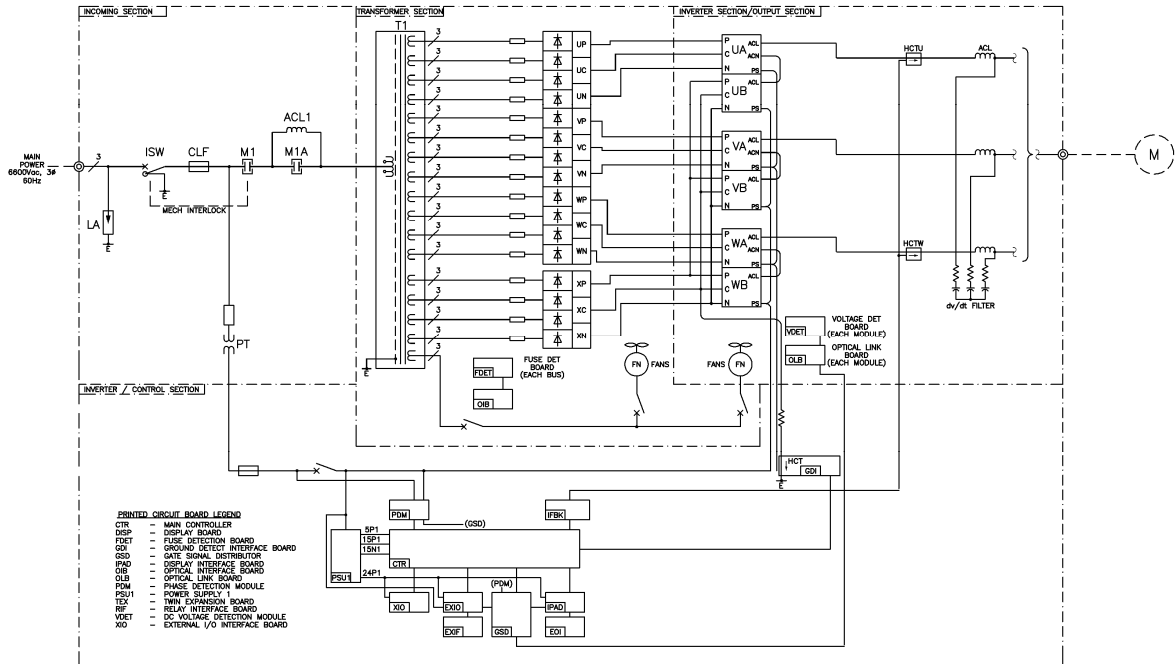


### 4160V configuration (Regen)



## CIRCUIT OPERATION (cont'd)

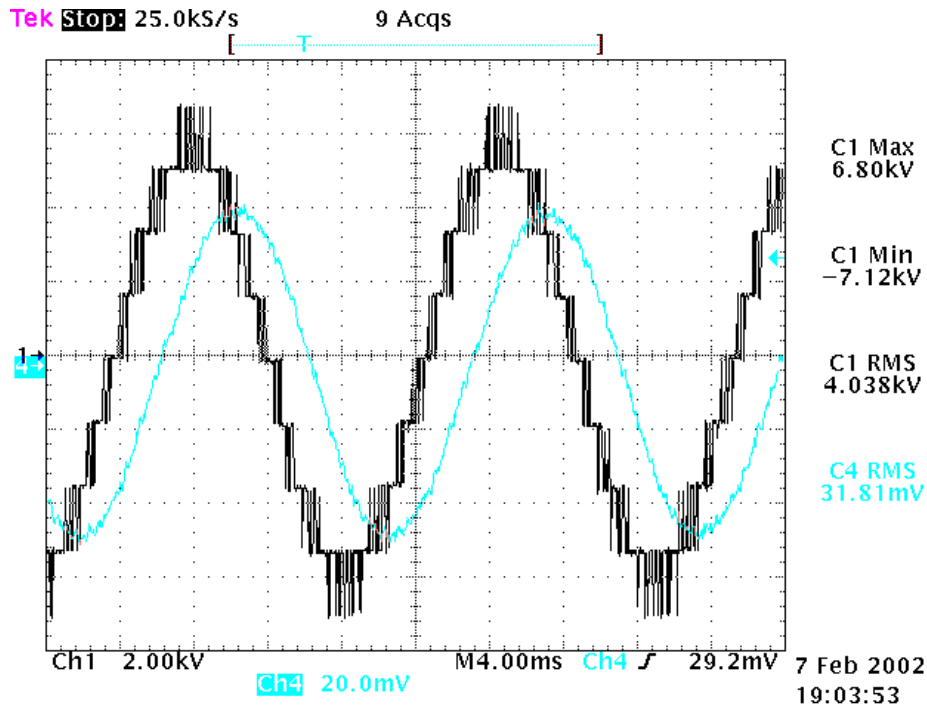
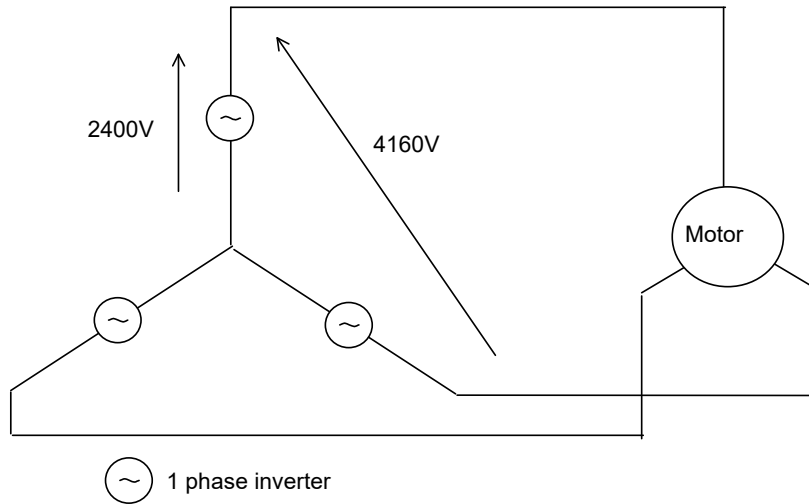
### 6600V configuration



## CIRCUIT OPERATION (cont'd)

The AC output voltage of the each inverter power module, for the 4160V drive, is 2400V line to neutral. With phase voltages shifted 120° from one other, an output voltage of 4160V between phases is generated. The output voltage closely approximates a sine wave. This is shown in the output waveform below. This produces a sine wave motor current with low distortion.

### Generation of High Voltage by Wye Connection



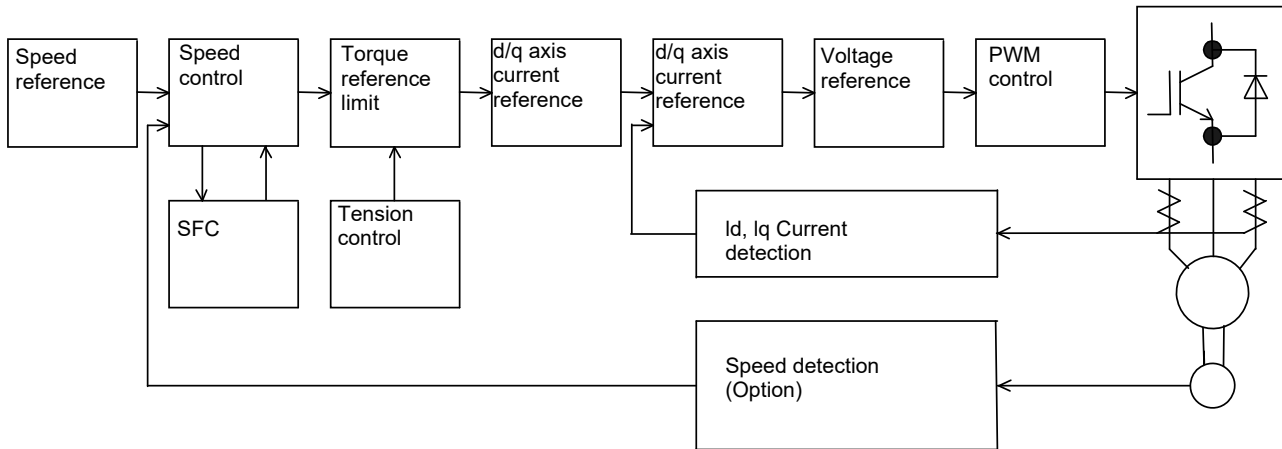
### Output Voltage and Current Waveforms

## CIRCUIT OPERATION (cont'd)

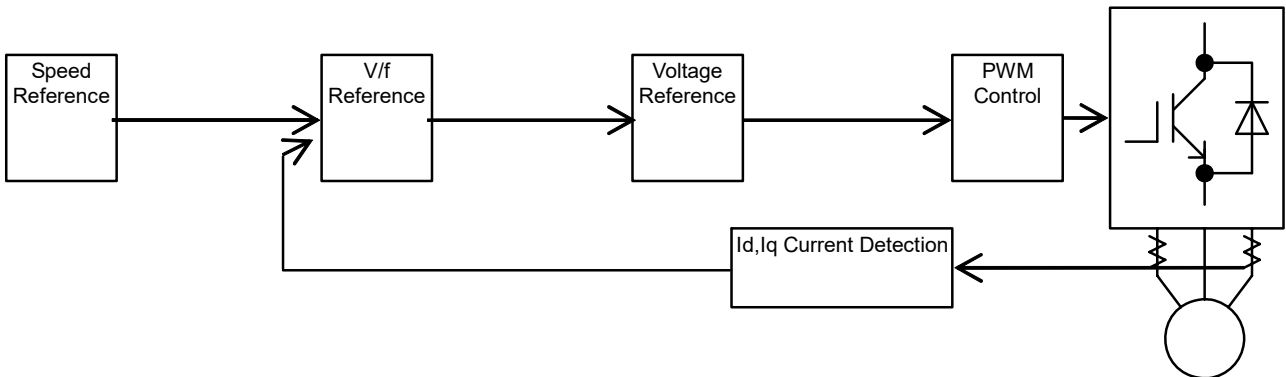
### Control

The following figures show the overall Control block diagrams for IM (Induction Motor) control.

### Vector Control Block Diagram



### V/f Control Block Diagram

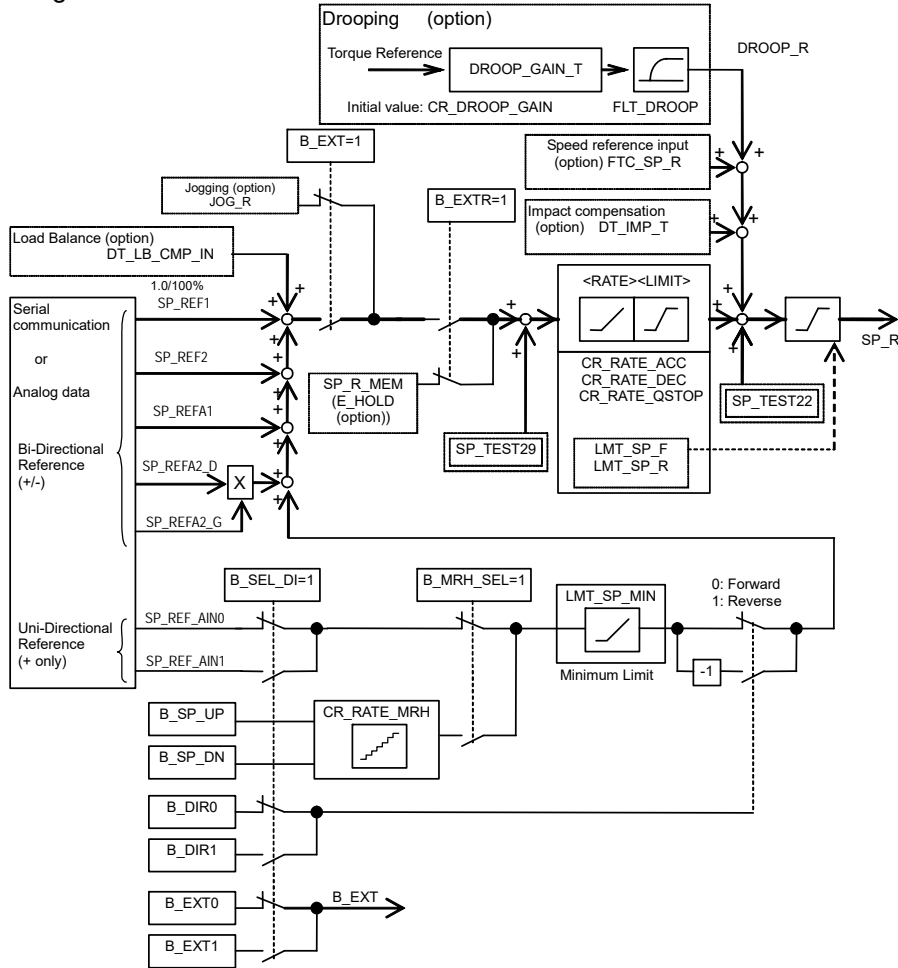




## CIRCUIT OPERATION (cont'd)

### Speed Reference

An external speed reference with count 1/100% weighting is input by serial transmission or analog input and subjected to rate processing and limit processing to output an SP\_R signal. The sign of the speed reference signal is "+" for normal rotation and "-" for reverse rotation.



**Speed Reference**

(1) Speed references

SP\_REF1 or SP\_REF2 can be used when the drive speed is to be controlled from one location only. When using local and remote control or there is a need for selection between two separate inputs SP\_REF\_AIN1 and SP\_REF\_AIN2 should be used. To select between references, one of the digital inputs should be programmed as SEL\_DI and an external selection switch to change SEL\_DI should be connected.

SP\_REF\_AIN1 is used when the SEL\_DI input is 0 (Open). SP\_REF\_AIN2 is used when SEL\_DI is 1 (Closed). The start commands (EXT) are also different for this application. When SEL\_DI is 0, EXT0 should be used and when SEL\_DI is 1, EXT1 should be used.

(2) LMT\_SP\_MIN

LMT\_SP\_MIN is used as a minimum speed. The drive will run at this speed anytime the start command is on and the speed reference is less than LMT\_SP\_MIN.

## CIRCUIT OPERATION (cont'd)

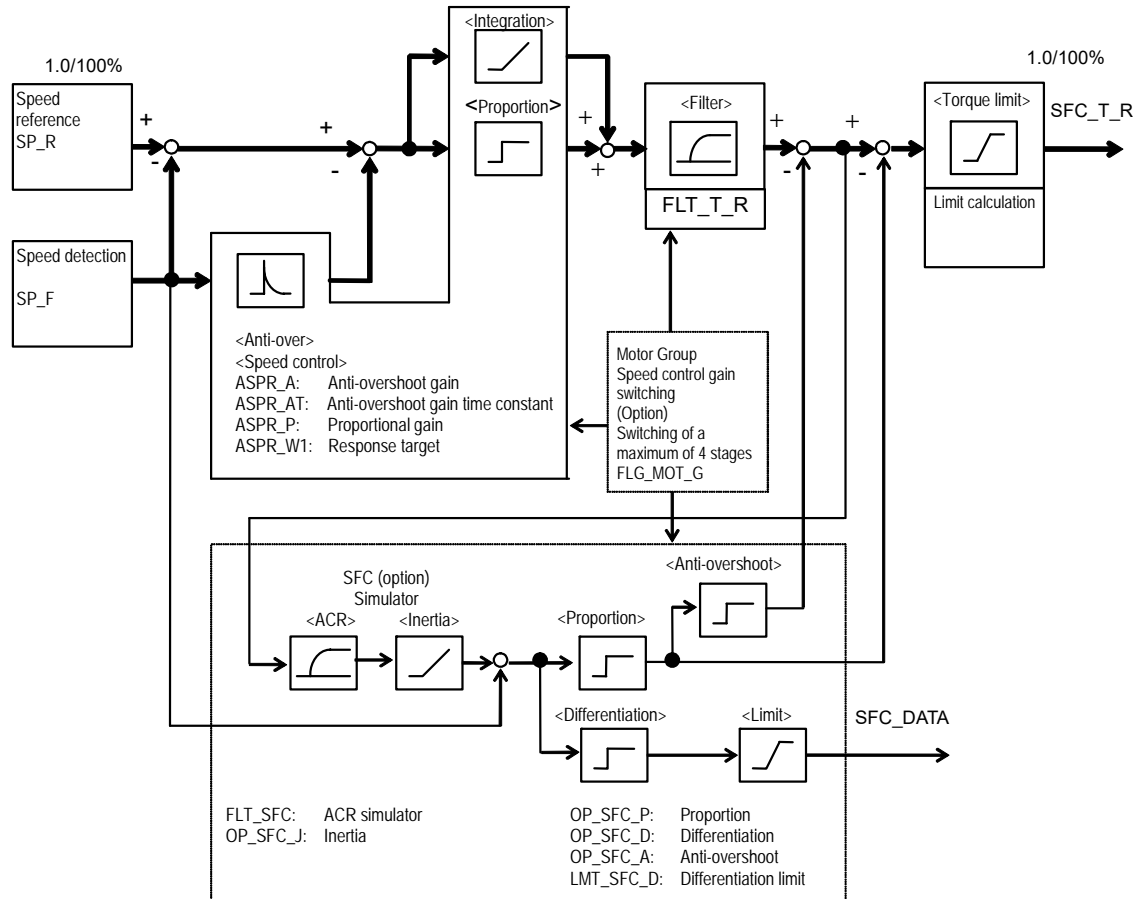
### Vector Control Speed Control

The following figure shows the speed control block diagram.

The speed reference signal SP\_R and the speed feedback signal SP\_F are input with the count/weight of 1.0/100% and the deviation between these two is subjected to proportional/integral operations and then output. After the previously output signal is subjected to speed filtering, and the torque limit is processed, its torque reference SFC\_T\_R is output with count/weight of 1.0/100%. The control response is performed with the following parameter settings:

- ASPR\_A: Anti-overshoot gain
- ASPR\_AT: Anti-overshoot time constant
- ASPR\_P: Proportional gain
- ASPR\_W1: Response target

Note, that if GD2 of the machine is extremely large, compared to the GD2 of the motor, there is a long extension shaft, or if there is torsional resonance, the control response may need to be slow.



**Speed Control**

## CIRCUIT OPERATION (cont'd)

### Vector Control Simulator Follower Control (SFC, optional control used with a speed sensor)

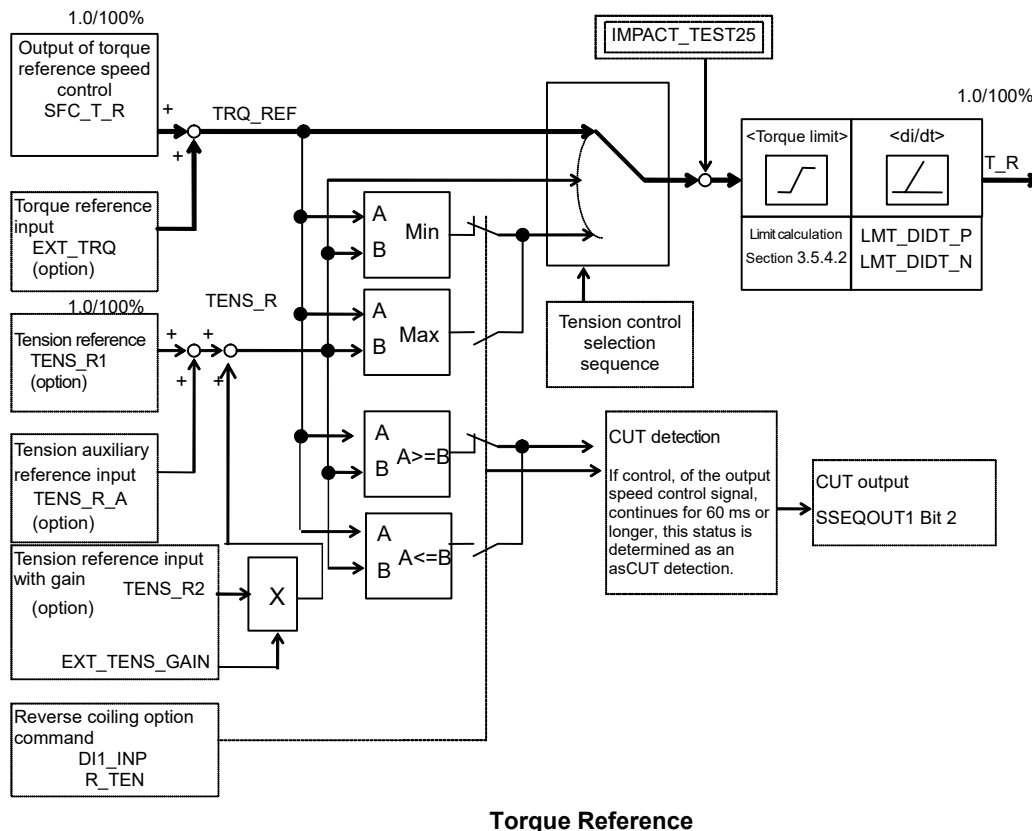
When the machine has torsional resonance, the (SFC) function may be used to try to reduce the torsional vibration and increase the speed response.

With SFC, the speed regulator output signal is input to an inertia compensation block. This block produces an estimated speed signal. The speed feedback is then subtracted from this value to create a speed deviation signal. This signal is then sent through a proportional block and added to the output of the speed regulator. The speed deviation signal is also sent through an anti-overshoot block and subtracted from the speed regulator output. The combination of these two functions can be used to help improve the recovery of the system during shock loading.

The speed deviation signal is also sent to a differential block and added to the torque reference (see below). This signal is effective for torsional vibration control. When the SFC function is not used, set all of the gains to 0.

### Vector Control Torque Reference and Current Reference

The TRQ\_REF signal, obtained from the calculation, results in the speed control compared with the external input tension reference TENS\_R signal, to find the torque reference T\_R. In this optional control, the operation is made based on TENS\_R, used as a torque reference, during normal operation, and the speed control circuit functioning as a speed limit. (Operation is made based on the external torque reference in winding machines. However, if materials are broken, operation is changed to the speed control operation.)

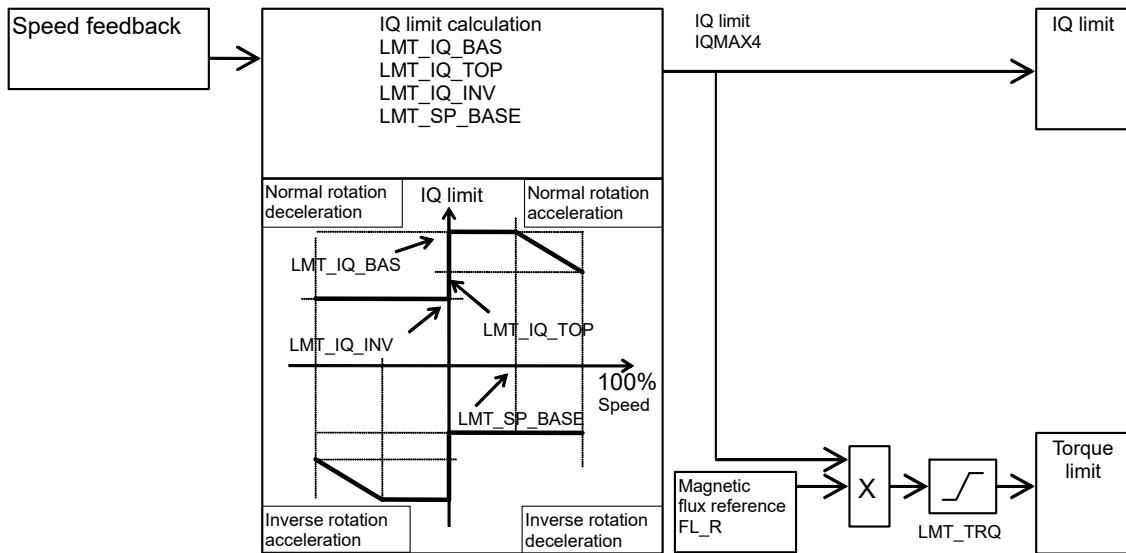


## CIRCUIT OPERATION (cont'd)

### Vector Control IQ Limit (Torque current limit)

The IQ limit has a flat characteristic from 0 to base speed and tapers from base to top speed. The following settings are used to adjust the limits.

- LMT\_IQ\_BAS: Base speed torque current limit. Set 110%, 115%, etc. according to OL specification of the drive.
- LMT\_IQ\_TOP: Top speed torque current limit. Set as required by the application or set the same as the base limit when field weakening is not used.
- LMT\_IQ\_INV: Regeneration torque current limit. Set to 1 or 2%. This Drive cannot regenerate.
- LMT\_SP\_BASE: The upper speed of the drive at which LMT\_IQ\_BASE is used. Set 125% for applications that do not use field weakening. Otherwise set as required by the application.
- LMT\_TRQ: Torque reference motoring absolute limit. The maximum motoring torque reference allowed regardless of speed. Set to the base speed torque current limit.
- LMT\_TRQ\_INV: Torque reference regeneration absolute limit. The maximum regeneration torque reference allowed regardless of speed. Set to 2%.



**IQ Limit**

## CIRCUIT OPERATION (cont'd) Vector Control D-Q Axis Current Control

The figure on the following page shows the block diagram of the D-Q axis current control.

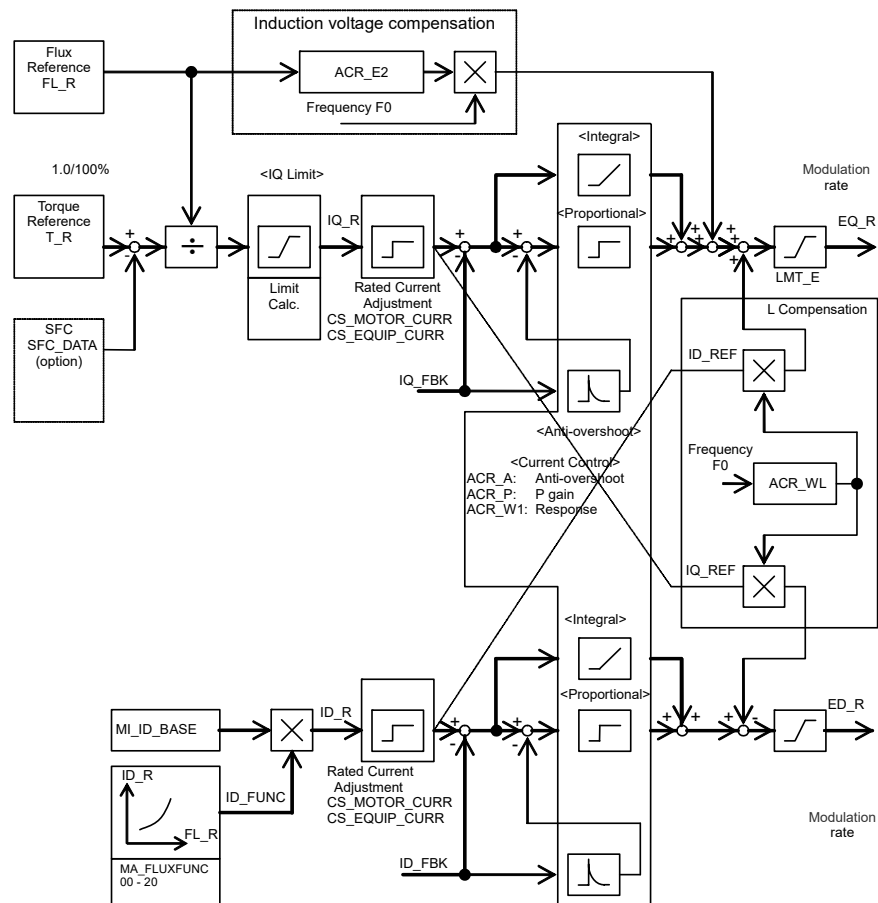
This system controls the current of an induction motor by separating it into a magnetic flux (Field) component and a torque component. This drive controls the current on the D-Q coordinates. It can control the current to an AC motor as a DC value, achieving high performance control irrespective of output frequencies.

### (1) ID (Field current) control

A magnetic flux reference is generated based upon the speed reference. This and the field current setting (MI\_ID\_BASE) are used to generate an ID reference. This ID reference and the ID feedback signal are input into a PI controller. The output of this controller is the ED\_R (Field voltage reference). Optional Inductance (L) compensation can also be used (ACR\_WL). If used, these signals are combined with the PI controller output to create the ED\_R.

### (2) IQ (Torque current) control

The torque reference, which is the result of the previously mentioned speed control, is input and divided by magnetic flux to obtain an IQ reference. This IQ reference and IQ feedback signal are input into a PI controller. The output of this controller is the EQ\_R (Torque voltage reference). An induction voltage compensation (ACR\_E2) and L compensation (ACR\_WL) may also be used. If used, these values are combined with the output of the PI controller to create the EQ\_R.



**D-Q Axis Current Control**

## CIRCUIT OPERATION (cont'd)

### V/f Control

#### (1) Frequency reference (F\_P)

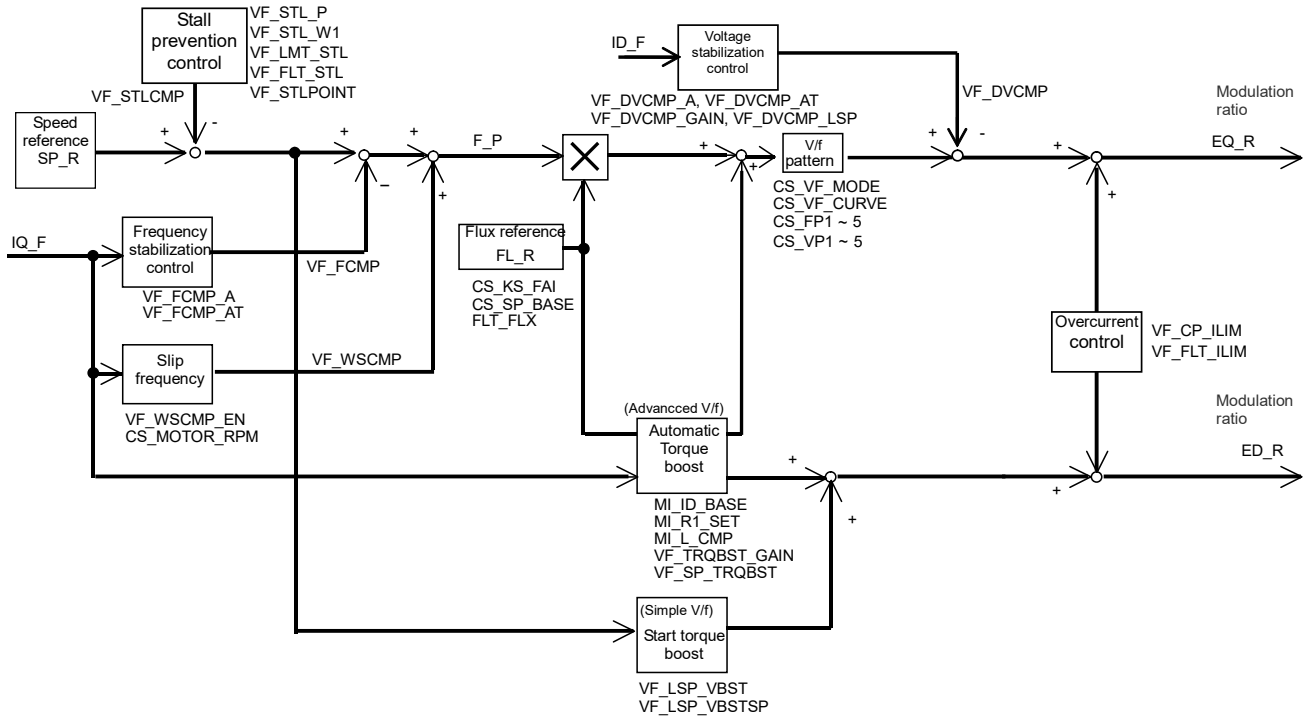
The frequency reference is determined by the speed reference signal (SP\_R) and the slip frequency, when slip compensation is used. The frequency is compensated by the change of the Q axis current for the control stability.

#### (2) Q axis voltage reference (EQ\_R)

The Q axis voltage reference is proportional to the frequency reference and flux reference. This voltage may be compensated by the Q axis current for auto torque boost, when advanced V/f control is used. The V/f rate can be changed by the selected V/f pattern. The Q axis voltage is compensated by the change of the D axis current for the control stability.

#### (3) D axis voltage reference (ED\_R)

The D axis voltage reference is used for low speed torque boost normally. This voltage can also be compensated based upon Q axis current, when advance V/f control is used.

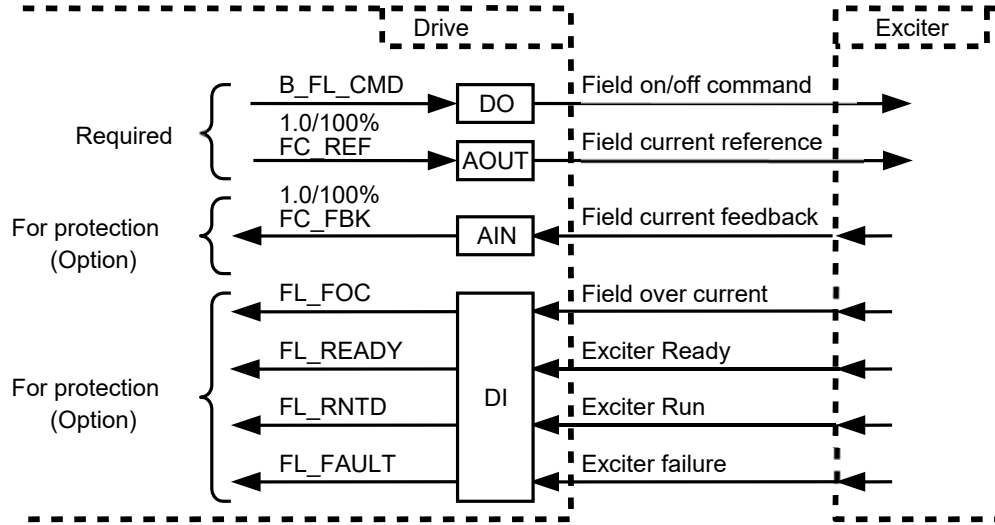


## CIRCUIT OPERATION (cont'd)

### Control Circuit for SM (Synchronous Motor) control

#### (1)Interface

SM control requires the use of an exciter. The exciter may be internal or external to the drive. The interface to the exciter is shown below.



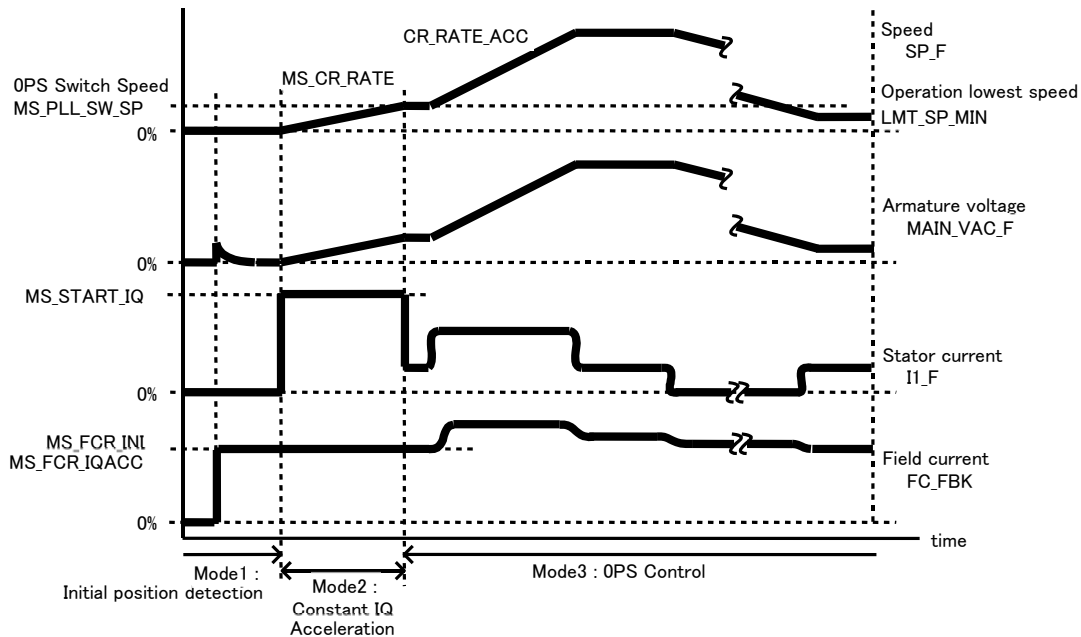
#### (2) Timing chart

There are 3 control modes.

Mode1 "Initial position detection" : Initial position is detected when the motor is stopped.

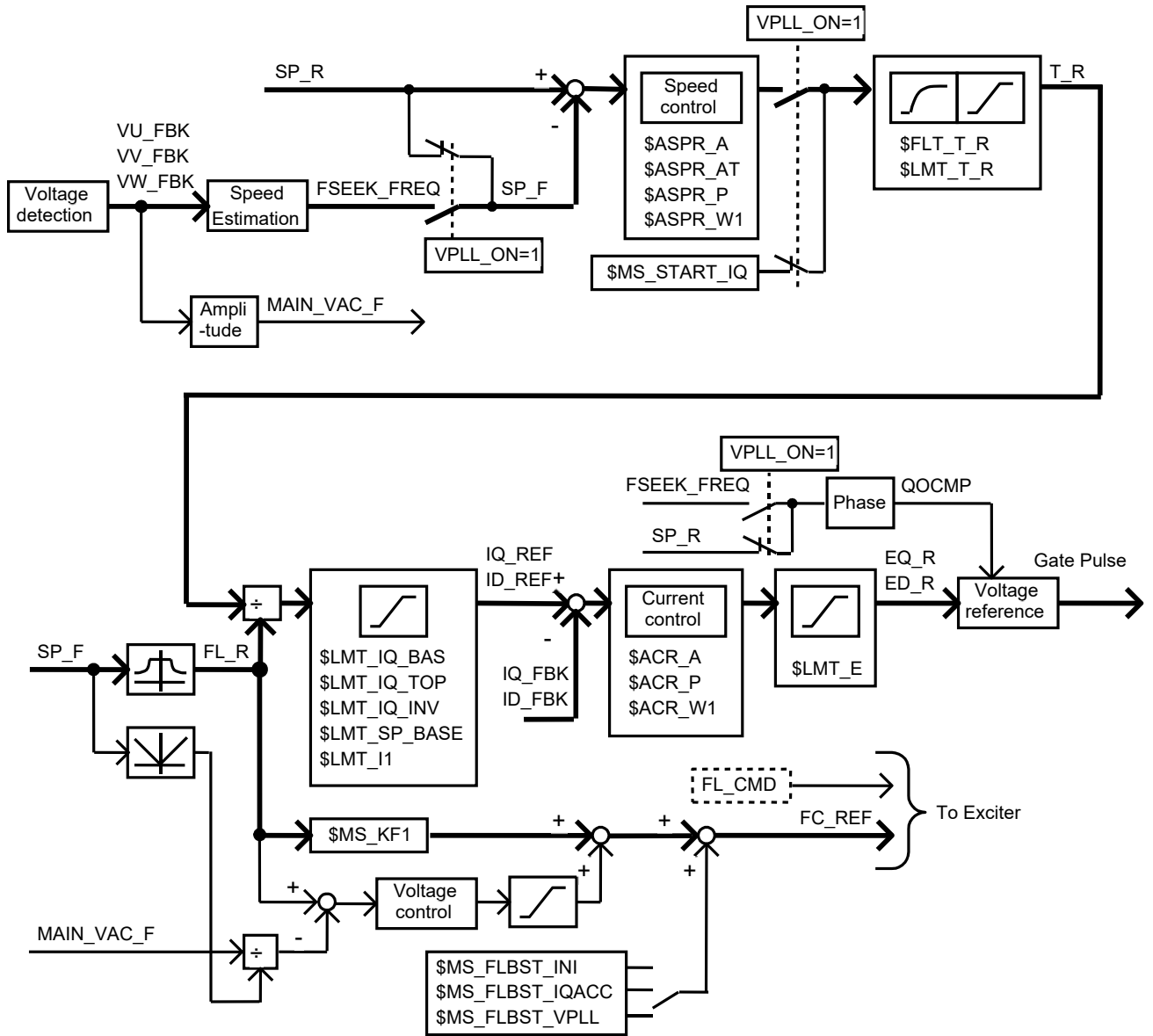
Mode2 "Constant IQ starting": This mode starts the motor without speed control. It uses the initial position and current control with pre-set speed reference rate and current.

Mode3 "ZPS control" (zero-PS): Speed and phase angle are estimated by the motor voltage PLL. Once the drive enters this mode it is in speed control and will follow the external speed reference.



## CIRCUIT OPERATION (cont'd)

### SM Control Block Diagram





## CIRCUIT OPERATION (cont'd)

### Speed Feedback (Option)

As an option, a Resolver or a Pulse Generator (PG) can be selected for speed feedback. Speed control with a Tach Generator is not available because Tach Generator performance is poor.

### Resolver

A resolver is an analog feedback device that used for speed feedback. Two sine wave excitation signals (sine and cosine) are sent to the resolver and two signals (sine and cosine) are returned to the drive. The use of these two phase shifted signals allows the direction rotation to be determined. The position of the motor rotor is determined by the phase difference between the excitation and return signals. The speed is found from the change in this position over time.

### PG

A signal is detected from a single ended PG attached to the motor and converted to a speed. Detection is performed according to the pulse interval measurement system. This system converts a signal to a speed based on the fact that the interval (time) between pulses input is inversely proportional to the speed. The maximum input frequency is 10kHz(Single-Ended type) or 100kHz(differential type).

| Pulse signal |                                 | Count 1.0/100%       |
|--------------|---------------------------------|----------------------|
| PGA-F        | Speed detection                 | Speed detection SP_F |
|              | Pulse count measurement         |                      |
|              | Rotation direction detection    | $\theta_0$ detection |
| PGB-F        | CS_RES_TYPE = 1                 |                      |
|              | CS_RES_PGFLT (factory setting)  |                      |
|              | CS_PGOUT = 0                    |                      |
|              | CS_PGCNT = 256 (PG pulse count) |                      |

### PG Speed Detection

## OPERATION

The powering-on operation must follow a certain sequence. Failing to observe the powering-on sequence described here may cause unnecessary stress on the equipment. **Be sure to observe the powering-on sequence.**



**WARNING**

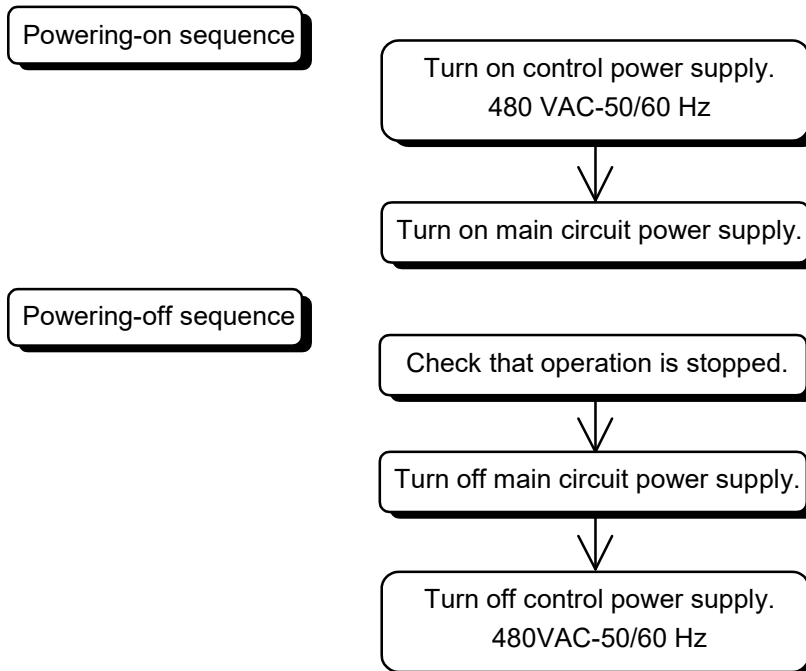


**While the equipment is in operation and the motor is running, do not turn off the main circuit power supply or control power supply under any circumstances. Do not open the cubicle doors or remove any covers.**

When the operation of the equipment is completely stopped, use the following basic procedure to turn on/off the power.

NOTE: On some drives, the control power supply is internally derived from the main circuit power supply. In this case, disregard the steps below involving the 480 VAC control power supply.

### *General power-on and power-off sequence.*



---

## OPERATION (cont'd)

### Pre-Operation Check Points

Check the following points before starting the operation.

- 1) Wiring is correct.
- 2) A voltage of 2400 V, or 4160 V,  $\pm 10\%$  can be supplied as the input power supply voltage.
- 3) A voltage of 480 VAC  $\pm 10\%$  can be supplied as the control power supply voltage.
- 4) The ground bus and any shielded wires are grounded.
- 5) The motor frame is also grounded.
- 6) The motor main circuit wire is not grounded.

### Powering-On

The power should be turned on when the motor is completely stopped.

- 1) Turn on the control power supply MCCB "CONTROL."
- 2) Interlock the drive with the interlock switch on the keypad.
- 3) Turn on the main power supply.
- 4) Release the interlock switch on the keypad.

### Operation

This section shows a typical operation procedure. You are also required to observe your own safety rules to prevent accidents.

### Normal Operation

When carrying out a normal operation using the digital interface (refer to the keypad manual for keypad operation), check that the necessary interface signals are correctly connected and then follow the procedure below.

- 1) Set the frequency command signal.
- 2) Turn on the IL (interlock) input signal if used.
- 3) Turn on the UVS input.
- 4) Turn on the EXT (start command) input signal.
- 5) Vary the frequency command as needed. Do not run the drive at zero speed unless you have a speed sensor.
- 6) Turning off the EXT signal during operation ramps the motor to a stop.
- 7) Removing the UVS signal or the IL signal during operation turns off the output of the drive and the motor coasts to a stop. If these signals are removed during operation, the EXT command must be removed and the UVS and/IL restored before the drive will restart.

### Powering-Off

- 1) Stop the motor by removing the EXT, the IL, or the UVS command.
- 2) After the motor has stopped, interlock the drive with the interlock button on the keypad.
- 3) Turn off the external main power supply.
- 4) Turn off the control power supply MCCB "CONTROL."

## DATA CONTROL

### Setting Data

The parameter setfile is stored in the EEPROM on the main control brd.. This is non-volatile memory and will not generally be lost when the drive is powered down. However, this data could be lost if there is a brd. failure. If this data is lost, the drive will need to be re-commissioned. For this reason, it is recommended that the parameter setfile data be backed up in a file stored on a personal computer. This requires the use of the optional commissioning software. The software and training is available through Toshiba.

## FAULT AND RECOVERY



### Cautions when Handling Fault

## CAUTION

When a fault occurs, before resetting, understand the fault code. It may be unsafe to restart if a component or motor has failed. Every effort should be made to determine the cause of the fault and to correct any problems before attempting to restart the drive.

To do this, it is necessary to record and evaluate the phenomena and conditions of the fault in detail from both electrical and mechanical standpoints. Collect as much data as possible on the following items to determine the operation situation when the fault occurred.

- 1) Record the fault message (fault display) shown on the display/keypad at the moment the fault occurred.
- 2) Collect Tracesave data with a PC. Visit our website at <http://www.toshiba.com/tic/contact-us/find-support> for information about Tracesave and where to send the file for analysis.
- 3) Operation different from ordinary operation  
Check if there was anything that affected the input power supply of the equipment at the moment the fault occurred (for example, powering-on of large-capacity equipment which is connected to the common AC power supply or short-circuits, etc.).
- 4) Power failure  
Check if the input power supply of the equipment was disconnected at the time of the fault (for example, if the line of the AC power supply was switched or if the breaker was turned on or off).
- 5) Load condition  
Check if the load was drastically changed at the time of the fault.
- 6) Operation  
Check to see if any changes in the process or load machinery were made by the operator at the time of the fault.
- 7) Installation environment  
Check if there was any abnormal ambient conditions present in the electrical room at the time of the fault or before the fault. (Fault of air-conditioner or ventilation system, water leakage into the room, intrusion of dirt or chemicals, etc...)
- 8) Changes  
Check if there were any recent changes to other equipment around the drive or load machinery. For example, if some electrical work was carried out on or around the equipment.
- 9) Lightning  
Check if there were any lightning strikes in the area.
- 10) Abnormal sound, odor  
Check if there was any odor or abnormal sound around the equipment at the time of the fault or after.

Understanding the conditions before and during the fault can help to determine whether the fault is attributable to factors inside or outside of the drive. Further, this information becomes an important clue to determine the cause of intermittent faults. It is important to keep a precise record.

## Repair



## CAUTION

### Cautions on Repair

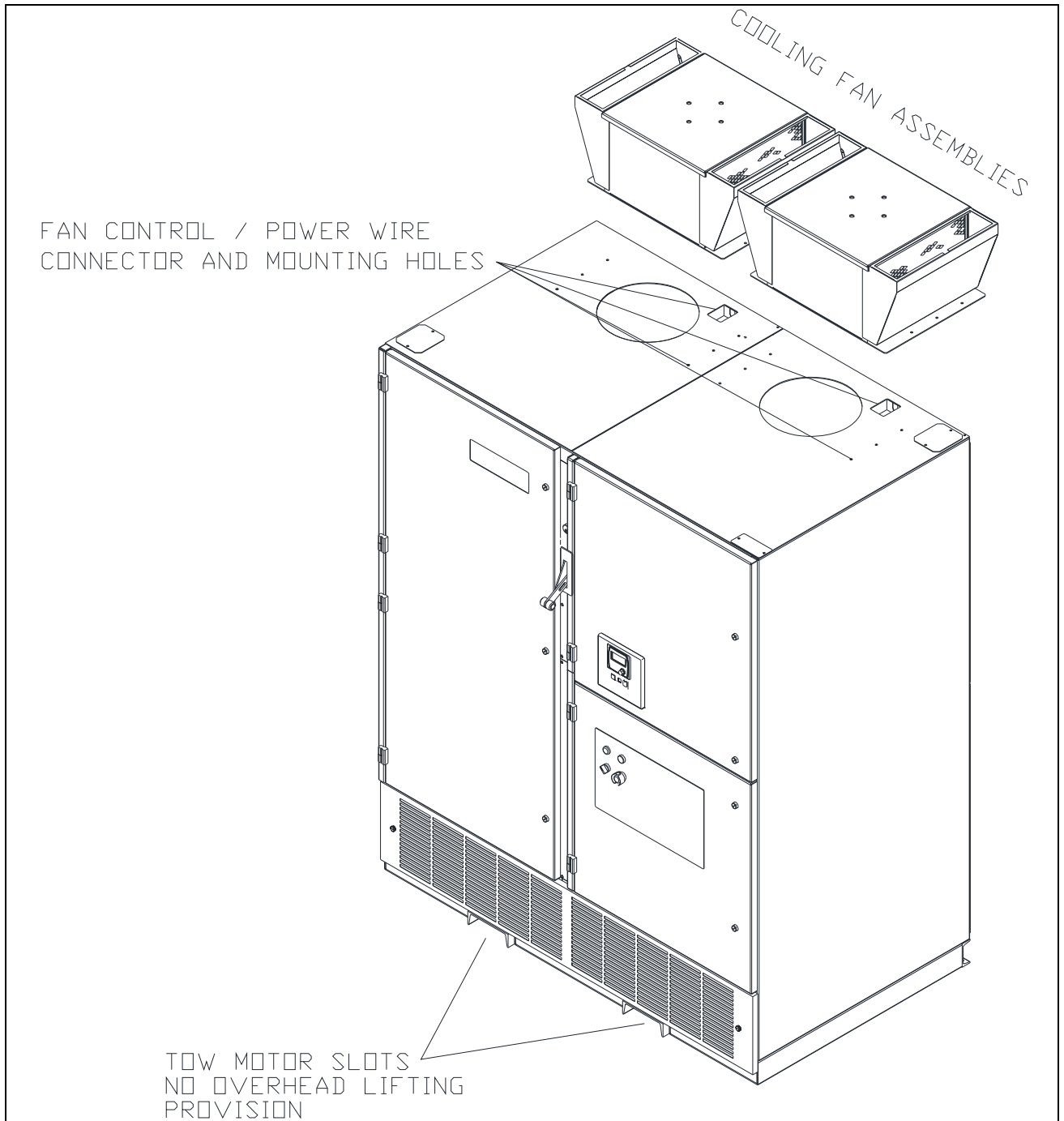
- **Be sure to use only the renewal parts specified by Toshiba. Parts other than those specified by Toshiba may not only not demonstrate the stipulated performance but also affect the safety. If spare parts are not available, contact Toshiba to order them or ask for replacement of parts.**

- **This equipment includes parts that need to be replaced periodically. It takes time to deliver parts, so order them as early as possible.**

- 1) The power modules have been designed for easy replacement as a unit. They are sold as units and should be replaced as units. Individual parts should not be removed from or installed on the power module assemblies. Modules that have failed or are believed to have failed should be returned to the factory for evaluation, repair, and testing. Refer to the information label on the inside of the power module compartment door for instructions on replacing a power module.
- 2) Prepare necessary tools and drawings, etc. before starting the work.
- 3) Be careful not to damage other parts when removing some parts.
- 4) Do not make wrong connections when changing parts. Put markings, etc., if necessary.
- 5) Before restarting after changing any part verify all connections are correct.
- 6) Use the right tools (torque wrench, etc.) when handling screws and bolts.
- 7) Special care is required when handling heavy articles.
- 8) When the work is completed, make sure that no tools or other foreign material is left in the drive.

## DRIVE INSTALLATION DRAWINGS

### Frame 0 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 0 4160V module lifting and installation

**WARNINGS**  
Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GC16720G055 and a lifting device rated 250 lbs minimum for removal and installation of modules.

**Power Module Removal**

1. Disconnect and remove AC neutral bus.
2. Disconnect power cables ACL, P, C & N.
3. Remove control wiring cover (two "A" bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".
6. Pull slide tray out until slides lock.
7. Remove four "C" bolts which secure module to tray.

**Power Module Removal (cont'd)**

8. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reconnect power cables ACL, P, C & N.
9. Reinstall AC neutral bus.
10. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.

PC94060P086

### Frame 0 2400V module lifting and installation

**WARNINGS**  
Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GC16720G055 and a lifting device rated 250 lbs minimum for removal and installation of modules.

**Power Module Removal**

1. Disconnect power cables ACL, P, C & N (P, C & N on right-hand module only).
2. Disconnect and remove bus bars P, C & N.
3. Remove control wiring cover (two "A" bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".
6. Pull slide tray out until slides lock.

**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reinstall bus bars P, C & N.
9. Reconnect power cables ACL, P, C & N (P, C & N on right-hand module only).
10. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.

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## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 1 4160V drive lifting and assembly



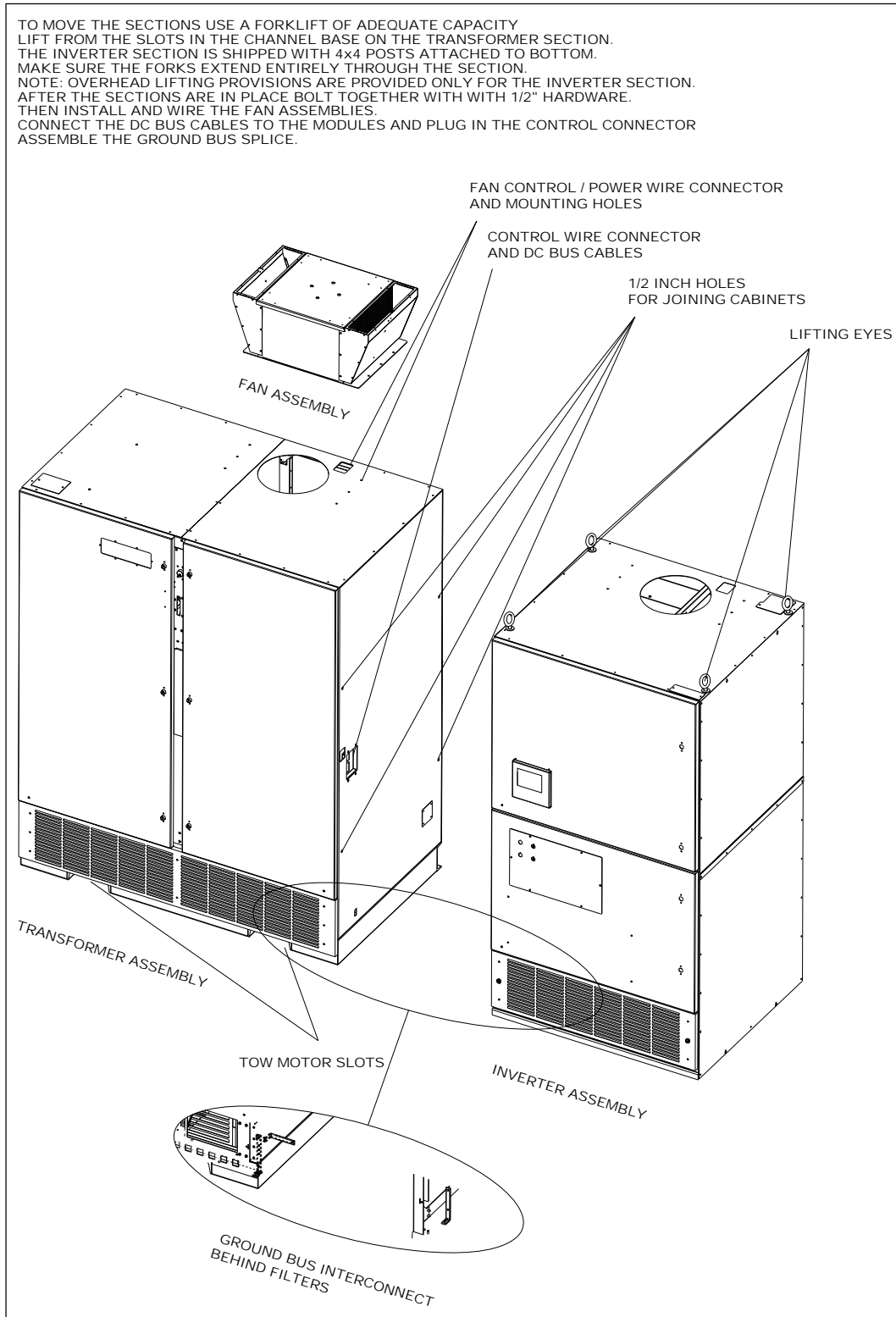
When the service drawer is withdrawn, the power modules have sufficient weight to tip over the Frame 1 inverter cabinet if it is not firmly anchored to the mounting floor, resulting in severe injury or death.

**DO NOT** attempt to install or withdraw the Frame 1 power modules before first securely anchoring the cabinet to the floor.



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 1 drive lifting and assembly (cont'd)



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 1 2400V module lifting and installation

**WARNINGS**  
Inverter cabinet is top heavy. Cabinet must be anchored to floor before withdrawing power modules to prevent tipping.

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GC16721G055 and a lifting device rated 350 lbs minimum for removal and installation of modules.

**Power Module Removal**

1. Disconnect power cables ACL, P, C & N (P, C & N on right-hand module only).
2. Disconnect and remove bus bars P, C & N.
3. Remove control wiring cover (two "A" bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".

**Power Module Removal (cont'd)**

6. Pull slide tray out until slides lock.
7. Remove four "C" bolts which secure module to tray.
8. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reinstall bus bars P, C & N.
9. Reconnect power cables ACL, P, C & N (P, C & N on right-hand module only).
10. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.

PC94060P099

### Frame 1 4160V module lifting and installation

**WARNINGS**  
Inverter cabinet is top heavy. Cabinet must be anchored to floor before withdrawing power modules to prevent tipping.

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GC16721G055 and a lifting device rated 350 lbs minimum for removal and installation of modules.

**Power Module Removal**

1. Disconnect and remove AC neutral bus.
2. Disconnect power cables ACL, P, C & N.
3. Remove control wiring cover (two "A" bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".

**Power Module Removal (cont'd)**

6. Pull slide tray out until slides lock.
7. Remove four "C" bolts which secure module to tray.
8. Using module lifting attachment and lifter, lift module from tray.

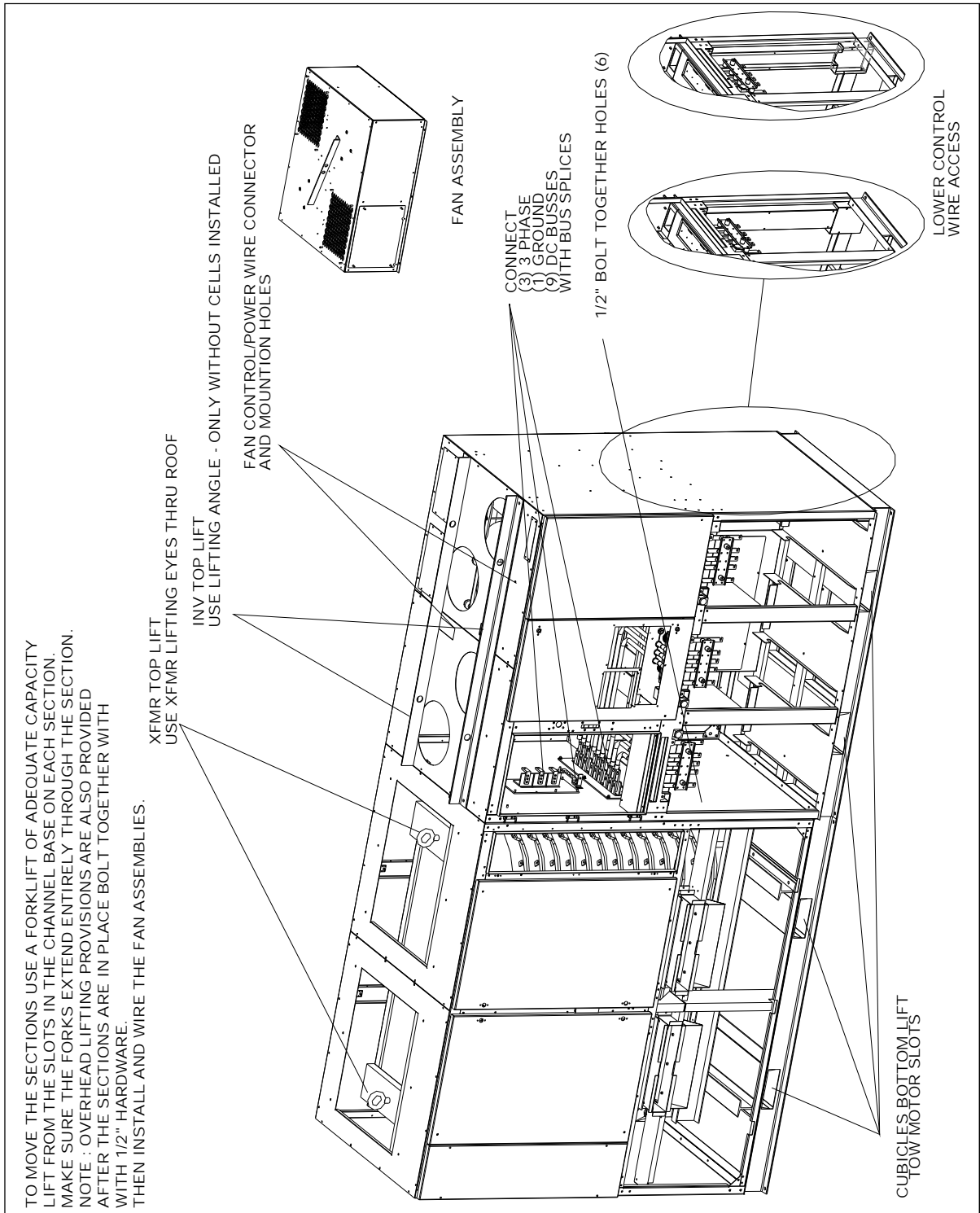
**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reconnect power cables ACL, P, C & N.
9. Reinstall AC neutral bus.
10. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.

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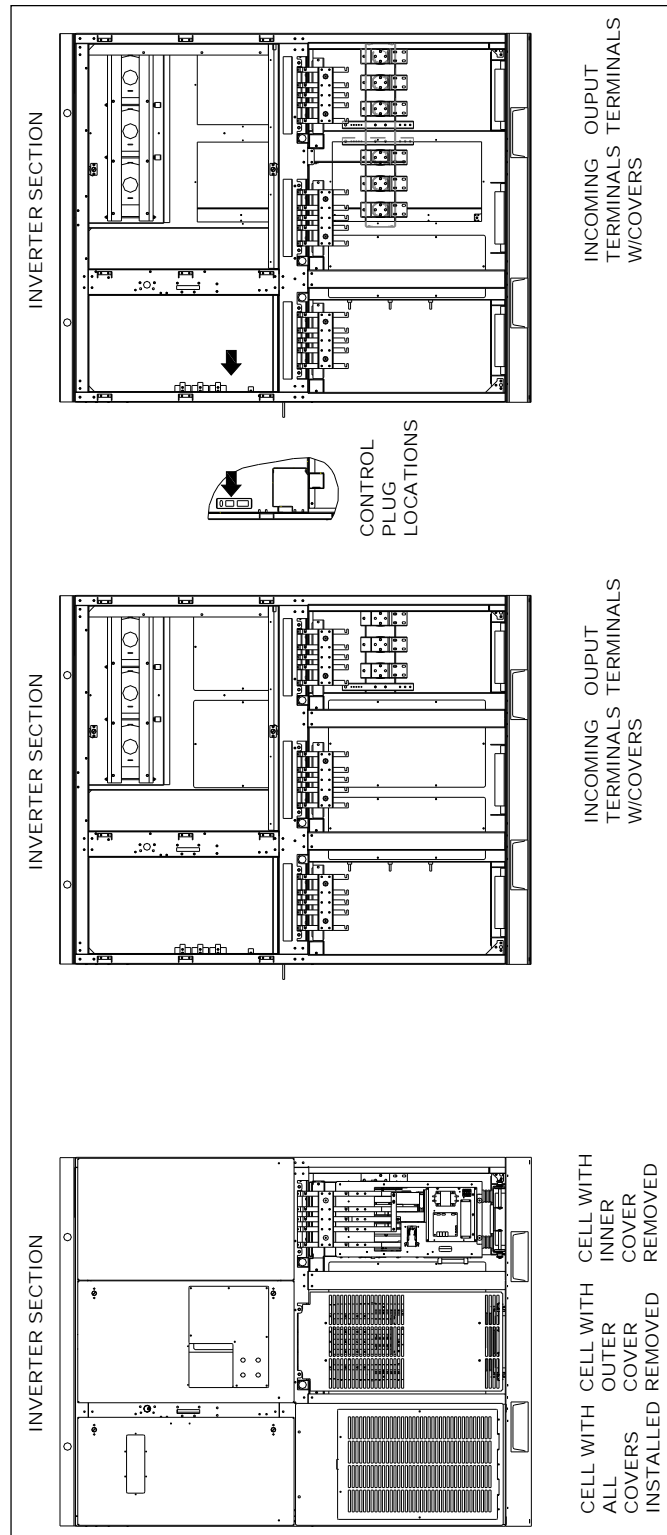
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 2 & C4 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 2 & C4 drive main cable installation



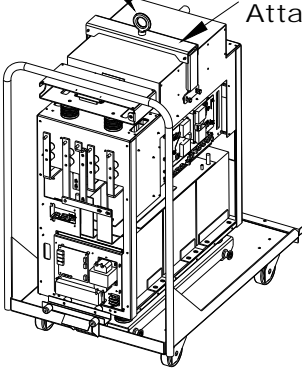
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 2 & C4 module lifting

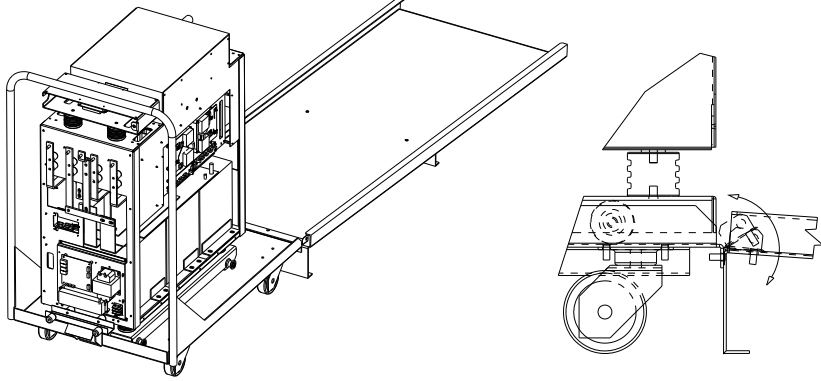
**LIFTING PROVISIONS**  
2 LIFTING PROVISIONS ARE AVAILABLE

Lift Here

Lifting Attachment



1. Load or remove power module from truck GC16723G055 using lifting attachment GC16722G055 and a lifting device rated for 750 lbs or more.  
  
Secure lifting attachment to power module using (4) 3/8-16 bolts provided.



2. Load or remove power module from truck GC16723G055 using ramp assembly GC16723G053.  
  
Lock truck to ramp by inserting truck pins into ramp holes.  
  
Set brakes on truck before carefully rolling power module up or down ramp.

PC94060P098

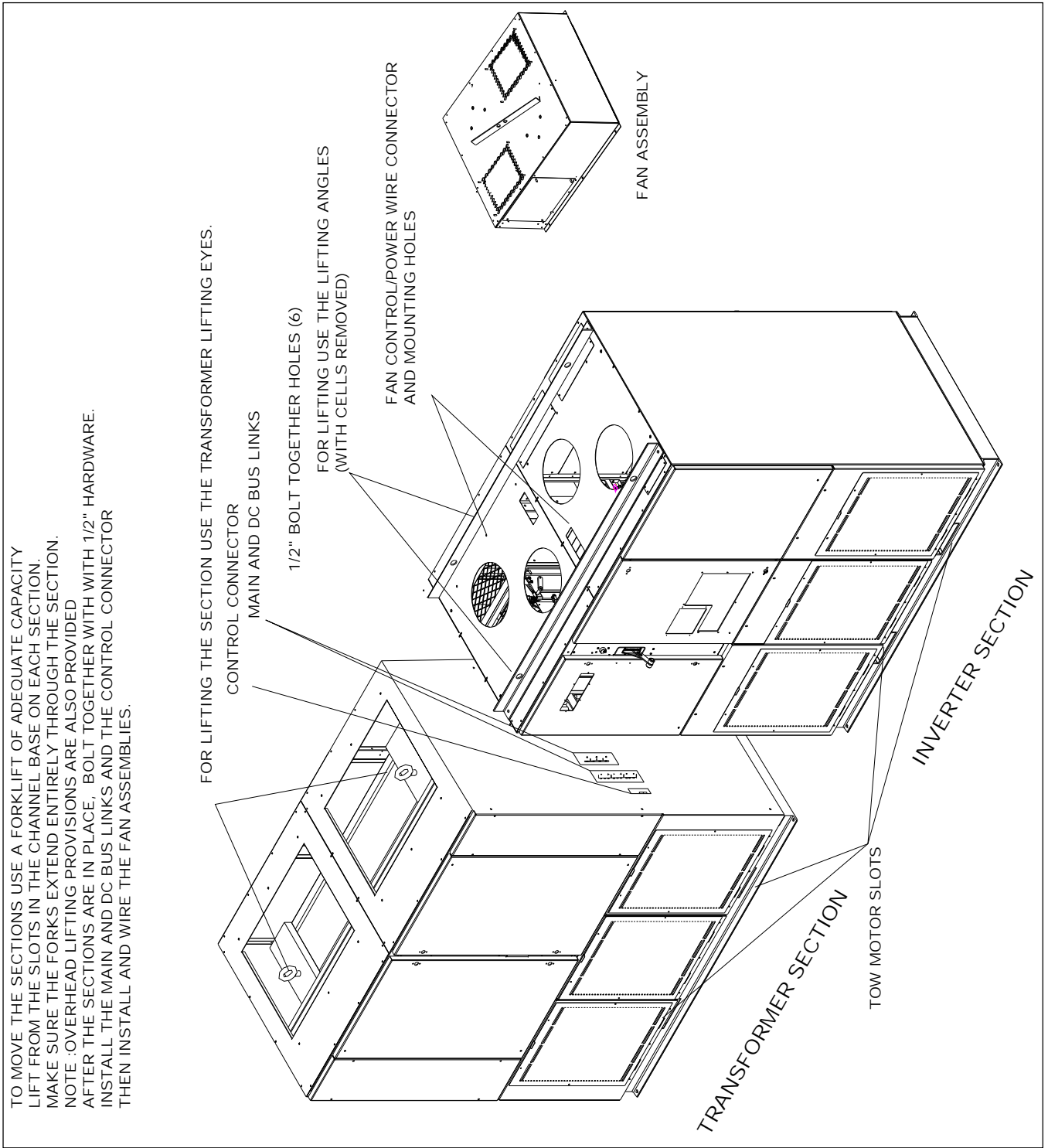
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 2 & C4 4160V module installation

|  |   |   |   |
|--|---|---|---|
| <p>Control Wiring Cover</p> <p>Control Signal Cable &amp; 120VAC Supply Cable</p> <p>Bus Link Assembly</p> <p>Front Barrier</p> <p><b>POWER MODULE DISCONNECTION</b></p>   | <p>Engage Latch</p> <p>Set Wheel Brakes</p> <p>Power Module Truck GCI6723G055</p> <p>Secure Truck to Cubicle</p> <p><b>POWER MODULE REMOVAL</b></p>   |   |   |
| <p><b>WARNINGS</b><br/>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> <p>Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.</p> | <p><b>Power Module Disconnection</b></p> <ol style="list-style-type: none"> <li>1. Remove front barrier (four bolts).</li> <li>2. Loosen ten nuts and remove bus link assembly by sliding sideways and off.</li> <li>3. Remove control wiring cover (two bolts)</li> <li>4. Disconnect control signal cable and 120VAC supply cable from module.</li> </ol> | <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>1. Align truck GCI6723G055 with front of cubicle.</li> <li>2. Secure truck to cubicle by inserting two studs into holes in base.</li> <li>3. Set wheel brakes on truck.</li> <li>4. Roll power module onto truck until front latch engages.</li> <li>5. Refer to additional instruction label for moving power module on and off of truck.</li> </ol> | <p><b>Power Module Reinstallation</b></p> <ol style="list-style-type: none"> <li>1. Reverse the procedure followed during disconnection and removal of power module.</li> <li>2. Ensure that control signal cable and 120VAC supply cable are properly reconnected.</li> <li>3. Reinstall all hardware previously removed.</li> <li>4. Torque bus link connections (5/16-18 hdwr) to 10-15 ft-lbs.</li> </ol> <p style="text-align: right;">PC94060P097</p> |

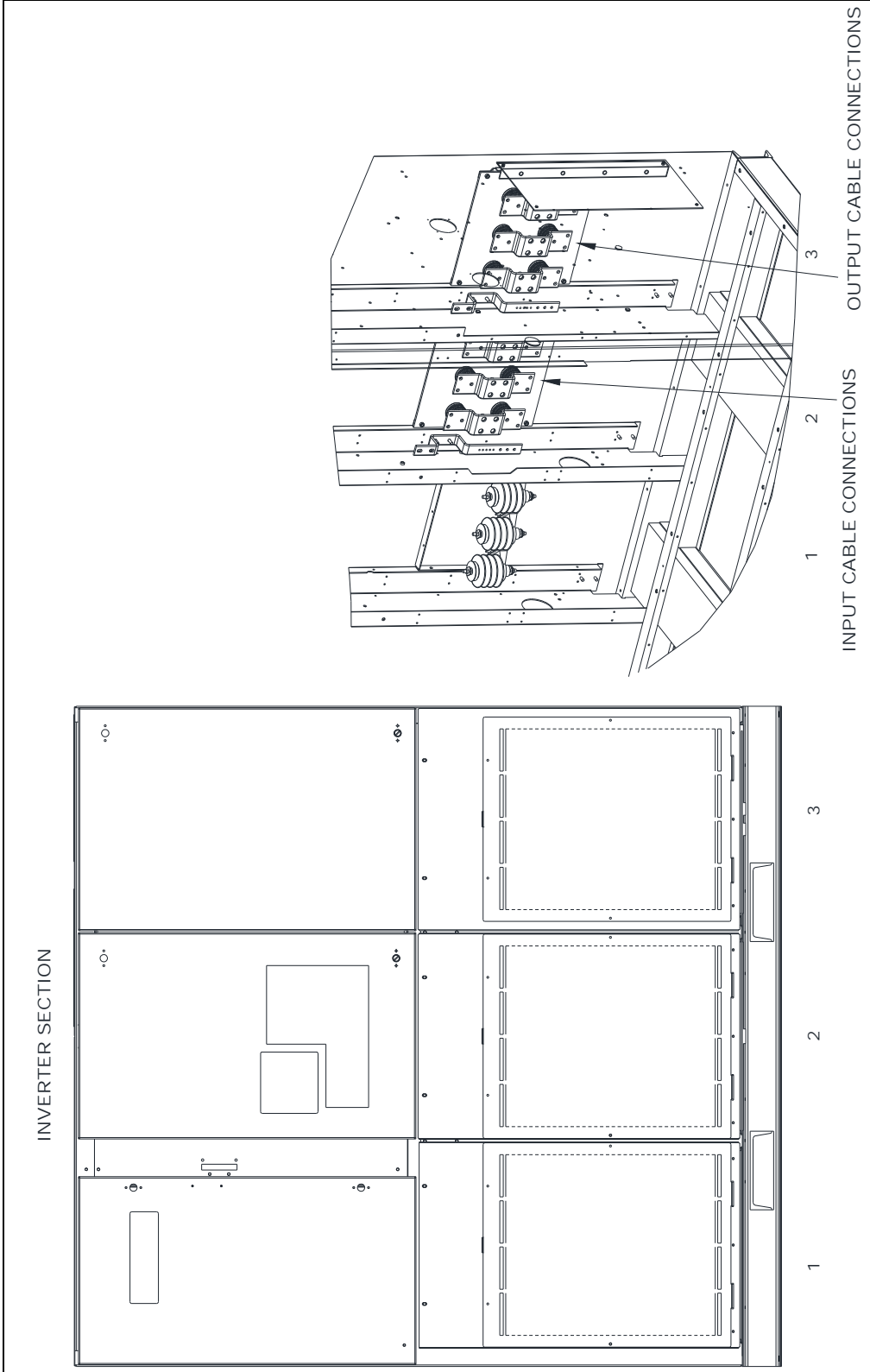
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 3 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 3 drive main cable installation



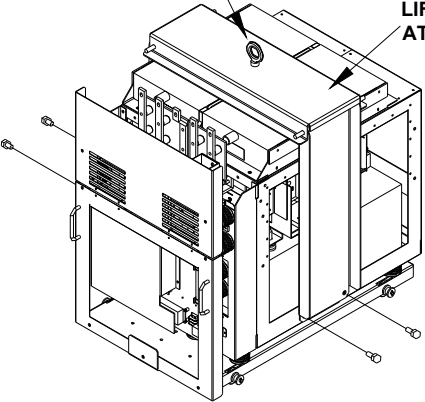


## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 3 module lifting

**LIFTING PROVISIONS**

**LIFT HERE**      **2 LIFTING PROVISIONS ARE AVAILABLE**

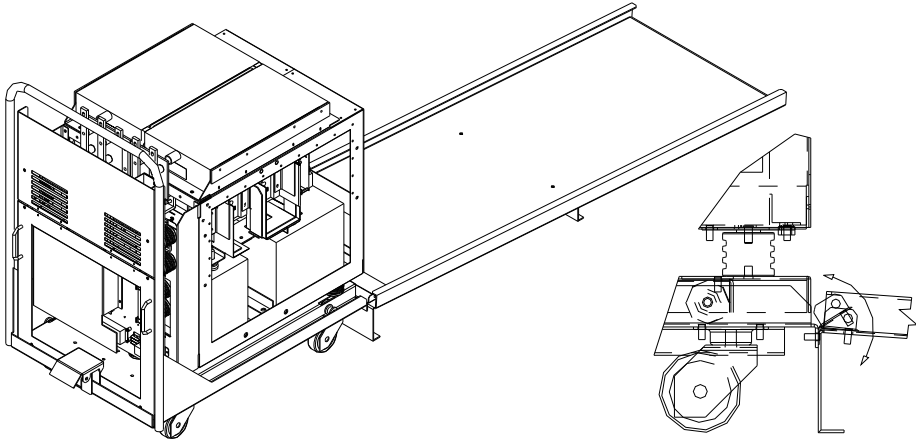


**LIFTING ATTACHMENT**

**1. LOAD OR REMOVE POWER MODULE FROM TRUCK GCI6723G055 USING LIFTING ATTACHMENT GCI6723G054 AND A LIFTING DEVICE RATED FOR 1000 LBS. OR MORE.**

**SECURE BRACKET TO POWER MODULE USING (4) 1/2-13 BOLTS.**

---



**2. LOAD OR REMOVE POWER MODULE FROM TRUCK USING RAMP ASSEMBLY GCI6723G053.**

**LOCK TRUCK TO RAMP BY INSERTING TRUCK PINS INTO RAMP HOLES.**

**SET BRAKE ON TRUCK BEFORE CAREFULLY ROLLING POWER MODULE UP OR DOWN RAMP**

**PC94060P093**

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 3 2400V module installation

|   |   |
|---|---|
| <p><b>WARNINGS</b></p> <p>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> <p>Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.</p> <p>Use Truck GCI6723G055 for removal &amp; installation of modules.</p>   |   |
| <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>1. After capacitor discharge, open upper Power Module cover.</li> <li>2. Disconnect Control Cable from PCB 'A' and lay in wireway above Power Module.</li> <li>3. Disconnect Control Power Cable 'B', lay in wireway above Power Module.</li> <li>4. Remove (4) bolts 'C' from bus stabs P, C, N &amp; ACL</li> <li>5. Remove (1) bolt 'D' from back of Power Module cableway.</li> <li>6. Lock Truck GCI6723G055 to enclosure, insert truck pins into holes in front edge of lower pan 'E'. Set truck brake.</li> <li>7. Withdraw Power Module by handles onto truck until latch engages 'F'. Unlock truck.</li> </ol> | <p><b>Power Module Installation</b></p> <ol style="list-style-type: none"> <li>1. Load Power Module onto Truck. Engage truck latch 'F'.</li> <li>2. Lock Truck GCI6723G055 to front of enclosure, inserting truck pins into holes in front edge of lower pan 'E'.</li> <li>3. Unlatch Power Module 'F'. Roll Power Module by handles from truck onto enclosure rail until enclosure and Power Module bus stabs touch.</li> <li>4. Install (1) bolt 'D' at back of cableway. Unlock, remove truck.</li> <li>5. Install (4) bolts 'C' through bus stabs P, C, N &amp; ACL. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.</li> <li>6. Connect Control Power Cable from wireway as shown at 'B'.</li> <li>7. Connect Control Cable from wireway to PCB as shown at 'A'.</li> <li>8. Close upper Power Module cover. Secure with 2 bolts.</li> <li>9. Replace outside filter cover.</li> </ol> <p style="text-align: right;">PC9406P100</p> |

## DRIVE INSTALLATION DRAWINGS (cont'd)

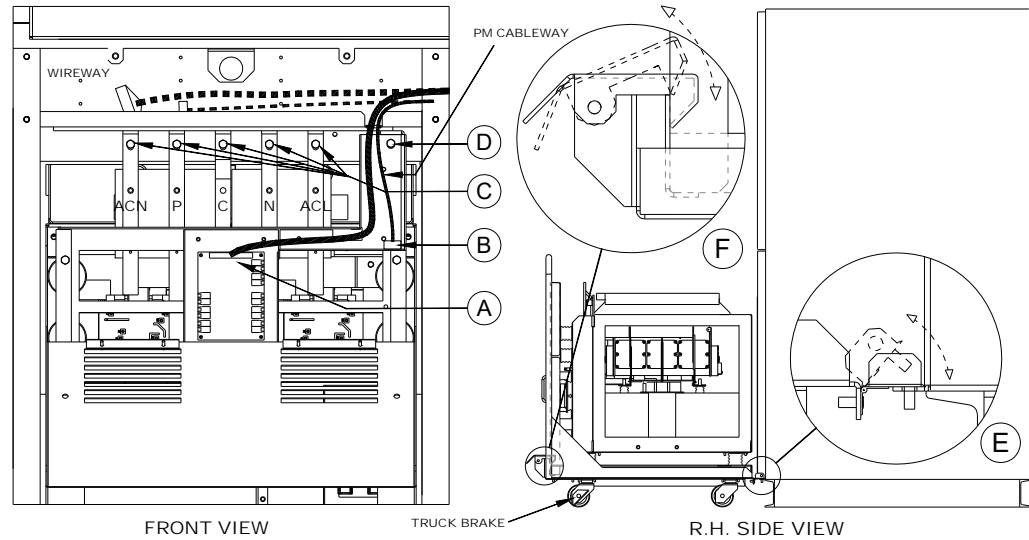
### Frame 3 4160V module installation

#### WARNINGS

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use Truck GCI6723G055 for removal & installation of modules.



#### Power Module Removal

1. After capacitor discharge, open upper Power Module cover.
2. Disconnect Control Cable from PCB 'A' and lay in wireway above Power Module.
3. Disconnect Control Power Cable 'B', lay in wireway above Power Module.
4. Remove (5) bolts 'C' from bus stabs ACN, P, C, N & ACL.
5. Remove (1) bolt 'D' from back of Power Module cableway.
6. Lock Truck GCI6723G055 to enclosure, insert truck pins into holes in front edge of lower pan 'E'. Set truck brake.
7. Withdraw Power Module by handles onto truck until latch engages 'F'. Unlock truck.

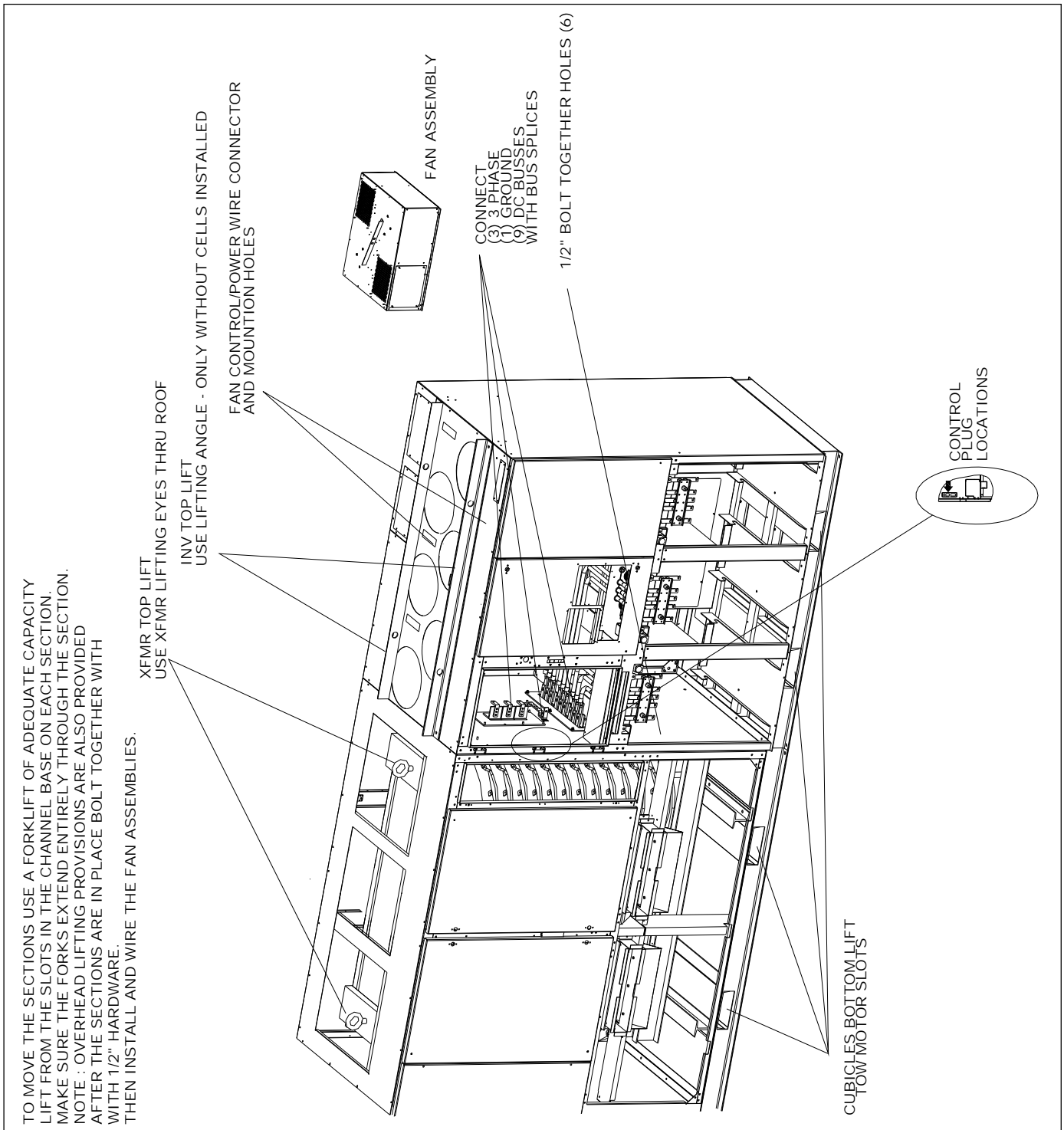
#### Power Module Installation

1. Load Power Module onto Truck. Engage truck latch 'F'.
2. Lock Truck GCI6723G055 to front of enclosure, inserting truck pins into holes in front edge of lower pan 'E'.
3. Unlatch Power Module 'F'. Roll Power Module by handles from truck onto enclosure rail until enclosure and Power Module bus stabs touch.
4. Install (1) bolt 'D' at back of cableway. Unlock, remove truck.
5. Install (5) bolts 'C' through bus stabs ACN, P, C, N & ACL. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.
6. Connect Control Power Cable from wireway as shown at 'B'.
7. Connect Control Cable from wireway to PCB as shown at 'A'.
8. Close upper Power Module cover. Secure with 2 bolts.
9. Replace outside filter cover.

PC94060P092

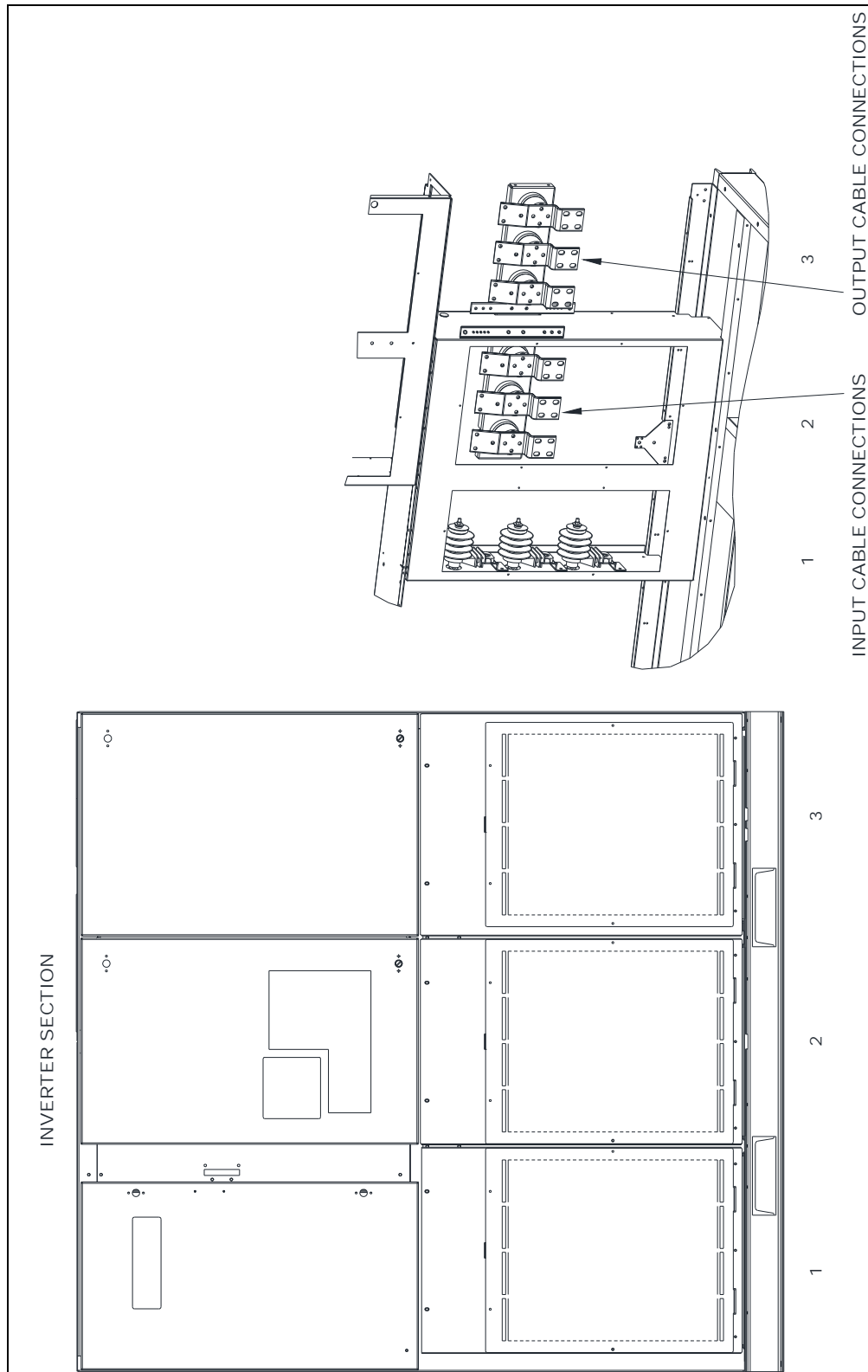
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 4 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 4 drive main cable installation



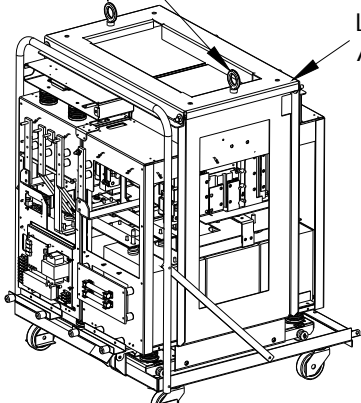
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 4 module lifting

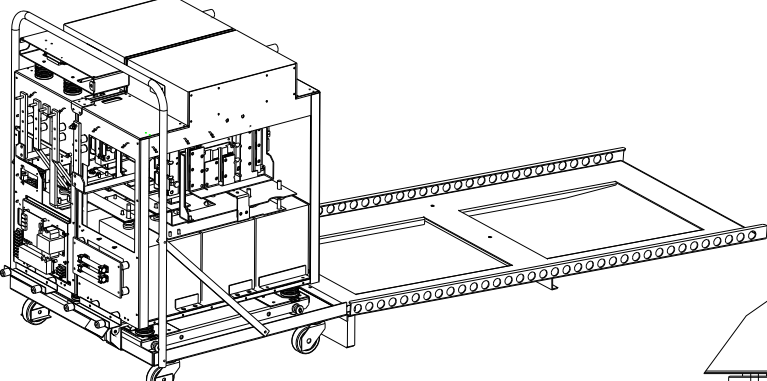
**LIFTING PROVISIONS**  
2 LIFTING PROVISIONS ARE AVAILABLE

Lift Here

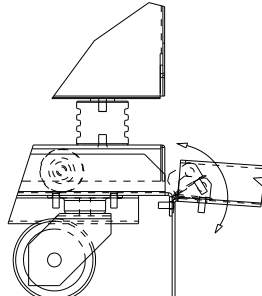
Lifting Attachment



1. Load or remove power module from truck GCI6724G054 using lifting attachment GCI6724G055 and a lifting device rated for 1000 lbs or more.  
  
Secure lifting attachment to power module using (4) 1/2-13 bolts provided.



2. Load or remove power module from truck GCI6724G054 using ramp assembly GCI6724G053.  
  
Lock truck to ramp by inserting truck pins into ramp holes.  
  
Set brakes on truck before carefully rolling power module up or down ramp.



PC94060P121

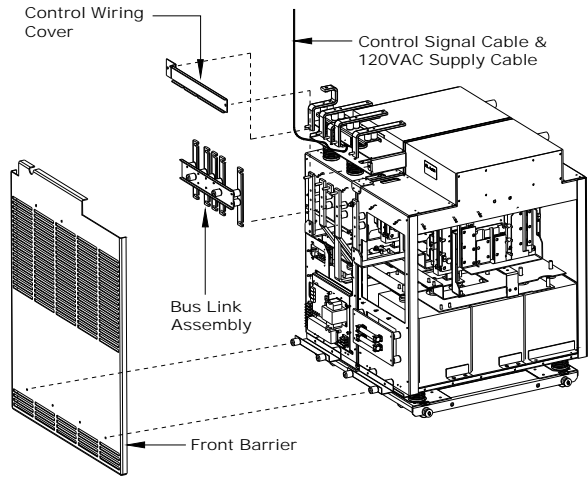
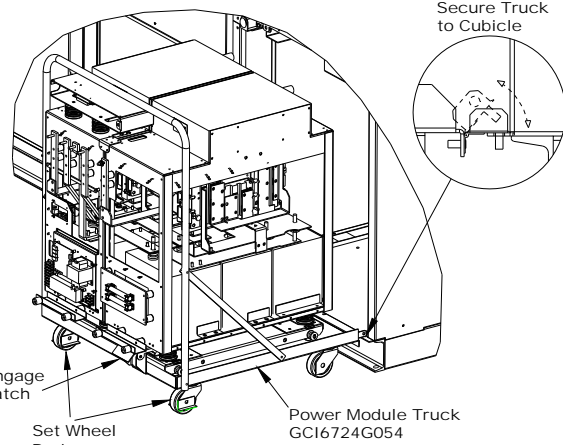
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame 4 2400V module installation

|  |  |   |   |
|--|--|---|---|
| <p>Control Wiring Cover</p> <p>Control Signal Cable &amp; 120VAC Supply Cable</p> <p>Bus Link Assembly</p> <p>Front Barrier</p> <p><b>POWER MODULE DISCONNECTION</b></p>   | <p>Secure Truck to Cubicle</p> <p>Engage Latch</p> <p>Set Wheel Brakes</p> <p>Power Module Truck GC16724G054</p> <p><b>POWER MODULE REMOVAL</b></p>  |   |   |
| <p><b>WARNINGS</b><br/>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> <p>Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.</p> | <p><b>Power Module Disconnection</b></p> <ol style="list-style-type: none"> <li>1. Remove front barrier (six bolts).</li> <li>2. Loosen eight nuts and remove bus link assembly by sliding sideways and off.</li> <li>3. Remove control wiring cover (two bolts)</li> <li>4. Disconnect control signal cable and 120VAC supply cable from module.</li> </ol> | <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>1. Align truck GC16724G054 with front of cubicle.</li> <li>2. Secure truck to cubicle by inserting two studs into holes in base.</li> <li>3. Set wheel brakes on truck.</li> <li>4. Roll power module onto truck until front latch engages.</li> <li>5. Refer to additional instruction label for moving power module on and off of truck.</li> </ol> | <p><b>Power Module Reinstallation</b></p> <ol style="list-style-type: none"> <li>1. Reverse the procedure followed during disconnection and removal of power module.</li> <li>2. Ensure that control signal cable and 120VAC supply cable are properly reconnected.</li> <li>3. Reinstall all hardware previously removed.</li> <li>4. Torque bus link connections (5/16-18 hdwr) to 10-15 ft-lbs.</li> </ol> <p style="text-align: right;">PC94060P174</p> |

## DRIVE INSTALLATION DRAWINGS (cont'd)

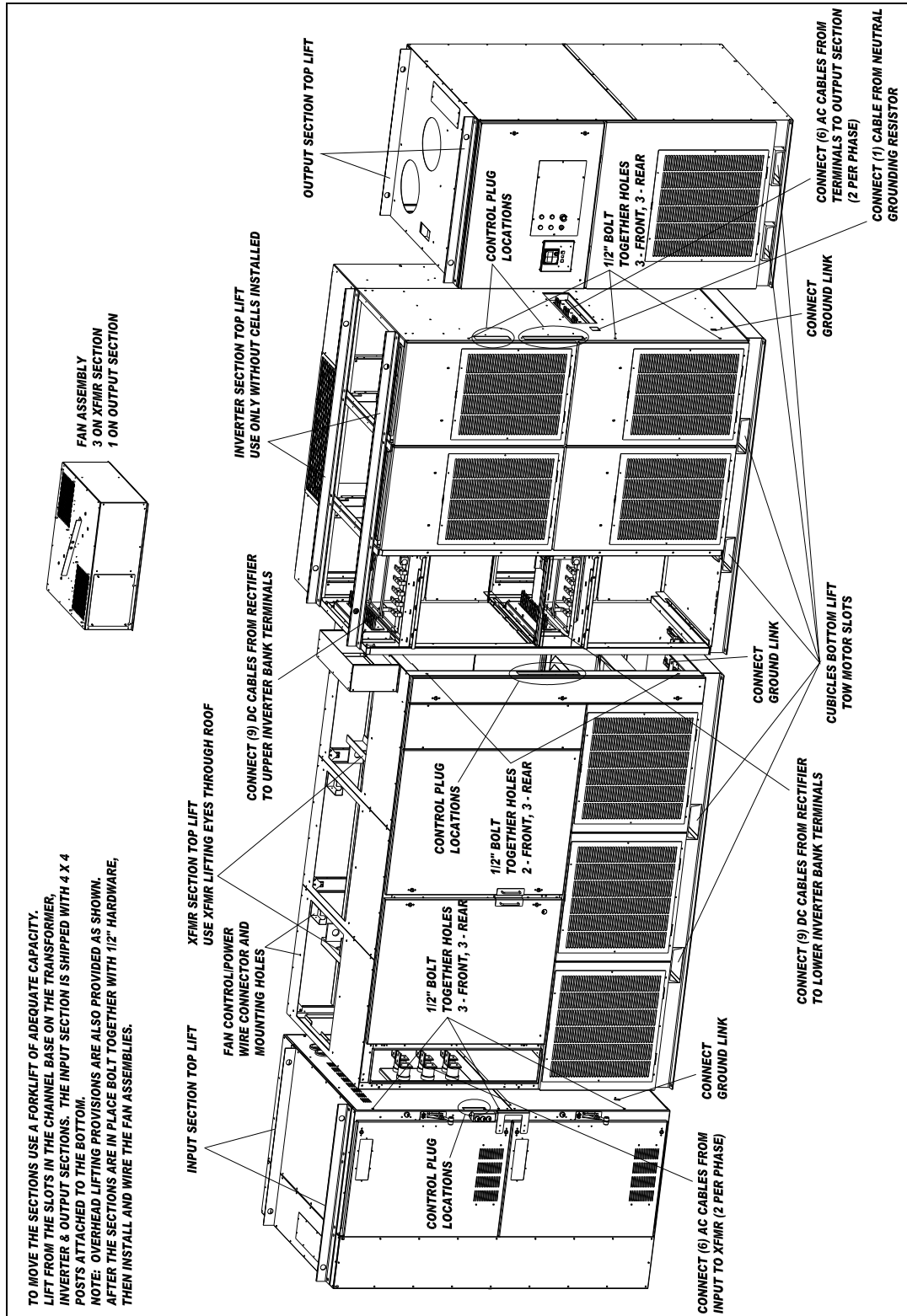
### Frame 4 4160V module installation

|  |  |   |  |
|--|--|---|--|
|  <p>Control Wiring Cover</p> <p>Control Signal Cable &amp; 120VAC Supply Cable</p> <p>Bus Link Assembly</p> <p>Front Barrier</p> <p style="text-align: center;"><b>POWER MODULE DISCONNECTION</b></p>   |  <p>Engage Latch</p> <p>Set Wheel Brakes</p> <p>Power Module Truck GCI6724G054</p> <p>Secure Truck to Cubicle</p> <p style="text-align: center;"><b>POWER MODULE REMOVAL</b></p>   |   |  |
| <p><b>WARNINGS</b><br/>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> <p>Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.</p> | <p><b>Power Module Disconnection</b></p> <ol style="list-style-type: none"> <li>1. Remove front barrier (six bolts).</li> <li>2. Loosen ten nuts and remove bus link assembly by sliding sideways and off.</li> <li>3. Remove control wiring cover (two bolts)</li> <li>4. Disconnect control signal cable and 120VAC supply cable from module.</li> </ol> | <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>1. Align truck GCI6724G054 with front of cubicle.</li> <li>2. Secure truck to cubicle by inserting two studs into holes in base.</li> <li>3. Set wheel brakes on truck.</li> <li>4. Roll power module onto truck until front latch engages.</li> <li>5. Refer to additional instruction label for moving power module on and off of truck.</li> </ol> | <p><b>Power Module Reinstallation</b></p> <ol style="list-style-type: none"> <li>1. Reverse the procedure followed during disconnection and removal of power module.</li> <li>2. Ensure that control signal cable and 120VAC supply cable are properly reconnected.</li> <li>3. Reinstall all hardware previously removed.</li> <li>4. Torque bus link connections (5/16-18 hdwr) to 10-15 ft.-lbs.</li> </ol> <p style="text-align: right;">PC94060P120</p> |



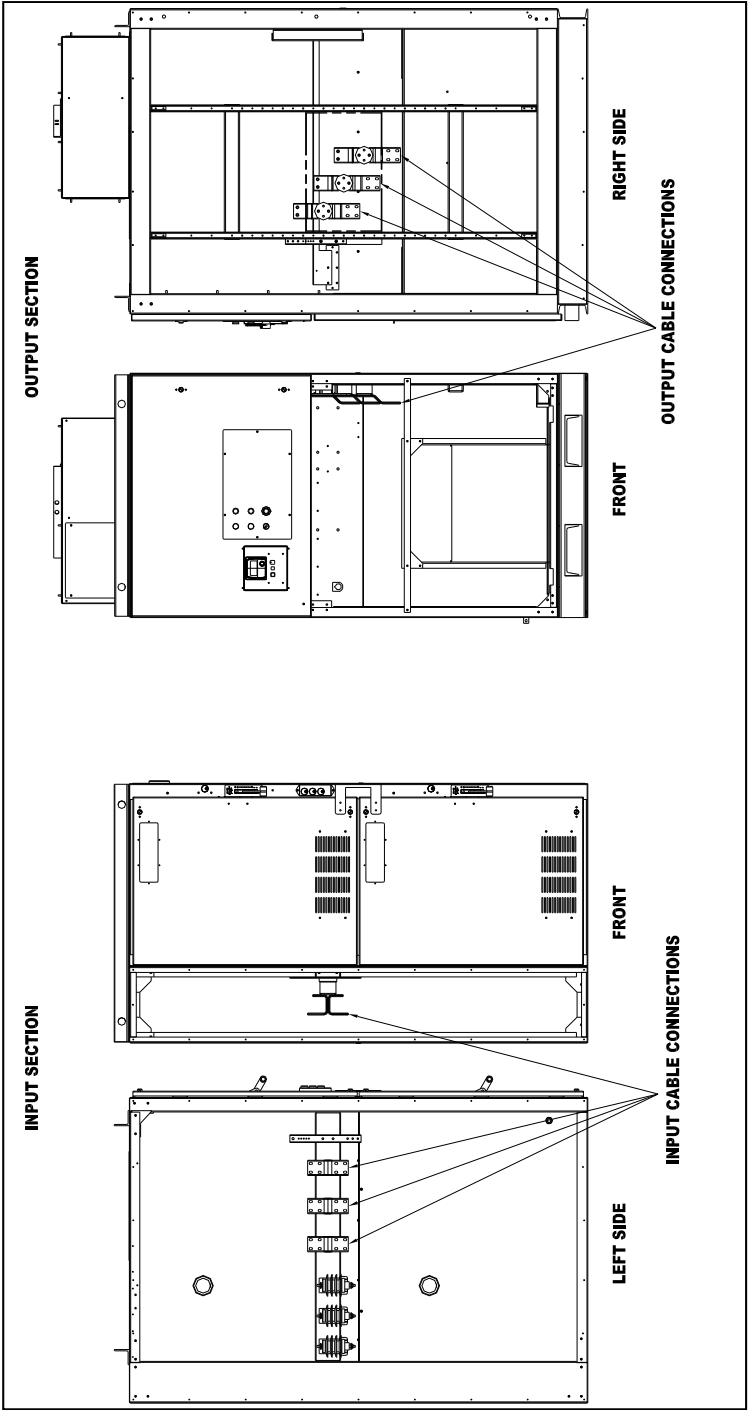
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame G4P drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame G4P drive main cable installation



## DRIVE INSTALLATION DRAWINGS (cont'd)

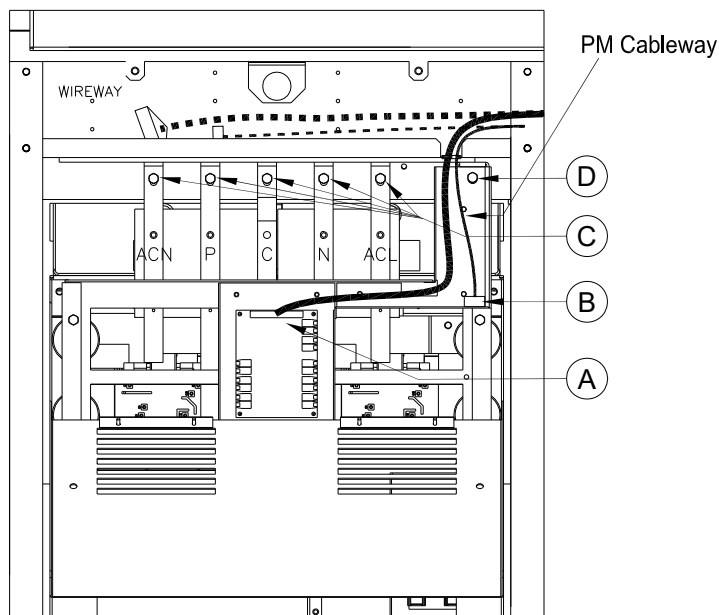
### Frame G4P module lifting and installation

#### WARNINGS

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use Lift PC10480P910 for removal & installation of modules



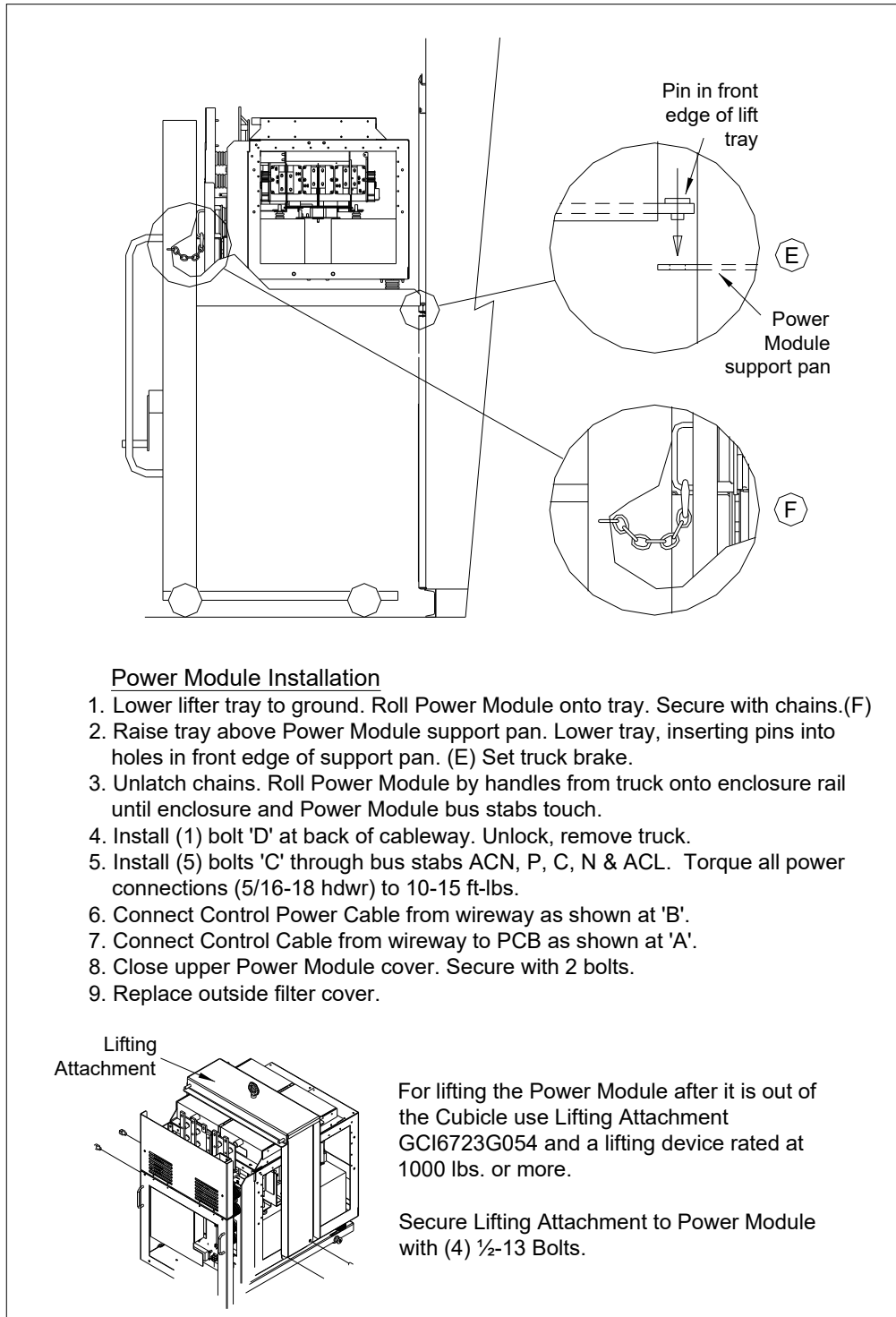
#### Power Module Removal

1. After capacitor discharge, open upper Power Module cover.
2. Disconnect Control Cable from PCB 'A' and lay in wireway above Power Module.
3. Disconnect Control Power Cable 'B', lay in wireway above Power Module.
4. Remove (5) bolts 'C' from bus stabs ACN, P, C, N & ACL
5. Remove (1) bolt 'D' from back of Power Module cableway.
6. Raise tray of lifter PC10480P910 above Power Module support pan. Lower tray inserting tray pins into holes in front edge of support pan. (E) Set truck brake.
7. Withdraw Power Module by handles onto tray. Secure Power Module to tray by connecting chains to Power Module handles.(F)
8. Raise tray to until pins are clear of mounting pan. Slowly move lifter back, away from cubicle. Use crank to slowly lower Power Module to the floor.

PC94060P191

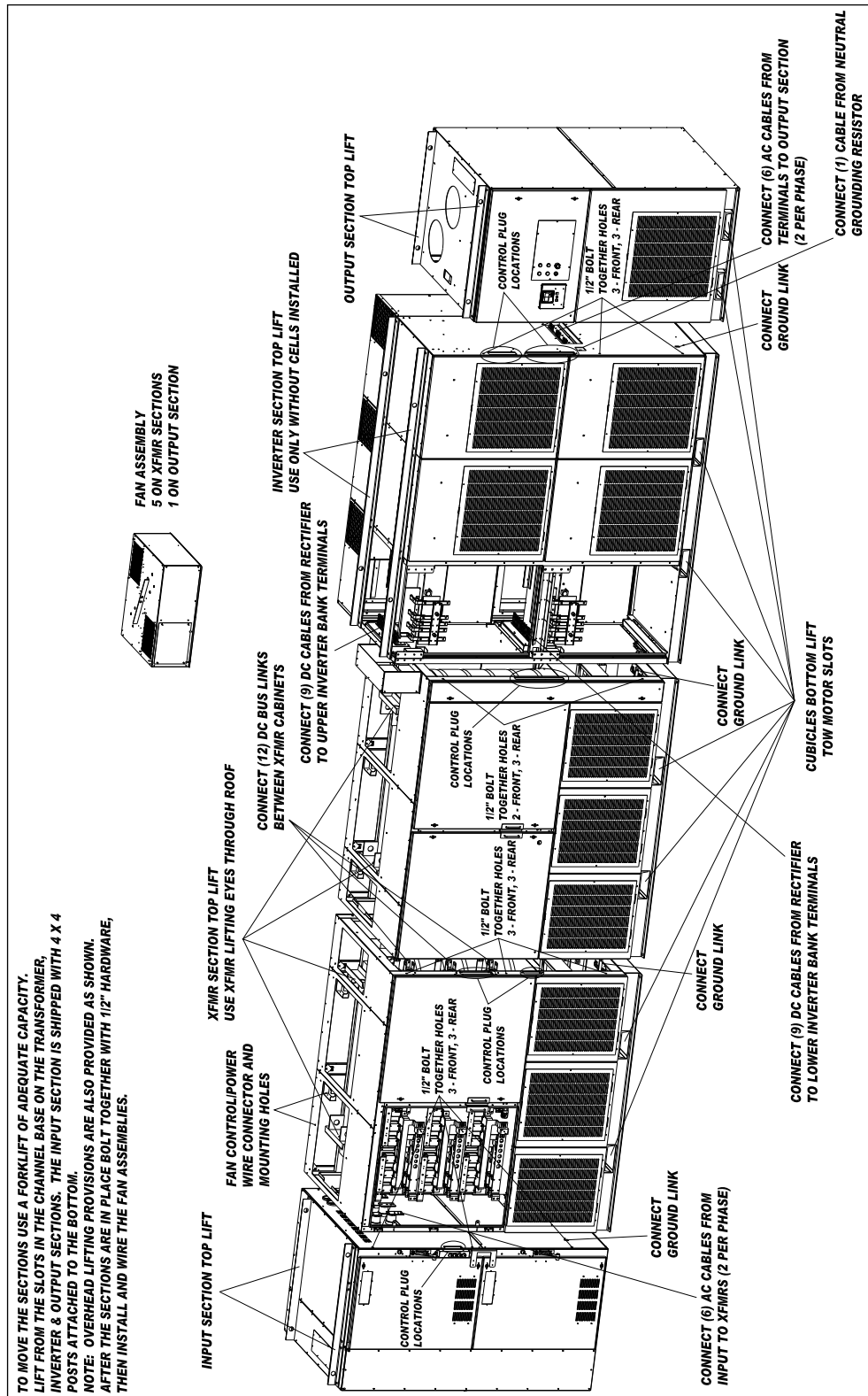
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame G4P module lifting and installation continued



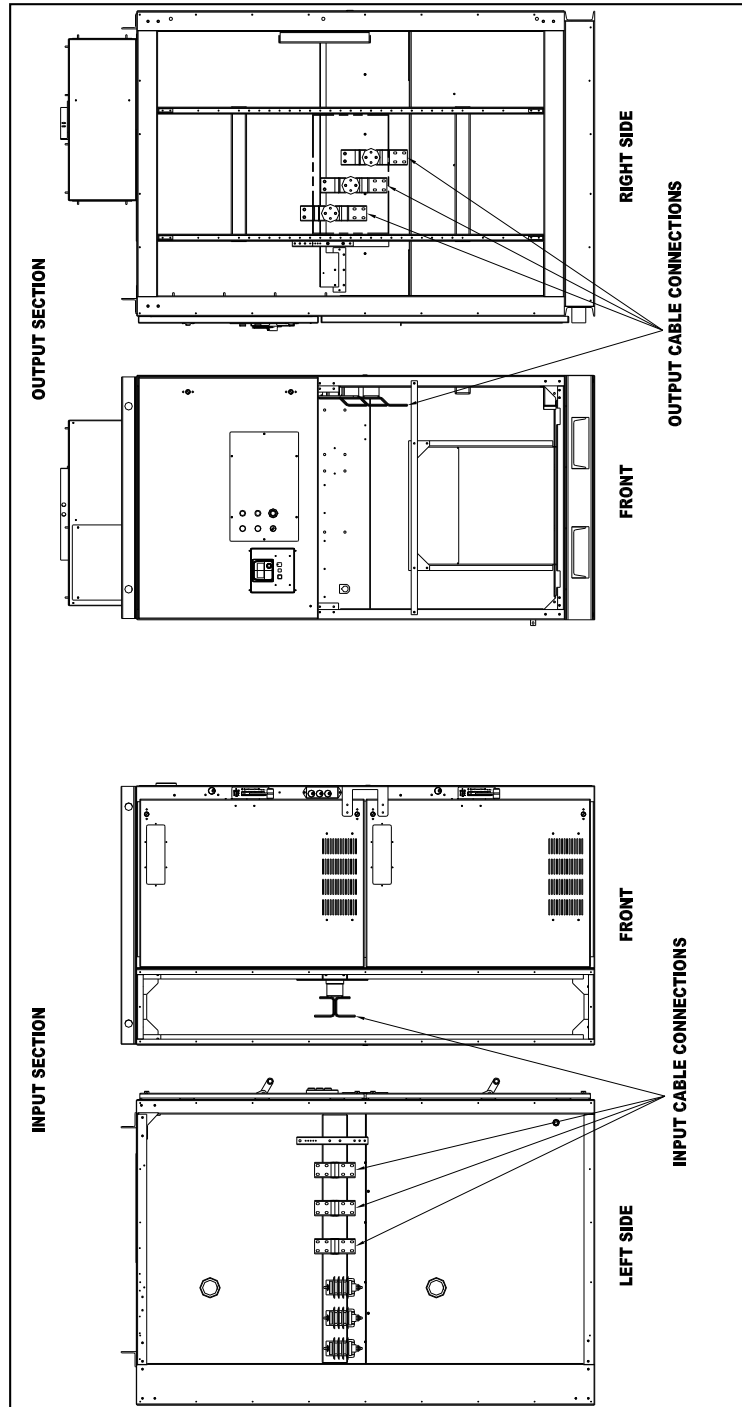
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame H4P drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame H4P drive main cable installation



## DRIVE INSTALLATION DRAWINGS (cont'd)

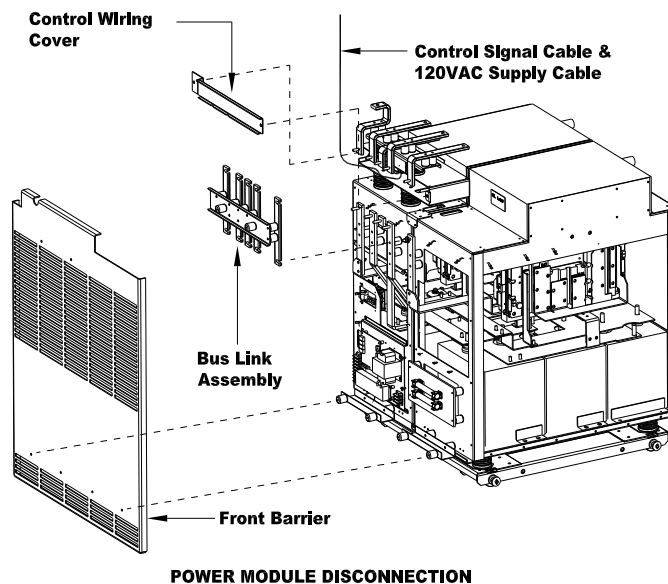
### Frame H4P module lifting and installation

#### WARNINGS

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use Lift PC10480P910 for removal & installation of modules



#### Power Module Disconnection

1. Remove front barrier (six bolts).
2. Loosen ten nuts and remove bus link assembly by sliding sideways and off.
3. Remove control wiring cover (two bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.

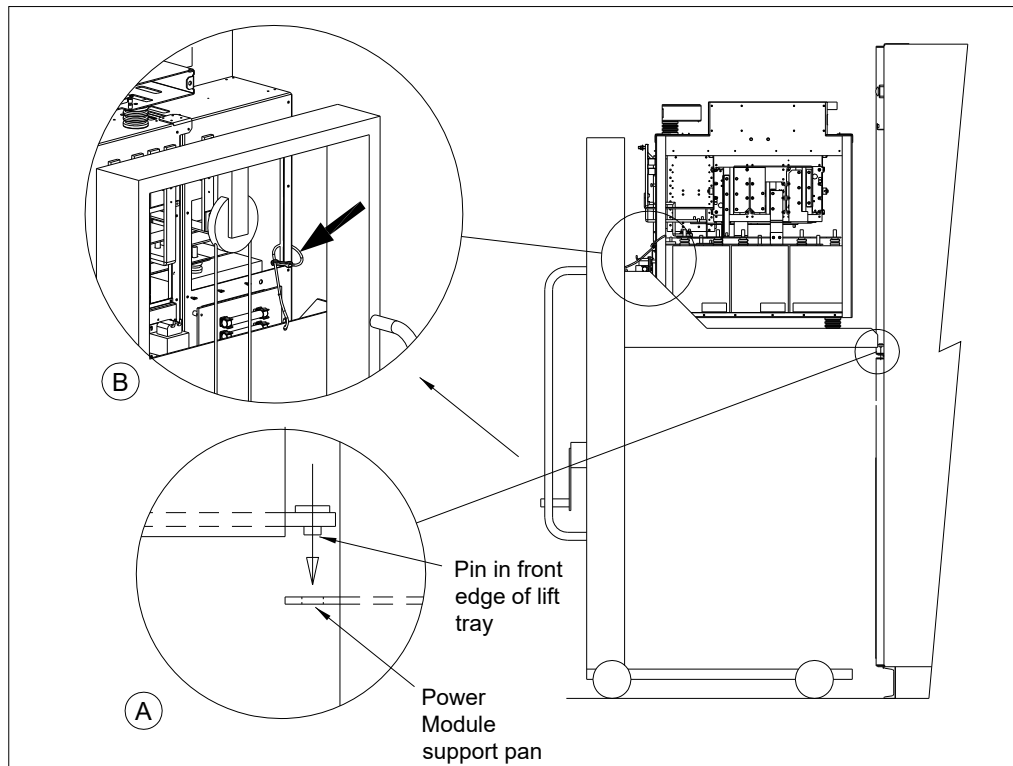
#### Power Module Removal

1. Position lifter squarely in front of cubicle. Raise tray of lifter PC10480P910 above Power Module support pan. Lower tray inserting tray pins into holes in front edge of support pan. (A) Set truck brake.
2. Withdraw Power Module onto lifter tray. Secure Power Module to tray by looping and latching chain or cable through right side of chassis.(B)
3. Raise tray to until pins are clear of support pan. Slowly move lifter back, away from cubicle. Use crank to slowly lower Power Module to the floor.

PC94060P193

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame H4P module lifting and installation continued

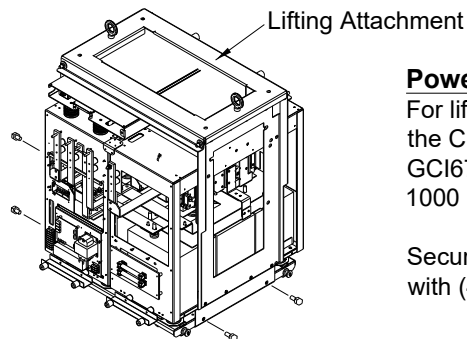


#### **Power Module Installation**

1. Lower lifter tray to ground. Roll Power Module onto tray. Secure Power Module.(B)
2. Raise tray above Power Module support pan. Lower tray, inserting pins into holes in front edge of support pan. (A) Set truck brake.
3. Unlatch Power Module (B). Roll Power Module from truck onto enclosure rails.

#### **Power Module Reconnection**

1. Reverse the procedure followed during disconnection and removal of Power Module.
2. Ensure that control signal cable and 120VAC supply cable are properly reconnected.
3. Reinstall all hardware previously removed.
4. Torque bus link connections (5/16-18 hdwr) to 10-15 ft-lbs.



#### **Power Module Lifting**

For lifting the Power Module after it is out of the Cubicle use Lifting Attachment GCI6724G055 and a lifting device rated at 1000 lbs. or more.

Secure Lifting Attachment to Power Module with (4) ½ -13 Bolts.

PC94060P194



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A2 module lifting and installation

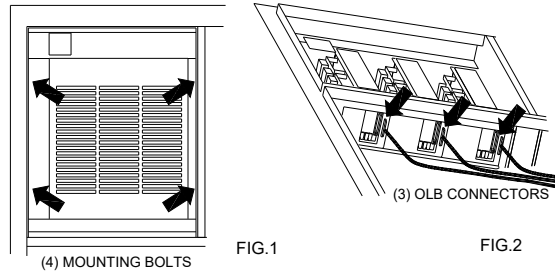
**WARNINGS:**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care when handling fiber optic cables.

**REMOVING A SINGLE PHASE POWER MODULE**

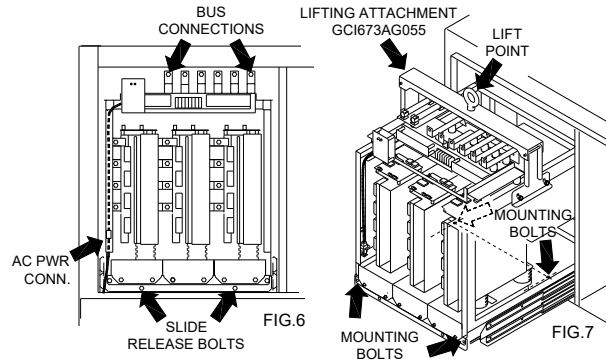
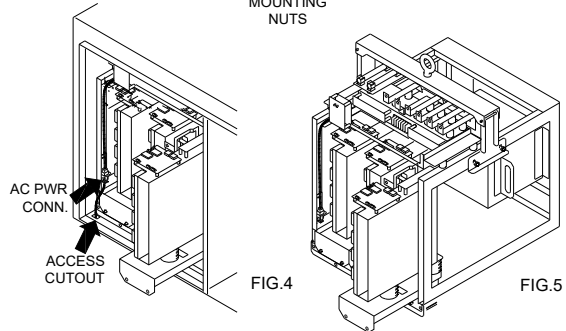
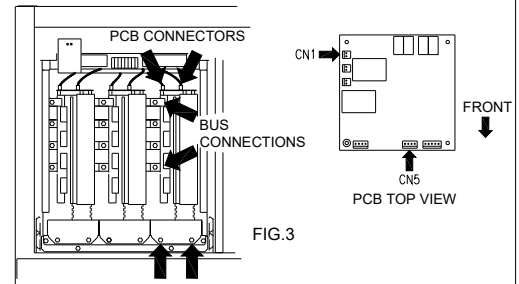
1. After 15 minute capacitor discharge time, remove front barrier, (4) bolts. Figure 1.
2. Disconnect OLB Cable from bottom of Cell. Access from below through LV Compartment. Figure 2.
3. Disconnect PCB connectors marked CN1 and CN5. Figure 3. Set wires up on support rail to avoid snagging during cell removal.
4. Remove bus connection bolts (4). Figure 3.
5. Remove cell mounting nuts (2). Figure 3.
6. Slide cell forward and remove from cabinet. Figure 4.
7. Replace cell by following the steps above in reverse order.



**REMOVING THE THREE PHASE CELL ASSEMBLY**

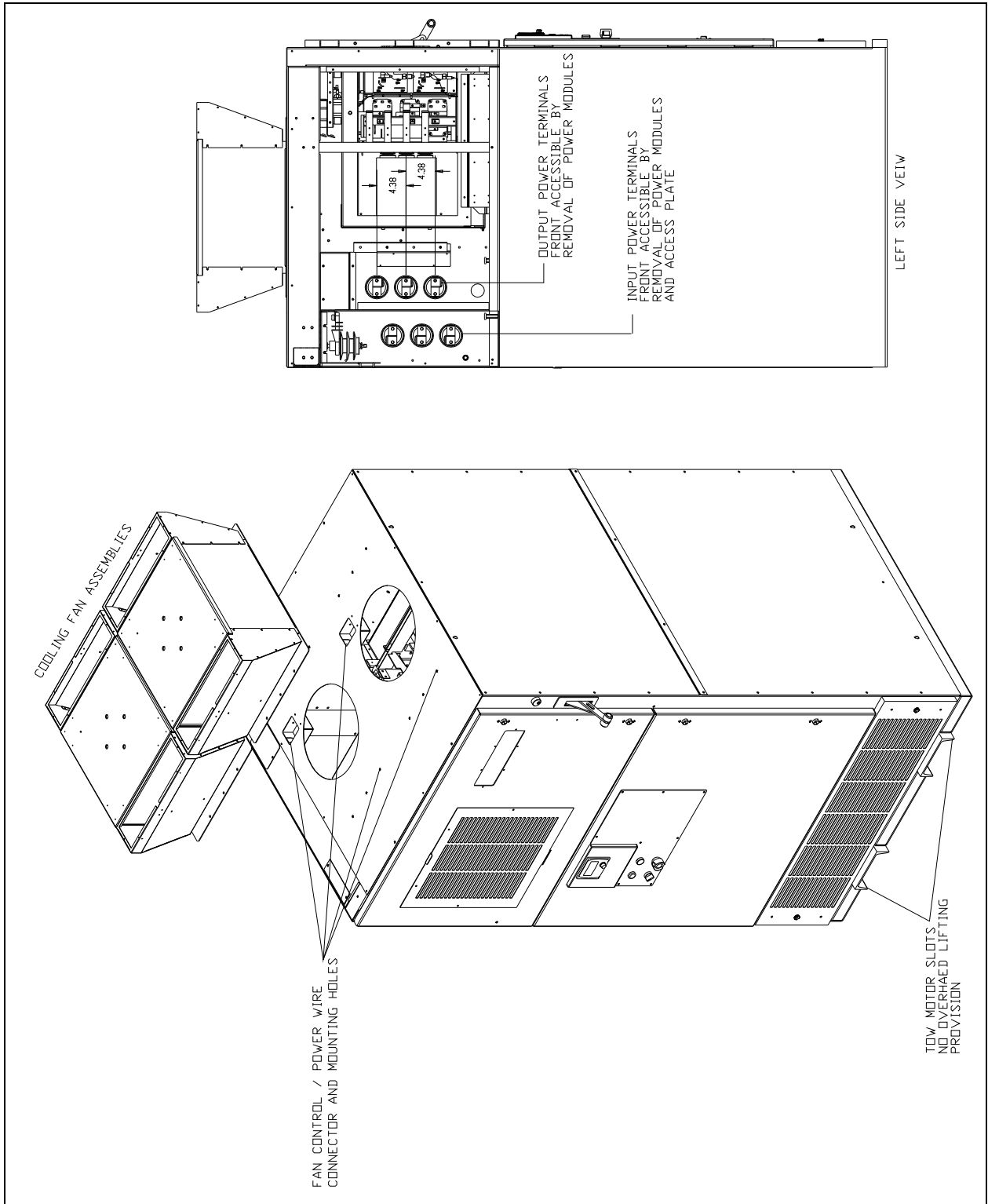
Use lifting attachment GCI673AG055 and a lifting device rated 300 lbs minimum for removal and installation of Three Phase Cell Assembly.

1. After 15 minute capacitor discharge time, remove front barrier, (4) bolts. Figure 1.
  2. Disconnect (3) OLB Cables from bottom of the Cells. Access from below through LV Compartment. Figure 2.
  3. Remove bus connection bolts (6) on top of assembly. Figure 6.
  4. Disconnect AC power connector (1). Slide wires down access cutout into L.V. compartment before proceeding to the next step. Fig. 4 and 6.
  5. Remove slide release bolts (2). Figure 6.
  6. Slide assembly forward until slides lock. Figure 7.
  7. Install Lifting Attachment GCI673AG055. Bolt (4) places. Fig. 7.
  8. Remove assembly mounting bolts (4). (2) in front edge, (2) behind cells through base panel. Figure 7.
  9. Lift assembly off tray with a lifting device rated for 300 lbs or more.
- Replace cell by following the steps above in reverse order. Release all slide locks before sliding assembly back into cubicle.



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A2 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B2 2400V module lifting and installation Type 1

|                 |   |  |   |
|-----------------|---|--|---|
| <u>WARNINGS</u> | Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance. | Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care when handling fiber optic cables. | Use module lifting attachment GC1673BG055 and a lifting device rated 125 lbs minimum for removal and installation of modules. |
|-----------------|---|--|---|

**Power Module Removal**

1. Lift latch and lower shelf to service position.
2. Disconnect ACL power cable.
3. Disconnect control plug.
4. Disconnect P, C & N bus bars by removing hardware "A".
5. Remove bolt "B".
6. Slide module out of compartment and onto shelf.
7. Disconnect four (4) fiber optic cables from module.
8. Using module lifting attachment and lifter, lift module from shelf.

**Power Module Installation**

1. Lower shelf to service position.
2. Using module lifting attachment and lifter, place module on shelf.
3. Reconnect four (4) fiber optic cables to module.
4. Align module and push into compartment until it stops.
5. Reinstall bolt "B".
6. Install previously removed hardware "A" to connect P, C & N bus bars.
7. Reconnect control plug.
8. Reconnect ACL power cable.
9. Torque P, C, N & ACL connections (5/16-18 hdwr) to 10-15 ft-lbs.
10. Push shelf back up and latch in stowed position.

PC94060P198

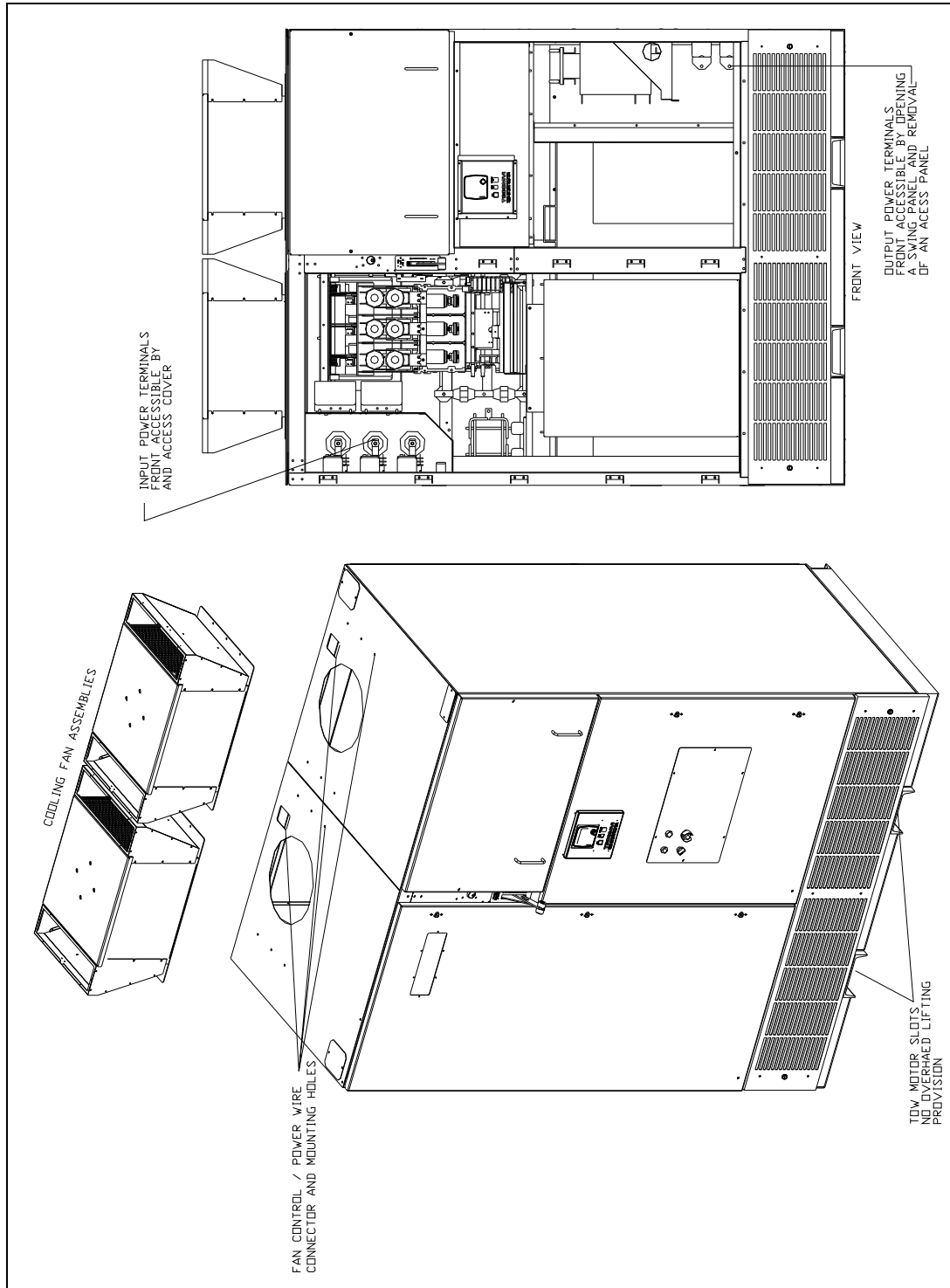
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B2 module lifting and installation Type 2

|   |  |   |  |
|---|--|---|--|
| <p><b>WARNINGS</b></p>  | <p>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> | <p>Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care when handling fiber optic cables.</p> | <p>Use module lifting attachment GC1673BG055 and a lifting device rated 125 lbs minimum for removal and installation of modules. Lifting attachment is stored inside the Power Module Compartment.</p> |
| <div style="display: flex; justify-content: space-between;"> <div data-bbox="261 436 633 1167" style="width: 45%;"> <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>1. Disconnect ACL power cable.</li> <li>2. Disconnect control plug.</li> <li>3. Disconnect P, C &amp; N bus bars by removing hardware "A".</li> <li>4. Remove bolt "B".</li> <li>5. Slide lifting attachment into module extension guide and fasten lifting attachment using bolt "C".</li> <li>6. Pull module out into lifting attachment.</li> <li>7. Latch module (see "LATCH DETAIL").</li> <li>8. Disconnect four (4) fiber optic cables from module.</li> <li>9. Couple lifting device to lifting attachment.</li> <li>10. Unfasten bolt "C".</li> <li>11. Using lifting device, slide power module and lifting attachment together out of module extension guide.</li> </ol> <p><b>Power Module Installation</b></p> <ol style="list-style-type: none"> <li>1. Using lifting device, insert module with lifting attachment into module extension guide.</li> <li>2. Fasten bolt "C".</li> <li>3. Reconnect four (4) fiber optic cables to module.</li> <li>4. Lift latch, align module and push into compartment until module bus bars are flush with P, C, &amp; N bus bars.</li> <li>5. Unfasten bolt "C".</li> <li>6. Remove lifting attachment by sliding it out of module extension guide.</li> <li>7. Reinstall bolt "B".</li> <li>8. Install previously removed hardware "A" to connect P, C &amp; N bus bars.</li> <li>9. Reconnect control plug.</li> <li>10. Reinstall previously removed ACL cable.</li> <li>11. Torque P, C, N &amp; ACL connections (5/16-18 hdwr) to 10-15 ft-lbs.</li> </ol> </div> <div data-bbox="633 436 1417 1167" style="width: 50%;"> </div> </div> |  |   |  |

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B2 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame D2 module lifting and assembly

**! DANGER**



**TOP HEAVY EQUIPMENT**

Cabinet Can Tip Over Causing Serious Injury or Death.

Do Not Attempt to Withdraw Power Modules Without First Securely Anchoring Equipment to Floor.

PC94060P007

**! DANGER**

When the service drawer is withdrawn, the power modules have sufficient weight to tip over the Frame D2 inverter cabinet if it is not firmly anchored to the mounting floor, resulting in severe injury or death.

**DO NOT** attempt to install or withdraw the Frame D2 power modules before first securely anchoring the cabinet to the floor.

|   |   |  |
|---|---|--|
| <p><b>WARNINGS</b></p> <p>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> | <p>Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care when handling fiber optic cables.</p> | <p>Use module lifting attachment GCI673DG055 and a lifting device rated 200 lbs minimum for removal and installation of modules. Lifting attachment is stored inside low voltage compartment door.</p> |
|---|---|--|

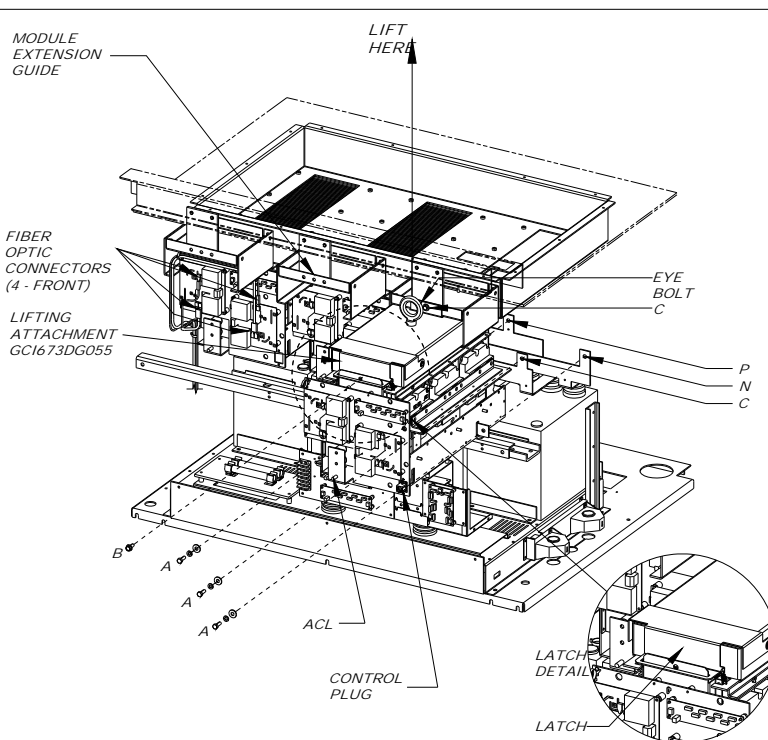
  

**Power Module Removal**

1. Disconnect ACL power cable.
2. Disconnect control plug.
3. Disconnect P, C & N bus bars by removing hardware "A".
4. Remove bolt "B".
5. Disconnect four (4) fiber optic cables from module.
6. Slide lifting attachment into module extension guide and fasten lifting attachment using bolt "C".
7. Pull module out into lifting attachment.
8. Latch module (see "LATCH DETAIL").
9. Couple lifting device to lifting attachment using "EYE BOLT".
10. Unfasten bolt "C".
11. Using lifting device, slide power module and lifting attachment together out of module extension guide.

**Power Module Installation**

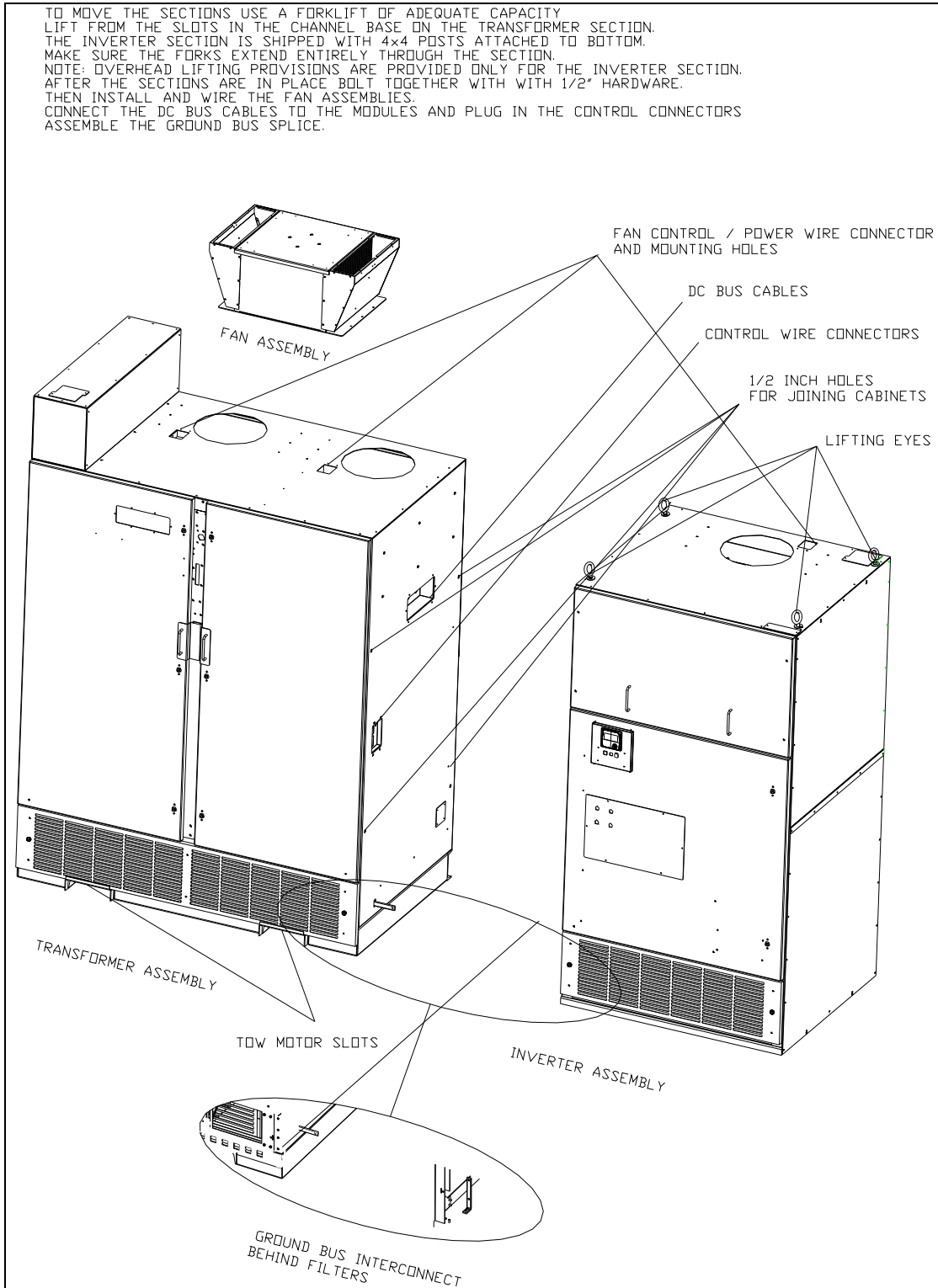
1. Using lifting device, insert module with lifting attachment into module extension guide.
2. Fasten bolt "C".
3. Lift latch, align module and push into compartment until module bus bars are flush with P, C, & N bus bars.
4. Unfasten bolt "C".
5. Remove lifting attachment by sliding it out of module extension guide.
6. Reinstall bolt "B".
7. Reconnect four (4) fiber optic cables to module.
8. Install previously removed hardware "A" to connect P, C & N bus bars.
9. Reconnect control plug.
10. Reinstall previously removed ACL cable.
11. Torque P, C, N & ACL connections (5/16-18 hdwr) to 10-15 ft-lbs.



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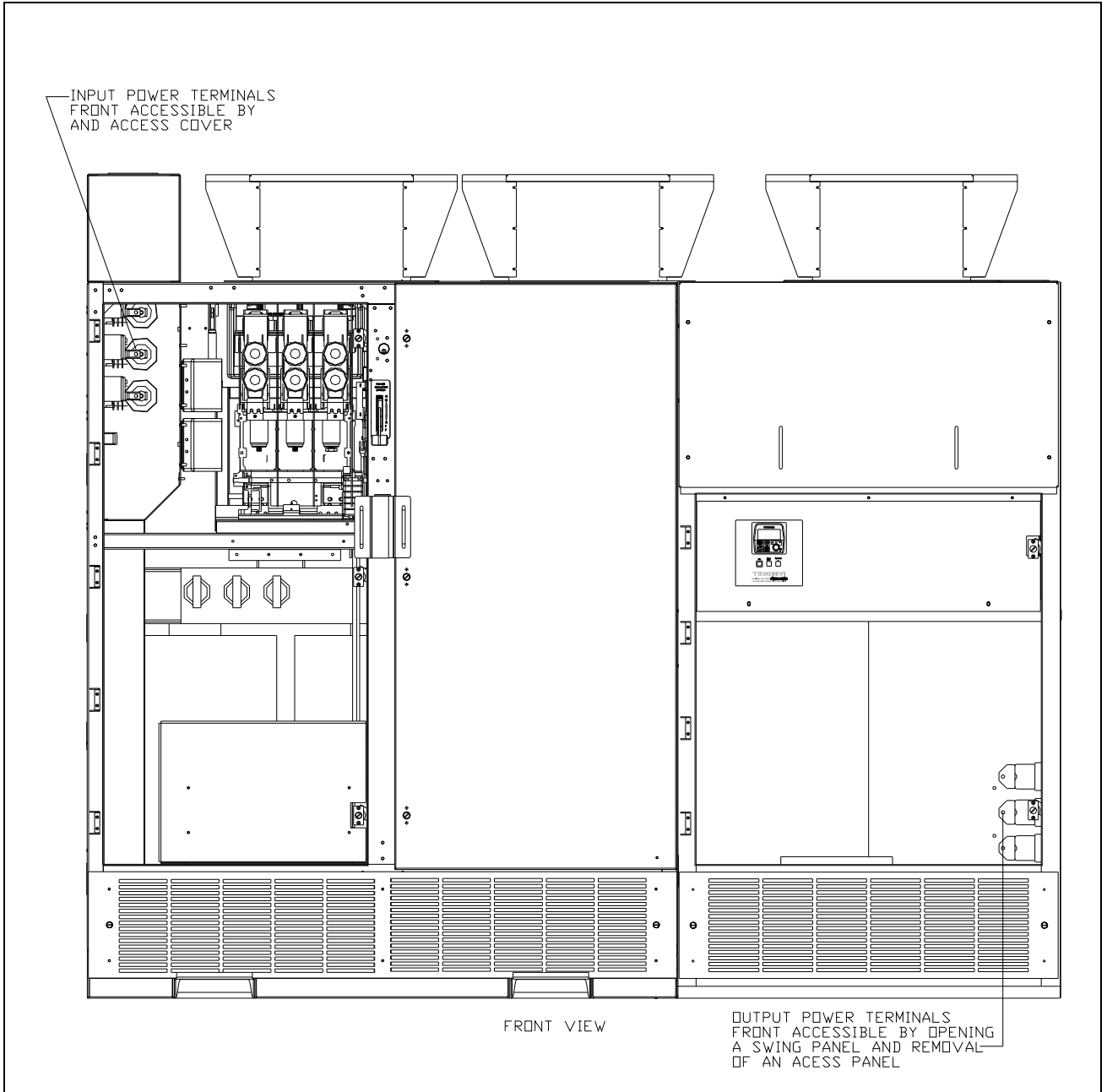
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame D2 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame D2 drive main terminal locations





## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A4μ module lifting and installation

**WARNINGS:**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care when handling fiber optic cables.

**REMOVING/REPLACING POWER MODULE**

1. After 15 minute capacitor discharge time, remove front barrier, four "A" bolts. Figure 1.
2. Disconnect AC Neutral Cable. Disconnect and remove AC Neutral Bus. Figure 2.
3. Disconnect Power Cables P,C,N & ACL. Figure 2.
4. Disconnect Control Signal Cable and 120VAC Supply Cable from bottom of Cell. Access from below through LV Compartment. Figure 3.
5. Free slide tray by removing two "B" bolts. Figure 4.
6. Pull slide tray out until slides lock. Figure 4.
7. Remove four "C" bolts which secure module to tray. Figure 4.
8. Use a lifting device rated for 200 pounds or more to lift module from tray by module lifting hole.
9. Replace module by following the steps above in reverse order. Press buttons on inside slide surfaces to slide tray back. Torque power connections (10-32 nuts) to 30 inch-lbs.

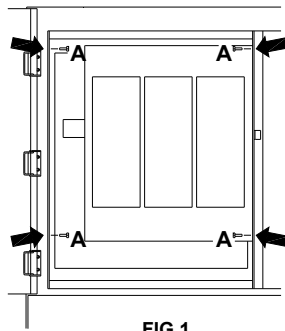


FIG.1

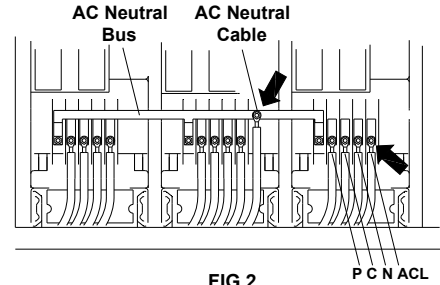


FIG.2

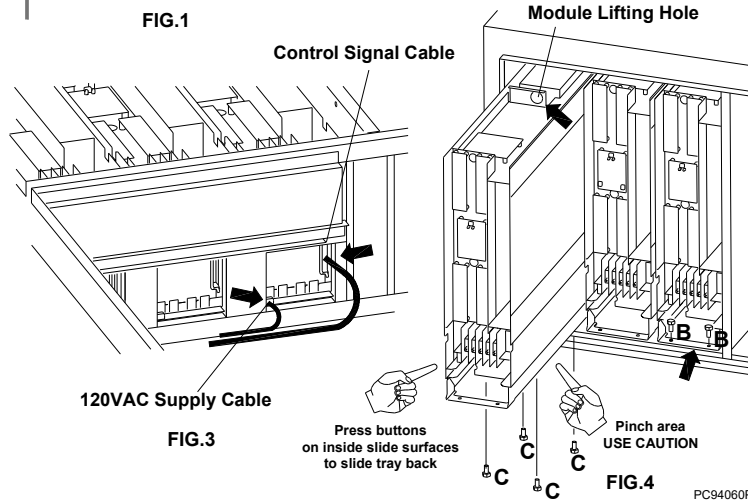


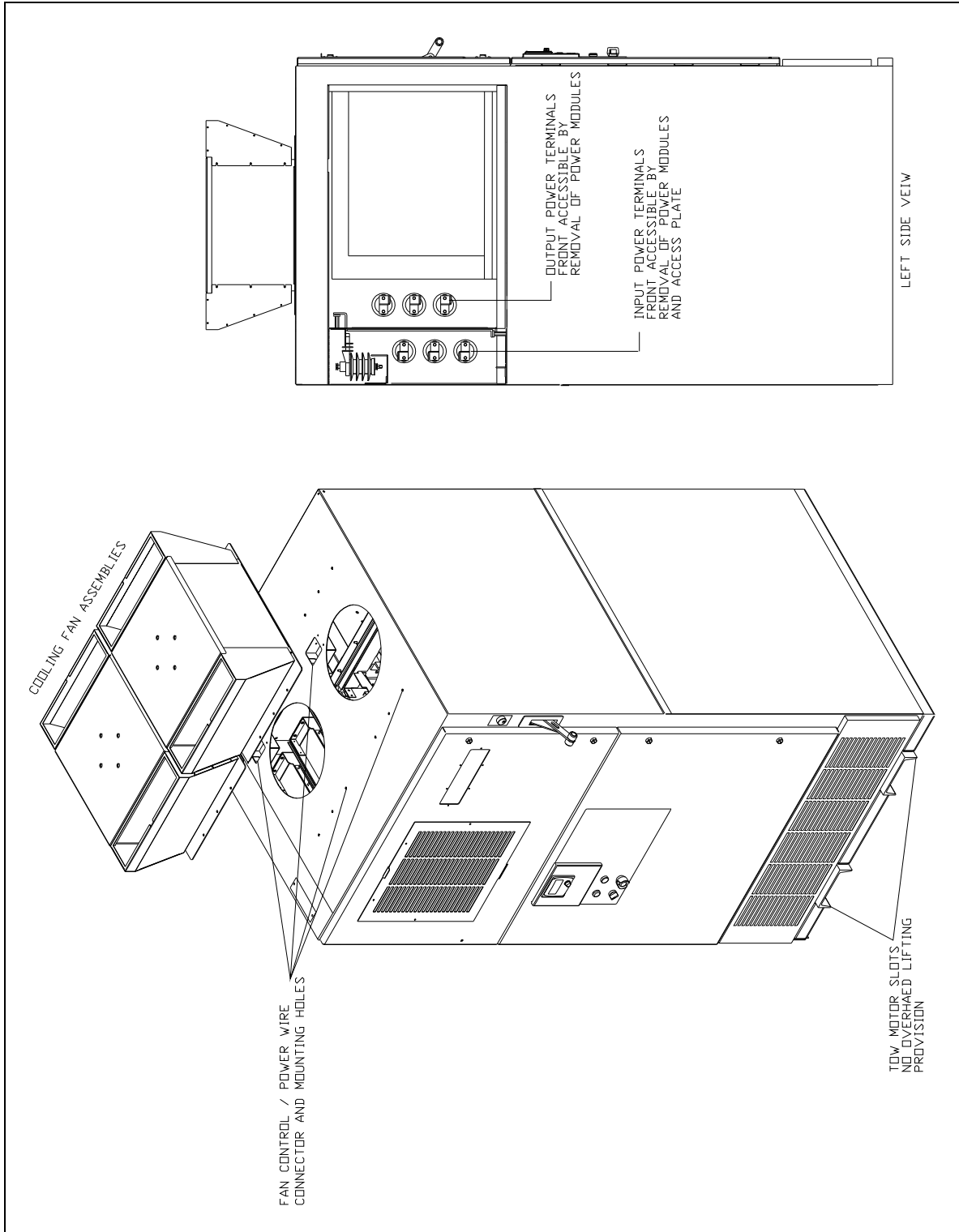
FIG.3

FIG.4

PC94060P214

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A4 $\mu$ drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A4 module lifting and installation

**WARNINGS**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GCI6720G055 and a lifting device rated 250 lbs minimum for removal and installation of modules.

**Power Module Removal**

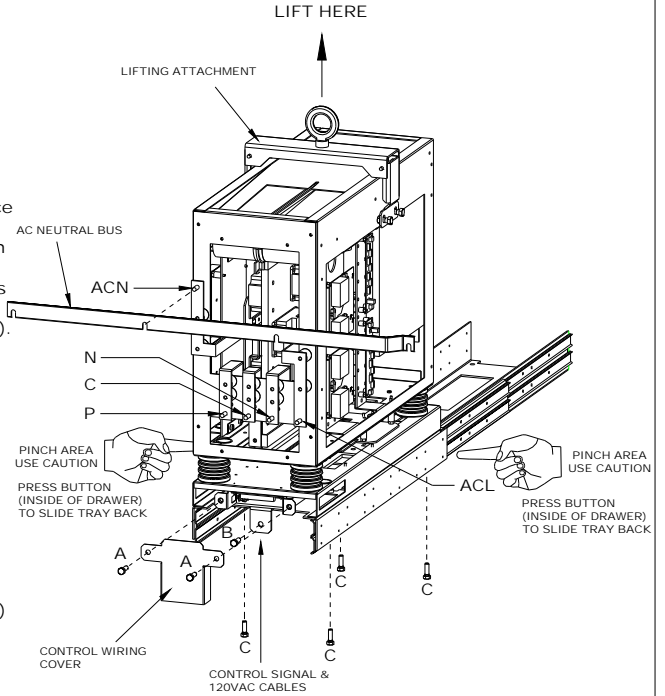
1. Disconnect and remove AC neutral bus.
2. Disconnect power cables ACL, P, C & N.
3. Remove control wiring cover (two "A" bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".
6. Pull slide tray out until slides lock.
7. Remove four "C" bolts which secure module to tray.

**Power Module Removal (cont'd)**

8. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

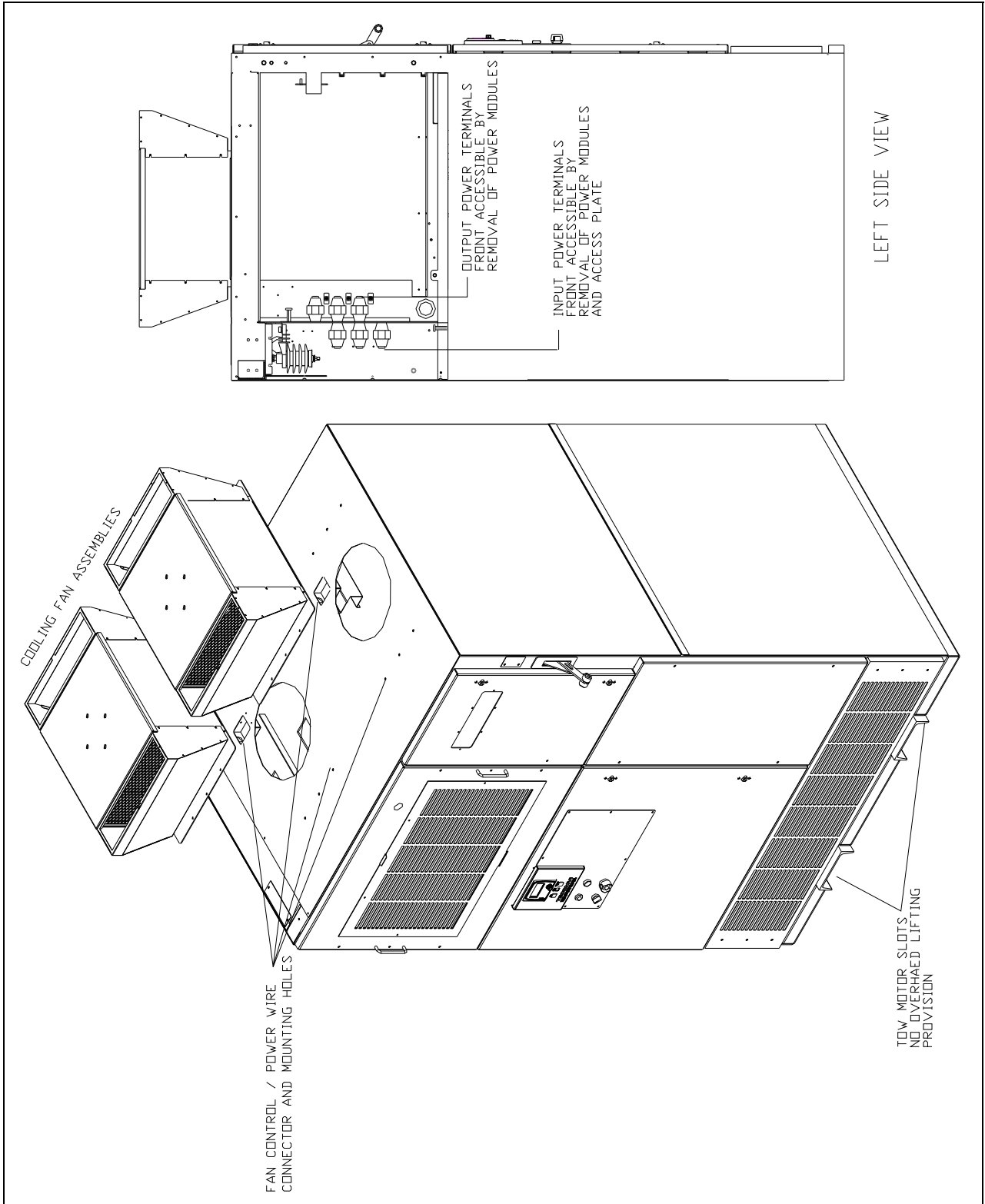
1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reconnect power cables ACL, P, C & N.
9. Reinstall AC neutral bus.
10. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.



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## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A4 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B4 module lifting and installation

**WARNINGS**

Inverter cabinet is top heavy. Cabinet must be anchored to floor before withdrawing power modules to prevent tipping.

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GCI6721G055 and a lifting device rated 350 lbs minimum for removal and installation of modules.

**Power Module Removal**

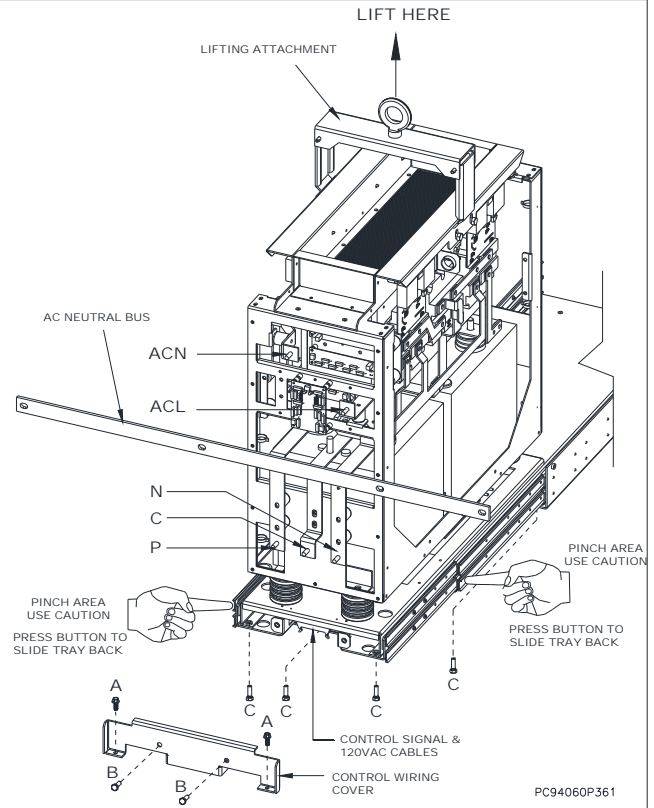
1. Disconnect and remove AC neutral bus.
2. Disconnect power cables ACL, P, C & N.
3. Remove control wiring cover with two "A" & two "B" bolts
4. Disconnect control signal cable and 120VAC supply cable from module.

**Power Module Removal (cont'd)**

5. Pull slide tray out until slides lock.
6. Remove four "C" bolts which secure module to tray.
7. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

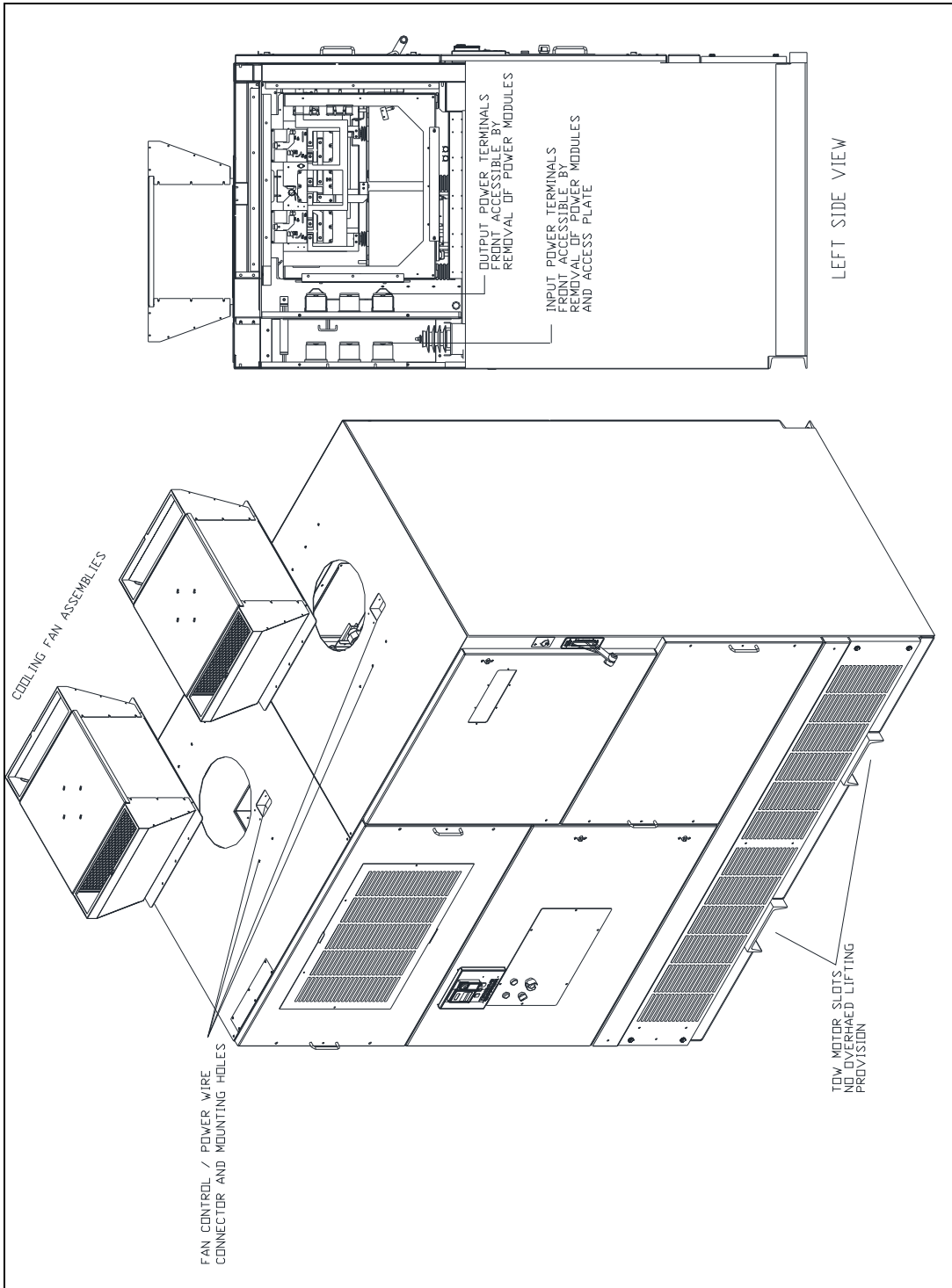
1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reconnect control signal cable and 120VAC supply cable to module connectors.
6. Reinstall control wiring cover and secure with two "A" & two "B" bolts.
7. Reconnect power cables ACL, P, C & N.
8. Reinstall AC neutral bus.
9. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.



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## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B4 drive lifting and installation



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B6S module lifting and installation

#### WARNINGS

Inverter cabinet is top heavy. Cabinet must be anchored to floor before withdrawing power modules to prevent tipping.

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

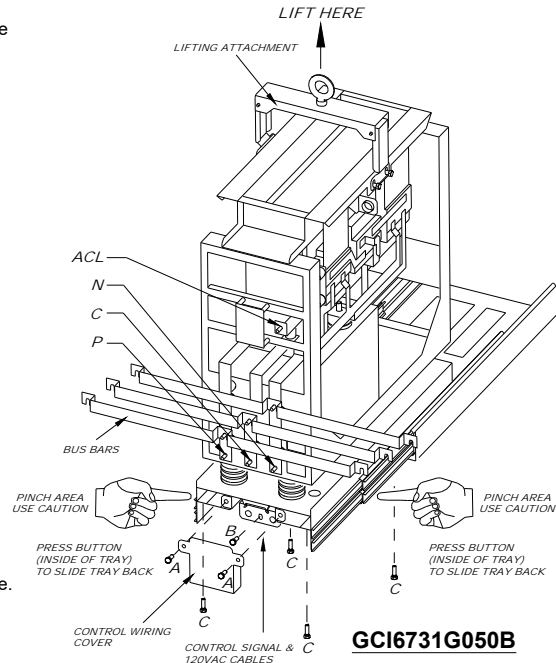
GCI6731G050B power modules can only be used in the upper power module position. GCI6721G050B2 power modules can be used in the upper or lower module position. In the upper position GCI6721G050B2 will have 4 bus connections and no 24C connection.

Use module lifting attachment GCI6721G055 and a lifting device rated 350 lbs minimum for removal and installation of modules.

#### GCI6731G050B

##### Upper Power Module Removal

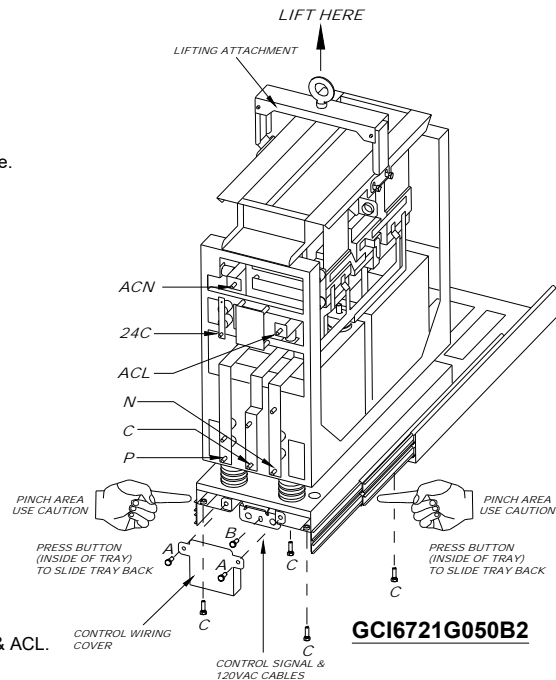
1. Disconnect power cables ACL, P, C & N (P, C & N on left module only).
2. Disconnect and remove bus bars P, C & N.
3. Remove control wiring cover (two "A" bolts).
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".
6. Pull slide tray out until slides lock.
7. Remove four "C" bolts which secure module to tray.
8. Using module lifting attachment and lifter, lift module from tray.



#### GCI6721G050B2

##### Lower Power Module Removal

1. Disconnect power cables ACN, 24C, P, C, N & ACL.
2. Remove control wiring cover (two "A" bolts).
3. Disconnect control signal cable and 120VAC supply cable from module.
4. Free slide tray by removing bolt "B".
5. Pull slide tray out until slides lock.
6. Remove four "C" bolts which secure module to tray.
7. Using module lifting attachment and lifter, lift module from tray.



#### Power Module Installation

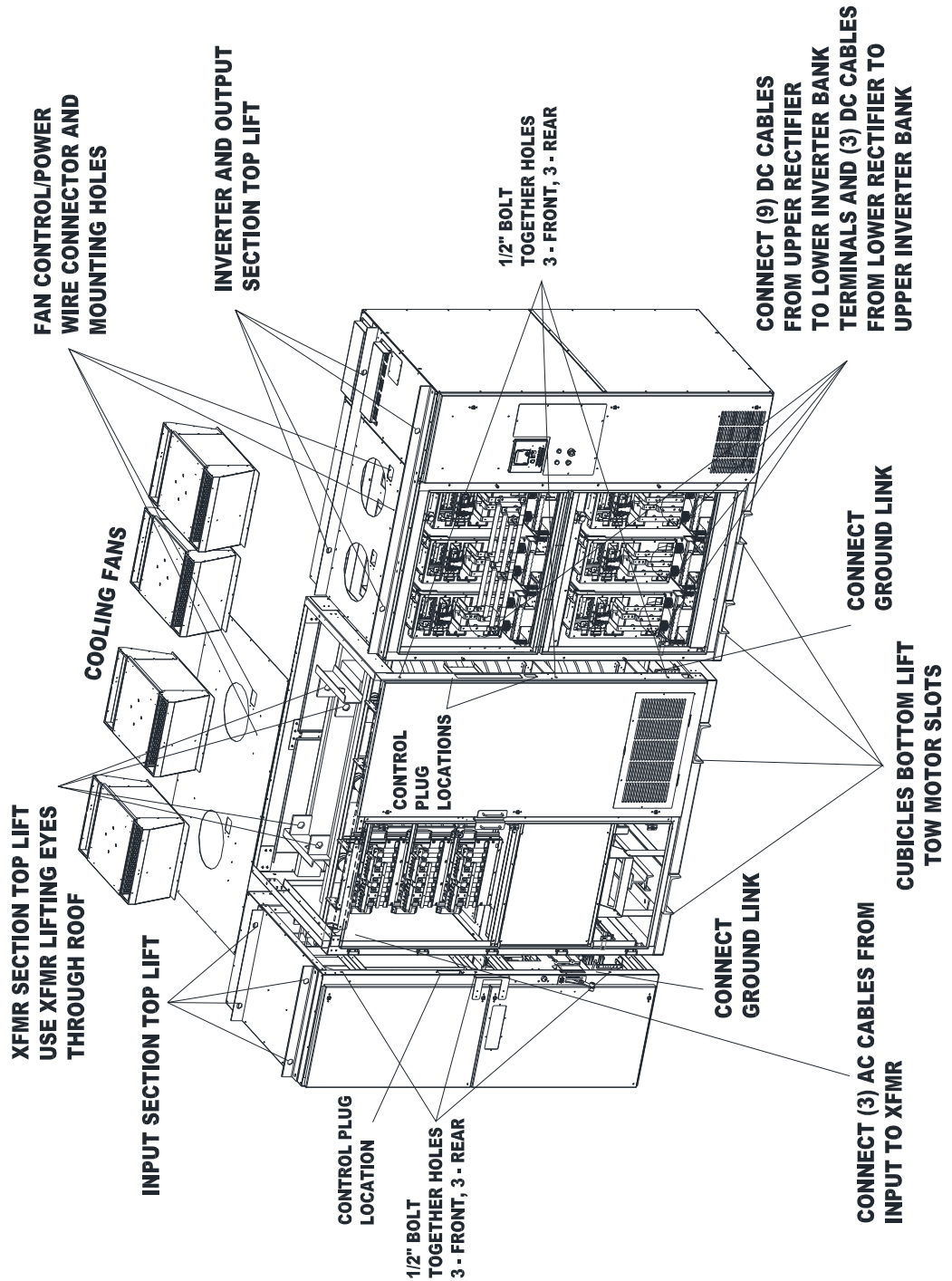
1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment. (Use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Upper Power Module: Reinstall bus bars P, C & N.
9. Upper Power Module: Reconnect power cables ACL, P, C & N (P, C & N on middle module only).
10. Lower Power Module: Reconnect power cables ACN, 24C, P, C, N & ACL.
11. Torque all power connections (5/16-18 hardware) to 10-15 ft-lbs.

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## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B6S drive lifting and assembly

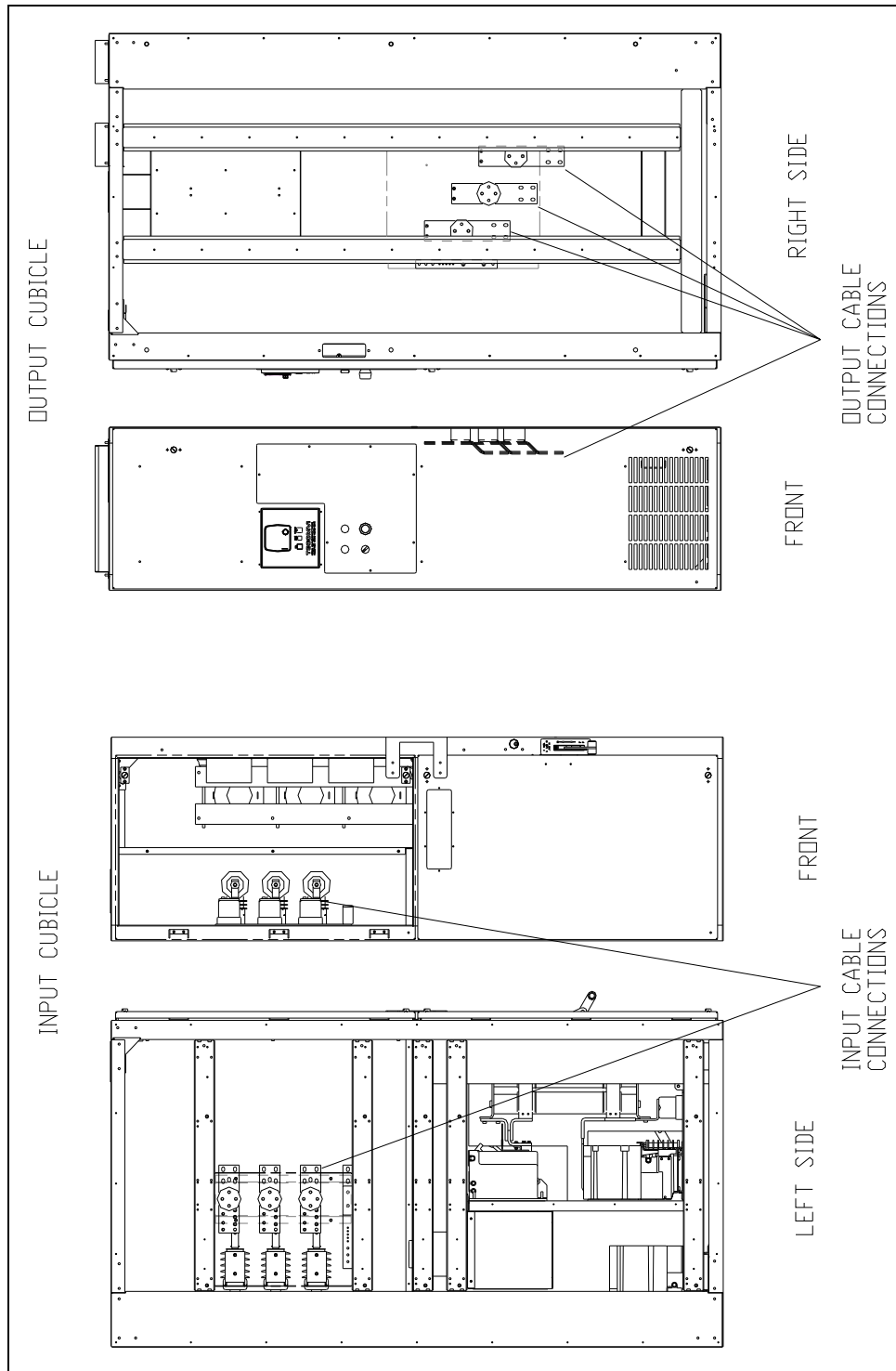
TO MOVE THE SECTIONS, USE A FORKLIFT OF ADEQUATE CAPACITY. LIFT FROM THE SLOTS IN THE CHANNEL BASE ON THE TRANSFORMER AND INVERTER-OUTPUT SECTIONS. THE INPUT SECTION IS SHIPPED WITH 4 X 4 POSTS ATTACHED TO THE BOTTOM.  
 NOTE: OVERHEAD LIFTING PROVISIONS ARE ALSO PROVIDED AS SHOWN. AFTER THE SECTIONS ARE IN PLACE BOLT TOGETHER WITH 1/2" HARDWARE, THEN INSTALL AND WIRE THE FAN ASSEMBLIES.





## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B6S drive main terminal locations



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame C6S module lifting and installation

#### WARNINGS

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

#### GCI6732G050A Power Module Disconnection

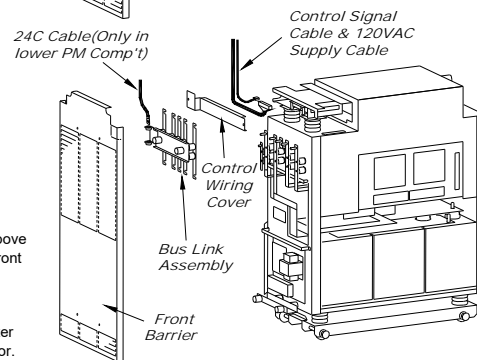
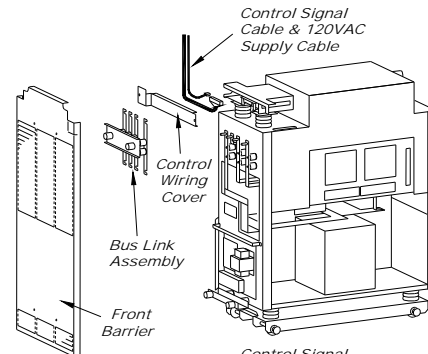
1. Remove front barrier (four bolts).
2. Loosen eight nuts and remove bus link assembly by sliding sideways and off.
3. Remove control wiring cover (two bolts)
4. Disconnect control signal cable and 120VAC supply cable from module
5. GCI6732G050 can be used in the upper PM compartment only.

#### GCI6722G050A2 Power Module Disconnection

1. Remove front barrier (four bolts).
2. Disconnect 24C terminal cable and slide out of bushing bracket.
3. Loosen ten nuts and remove bus link assembly by sliding sideways and off.
4. Remove control wiring cover (two bolts)
5. Disconnect control signal cable and 120VAC supply cable from module.
6. GCI6722G050A2 may be used in the upper or lower PM compartment. When used in the upper compartment, there will be 4 links in the bus link assembly and no 24C cable connection.

#### Power Module Removal

1. Use Only Lifter PC10480P910 for removal & installation of modules
2. Position lifter squarely in front of cubicle. Raise tray of lifter PC10480P910 above Power Module support pan. Lower tray, inserting pins or tabs into holes in front edge of support pan. (A) Set truck brake.
3. Withdraw Power Module onto lifter tray. Secure Power Module to tray by connecting chains to Power Module frames (B).
4. Raise tray to until tabs or pins are clear of support pan edge. Slowly move lifter back, away from cubicle. Use crank to slowly lower Power Module to the floor.



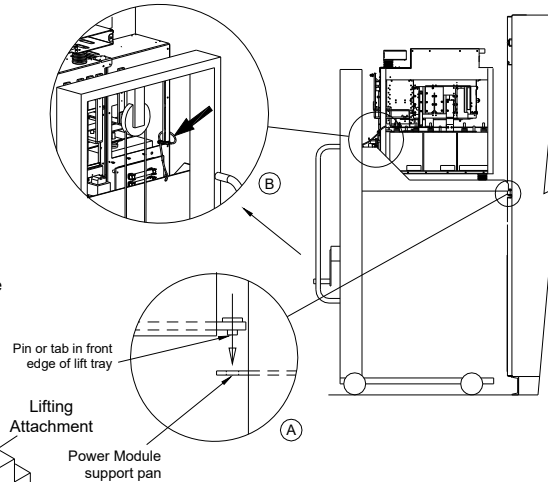
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#### Power Module Installation

1. Lower lifter tray to ground. Roll Power Module onto tray. Secure with chains.(B)
2. Raise tray above Power Module support pan. Lower tray, inserting tabs or pins into holes in front edge of support pan. (A) Set truck brake.
3. Unlatch chains. Roll Power Module from truck onto enclosure rails.

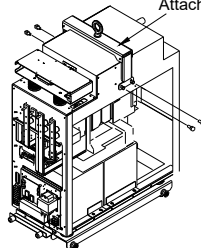
#### Power Module Reconnection

1. Reverse the procedure followed during disconnection and removal of power module.
2. Ensure that control signal cable, 120VAC supply cable and 24C cable, if required, are properly reconnected.
3. Reinstall all hardware previously removed.
4. Torque bus link connections (5/16-18 hdwr) to 10-15 ft-lbs.



#### Lifting PMs Outside the Cubicle

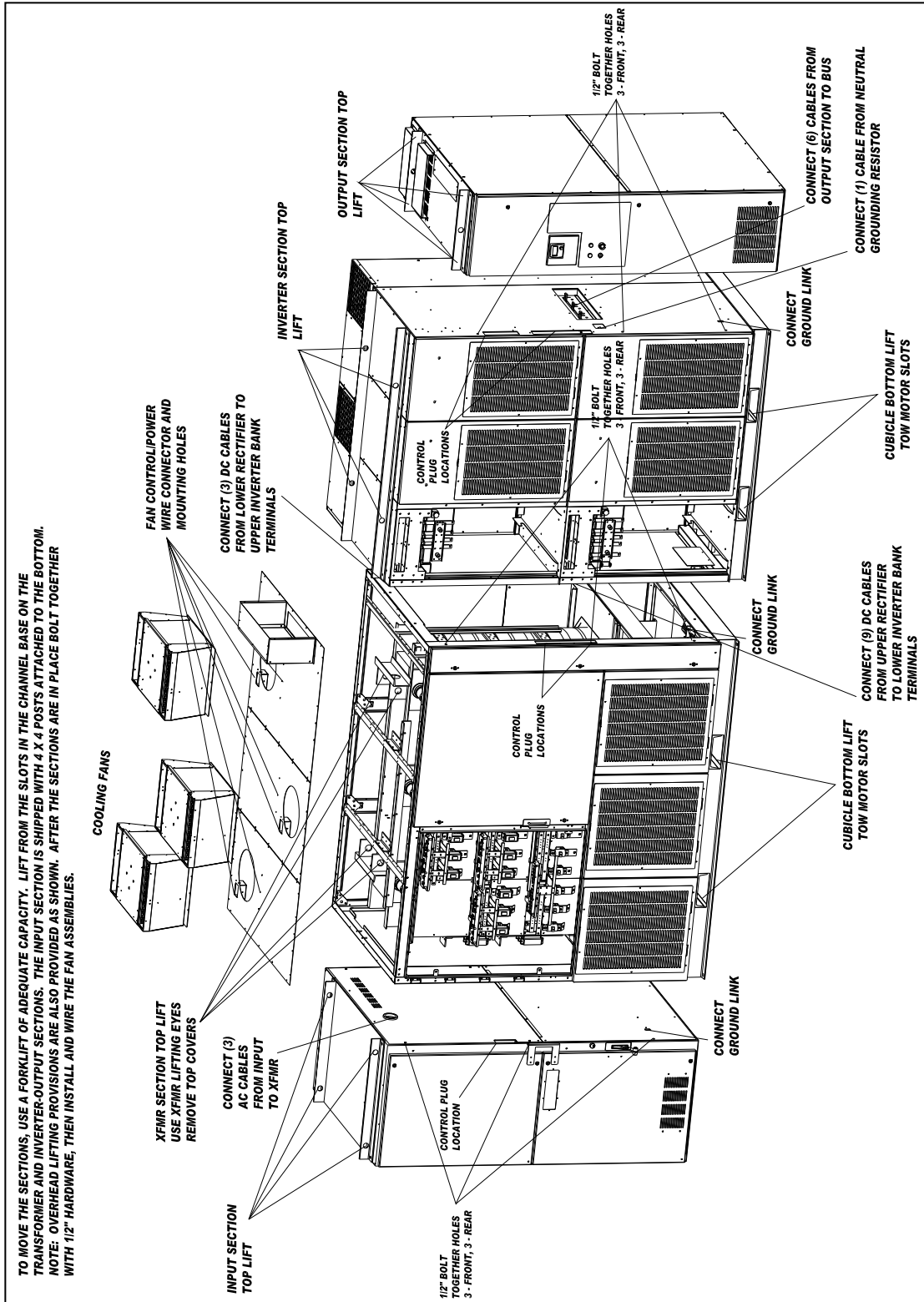
For lifting Power Module GCI673FG050 use Lifting Attachment GCI6722G055 and a lifting device rated at 1000 lbs. or more. Secure Lifting Attachment to Power Module with (4) 5/16-18 Bolts.



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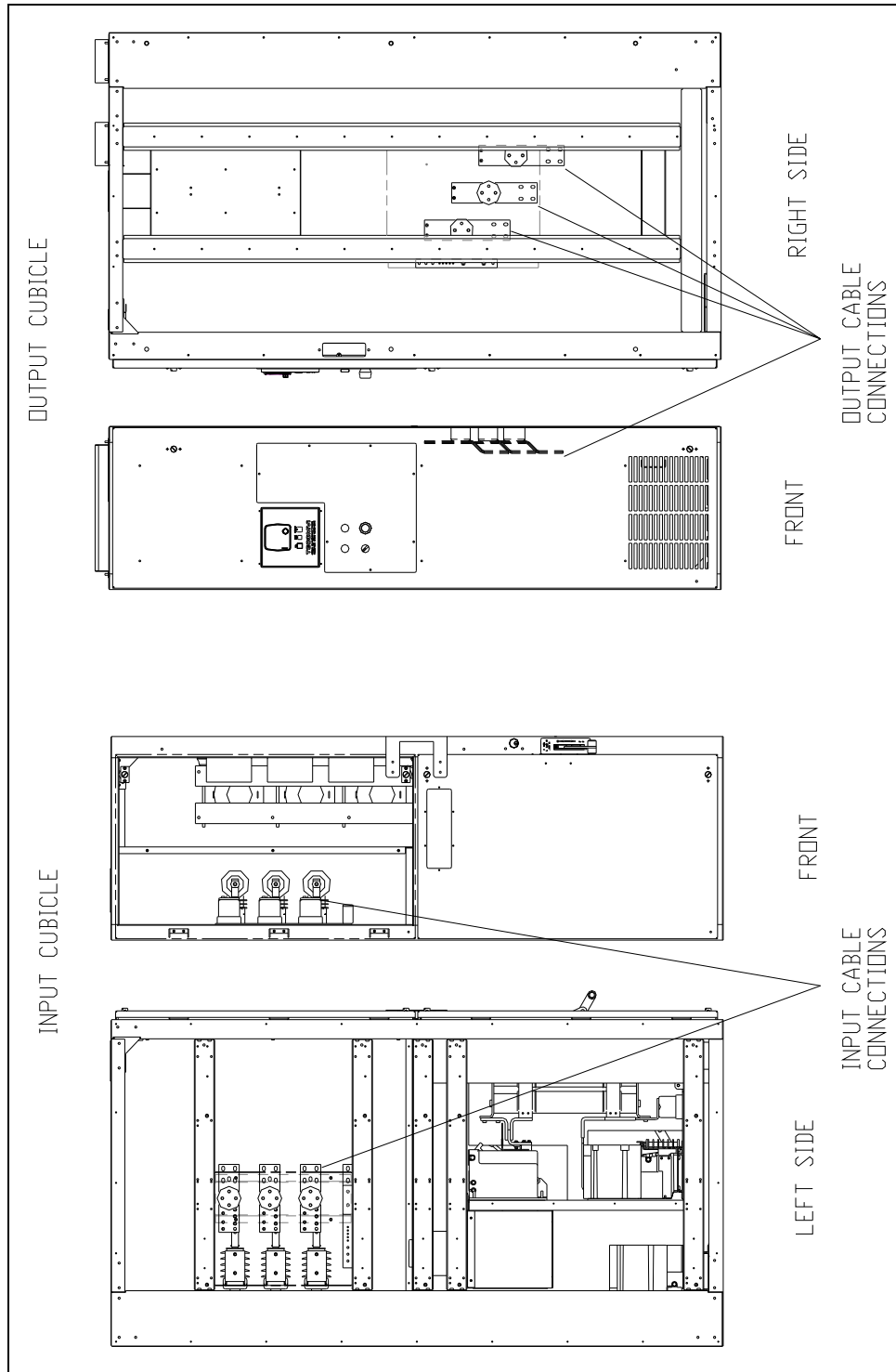
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame C6S drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame C6S drive main terminal locations



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame D6S module lifting and installation

**WARNINGS**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use Lift PC-10480P910 for removal & installation of modules

GC16733G050  
Can only be used in Upper Comp't.

GC16723G050A2  
Can be used in Upper or Lower Comp't.  
(with no ACN or 24C connection in the lower position)

**Power Module Removal**

1. After capacitor discharge, open upper Power Module cover.
2. Disconnect Control Cable from PCB 'A' and lay in wireway above Power Module (PM).
3. Disconnect Control Power Cable 'B' lay in wireway above PM.
4. In the Upper Comp't; Remove (4) bolts 'C' from bus stabs P, C, N & ACL.
5. In the Lower Comp't; Remove 24C Cable 'C1' from 24C terminal and lay in wireway above PM.
6. Remove (5) bolts 'C2' from bus stabs ACN, P, C, N & ACL.
7. In the Upper & Lower Comp't's; Remove (1) bolt 'D' from back of Power Module cableway.
8. Raise tray of lifter PC-10480P910 above Power Module support pan. Lower tray inserting tray pins into holes in front edge of support pan. (E) Set truck brake.
9. Withdraw Power Module by handles onto tray. Secure Power Module to tray by connecting chains to Power Module handles.(F)
10. Raise tray to until pins are clear of mounting pan. Slowly move lifter back away from cubicle. Use crane to slowly lower Power Module to the floor.

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**Power Module Installation**

1. Lower lifter tray to ground. Roll Power Module onto tray. Secure with chains.(F)
2. Raise tray above Power Module support pan. Lower tray, inserting pins into holes in front edge of support pan. (E) Set truck brake.
3. Unlatch chains. Roll Power Module by handles from truck onto enclosure rail until enclosure and Power Module bus stabs touch.
4. Install (1) bolt 'D' at back of cableway. Unlock, remove truck.
5. Install (4 or 5) bolts 'C7/C2' through bus stabs ACN, P, C, N & ACL. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.
6. Connect 24C Cable to 24C terminal as shown at 'C1'.
7. Connect Control Power Cable from wireway as shown at 'B'.
8. Connect Control Cable from wireway to PCB as shown at 'A'.
9. Close upper Power Module cover. Secure with 2 bolts.
10. Replace outside filter cover.

**Lifting Attachment**

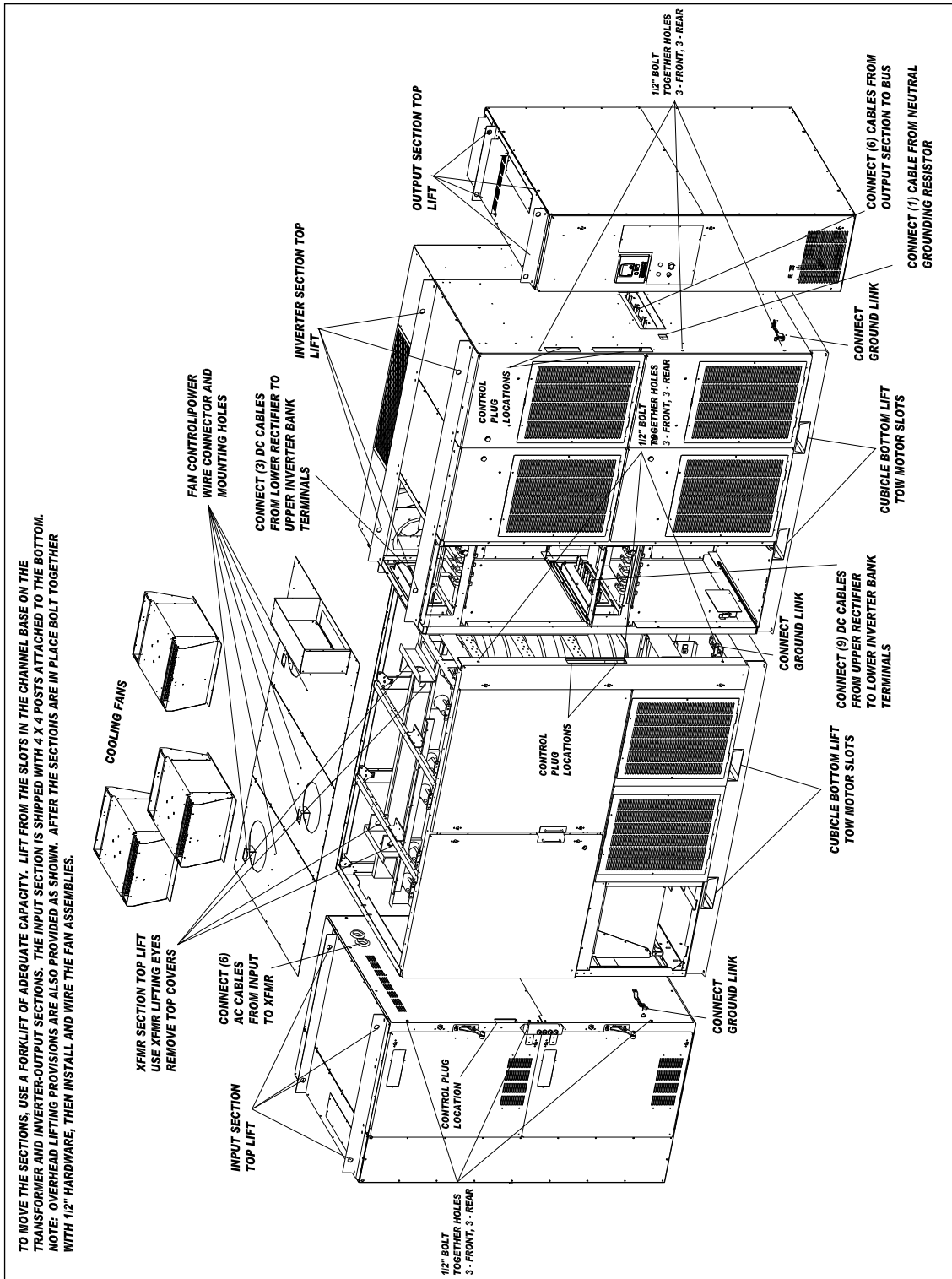
For lifting the Power Module after it is out of the Cubicle use Lifting Attachment GC16723G054 and a lifting device rated at 1000 lbs. or more.

Secure Lifting Attachment to Power Module with (4) 1/2-13 Bolts.

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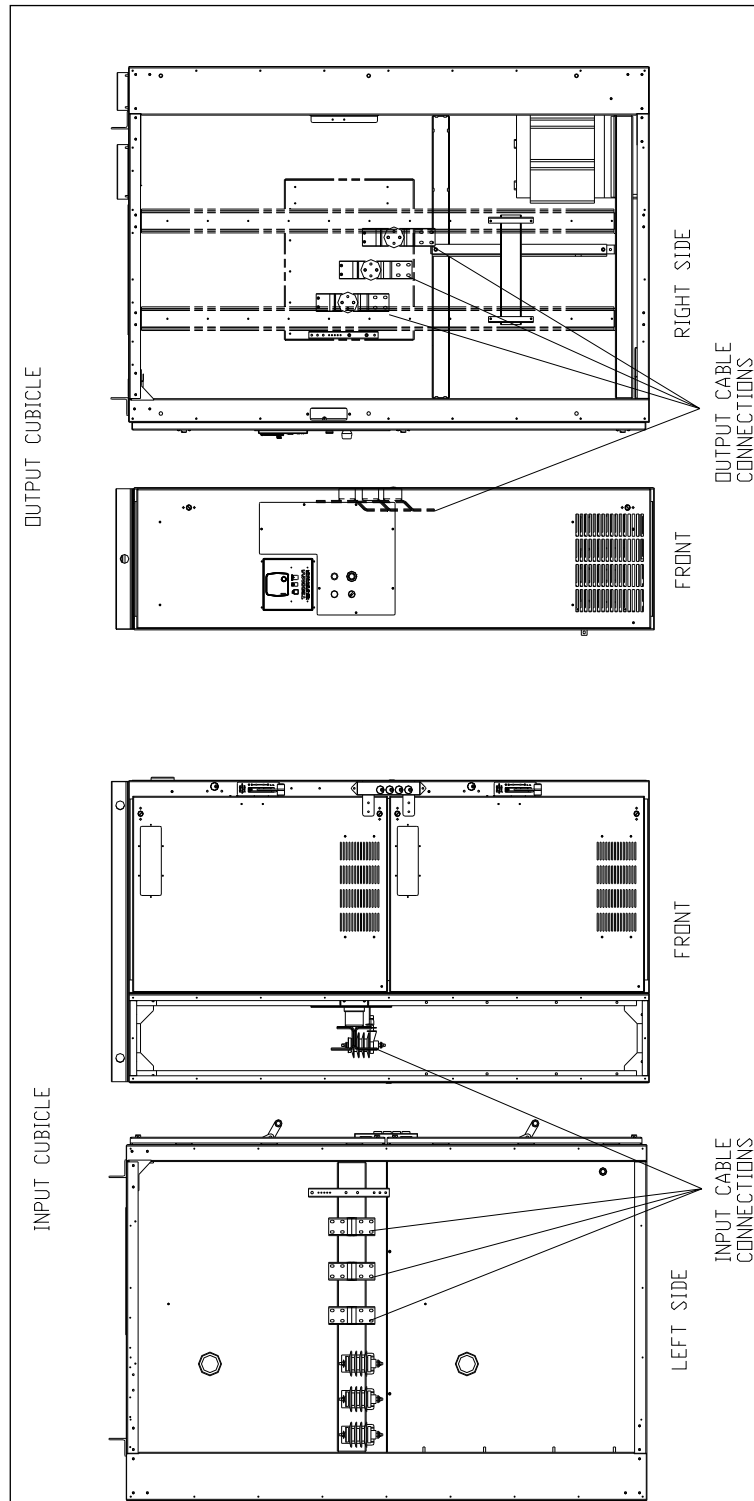
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame D6S drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame D6S drive main terminal locations



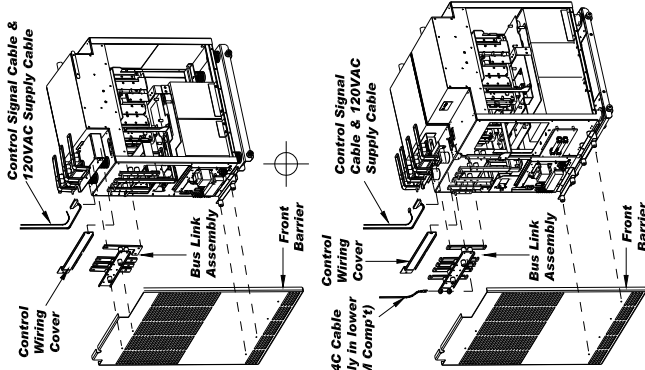
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F6S & F6S+ module lifting and installation

**WARNINGS**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.



**GC1673FG050 Power Module Disconnection**

1. Remove front barrier (four bolts).
2. Loosen four top nuts, remove bottom four nuts and remove bus link assembly.
3. Remove control wiring cover (two bolts)
4. Disconnect control signal cable and 120VAC supply cable from module
5. GC1673FG050 can be used in the upper PM compartment only.

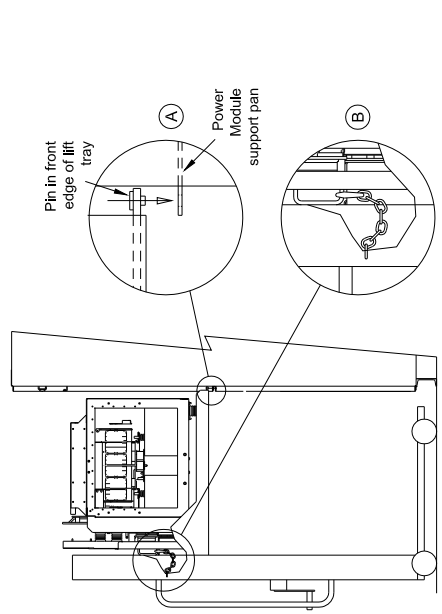
**GC16724G050A2 Power Module Disconnection**

1. Remove front barrier (six bolts).
2. Disconnect 24C terminal cable and slide out of bushing bracket.
3. Loosen ten nuts and remove bus link assembly by sliding sideways and off.
4. Remove control wiring cover (two bolts)
5. Disconnect control signal cable and 120VAC supply cable from module.
6. GC16724G050A2 may be used in the upper or lower PM compartment. When used in the upper compartment, there will be 4 links in the bus link assembly and no 24C cable connection.

**Power Module Removal**

1. Use Only Lifter PC10480P910 for removal & installation of modules
2. Position lifter squarely in front of cubicle. Raise tray of lifter PC10480P910 above Power Module support pan. Lower tray inserting tray pins into holes in front edge of support pan. (A) Set truck brake.
3. Withdraw Power Module onto lifter tray. Secure Power Module to tray by connecting chains to Power Module handles (B), one handle for GC1673FG050, two for GC16724G050A2.
4. Raise tray to until pins are clear of support pan. Slowly move lifter back, away from cubicle. Use crank to slowly lower Power Module to the floor.

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**Power Module Installation**

1. Lower lifter tray to ground. Roll Power Module onto tray. Secure with chains.(B)
2. Raise tray above Power Module support pan. Lower tray, inserting pins into holes in front edge of support pan. (A) Set truck brake.
3. Unlatch chains. Roll Power Module from truck onto enclosure rails.

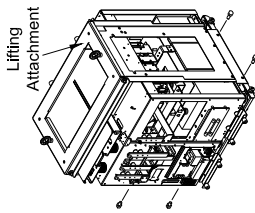
**Power Module Reconnection**

1. Reverse the procedure followed during disconnection and removal of power module.
2. Ensure that control signal cable, 120VAC supply cable and 24C cable, if required, are properly reconnected.
3. Reinstall all hardware previously removed.
4. Torque bus link connections (5/16-18 hdwr) to 10-15 ft-lbs.

**Lifting PMs Outside the Cubicle**

For lifting Power Module GC1673FG050 use Lifting Attachment GC16722G055 and a lifting device rated at 1000 lbs. or more. Secure Lifting Attachment to Power Module with (4) 5/16-18 Bolts.

For lifting Power Module GC16724G050A2 use Lifting Attachment GC16724G055 and a lifting device rated at 1000 lbs. or more. Secure Lifting Attachment to Power Module with (4) ½ -13 Bolts.

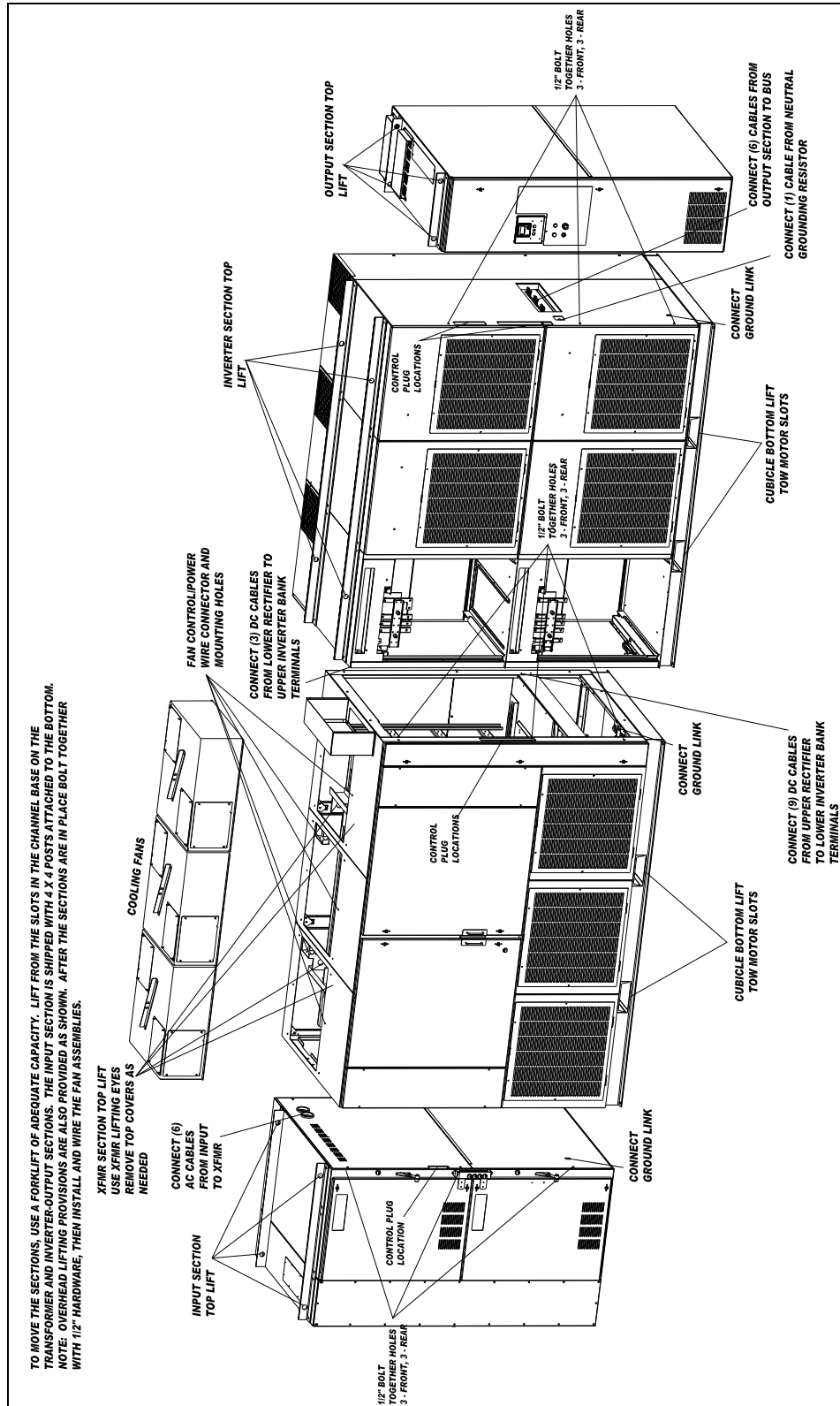


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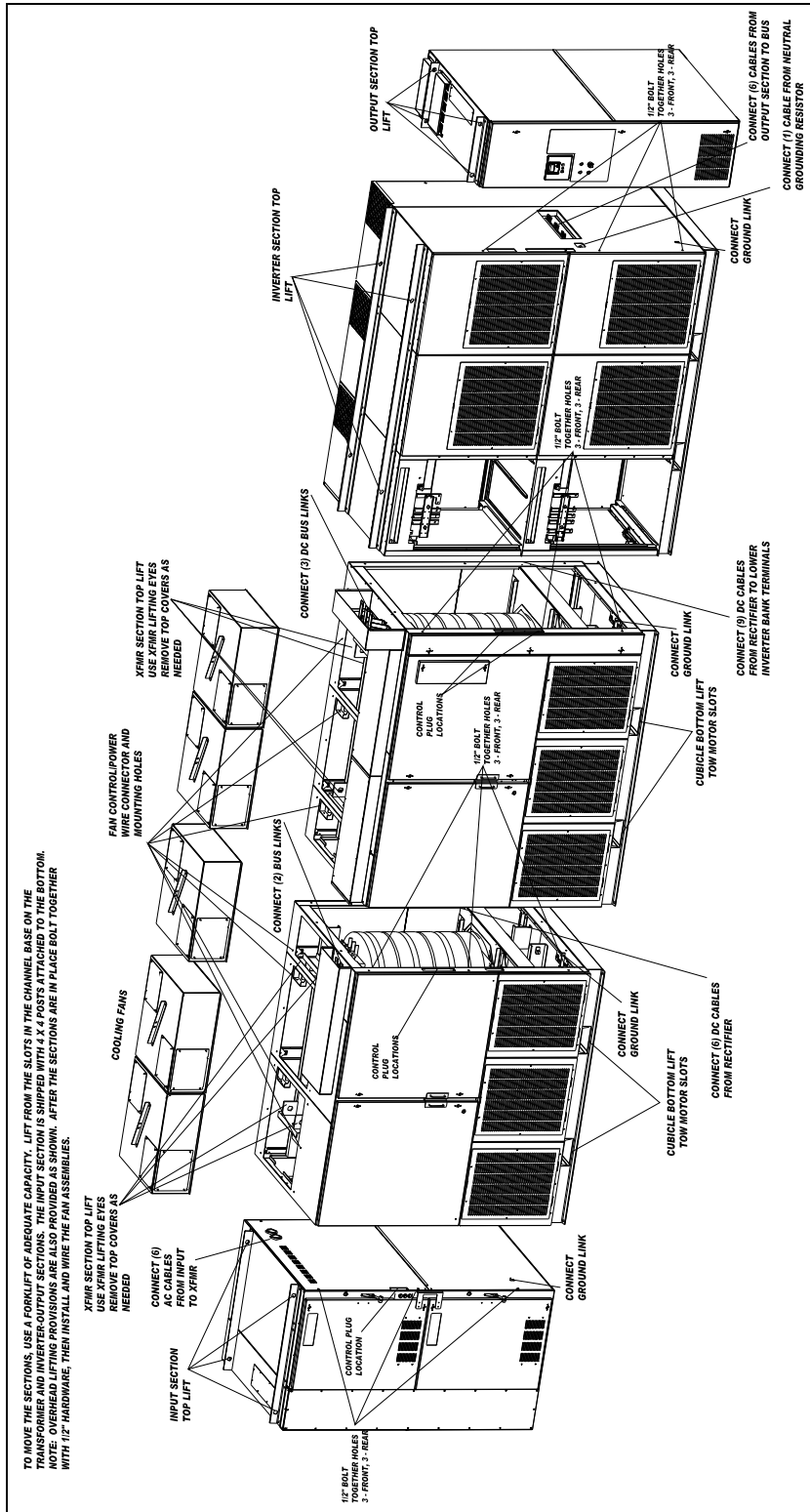
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F6S drive lifting and assembly



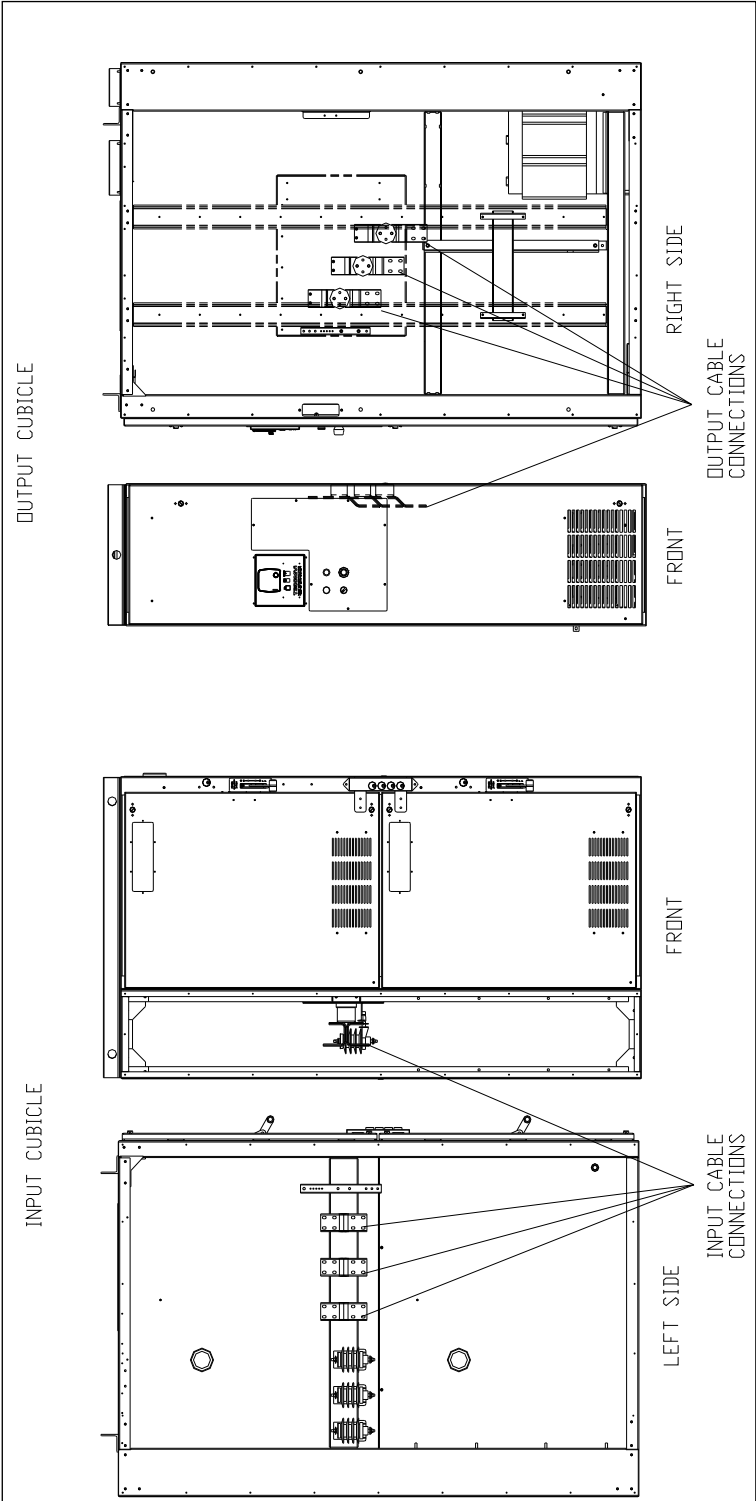
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F6S+ drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F6S & F6S+ drive main terminal locations



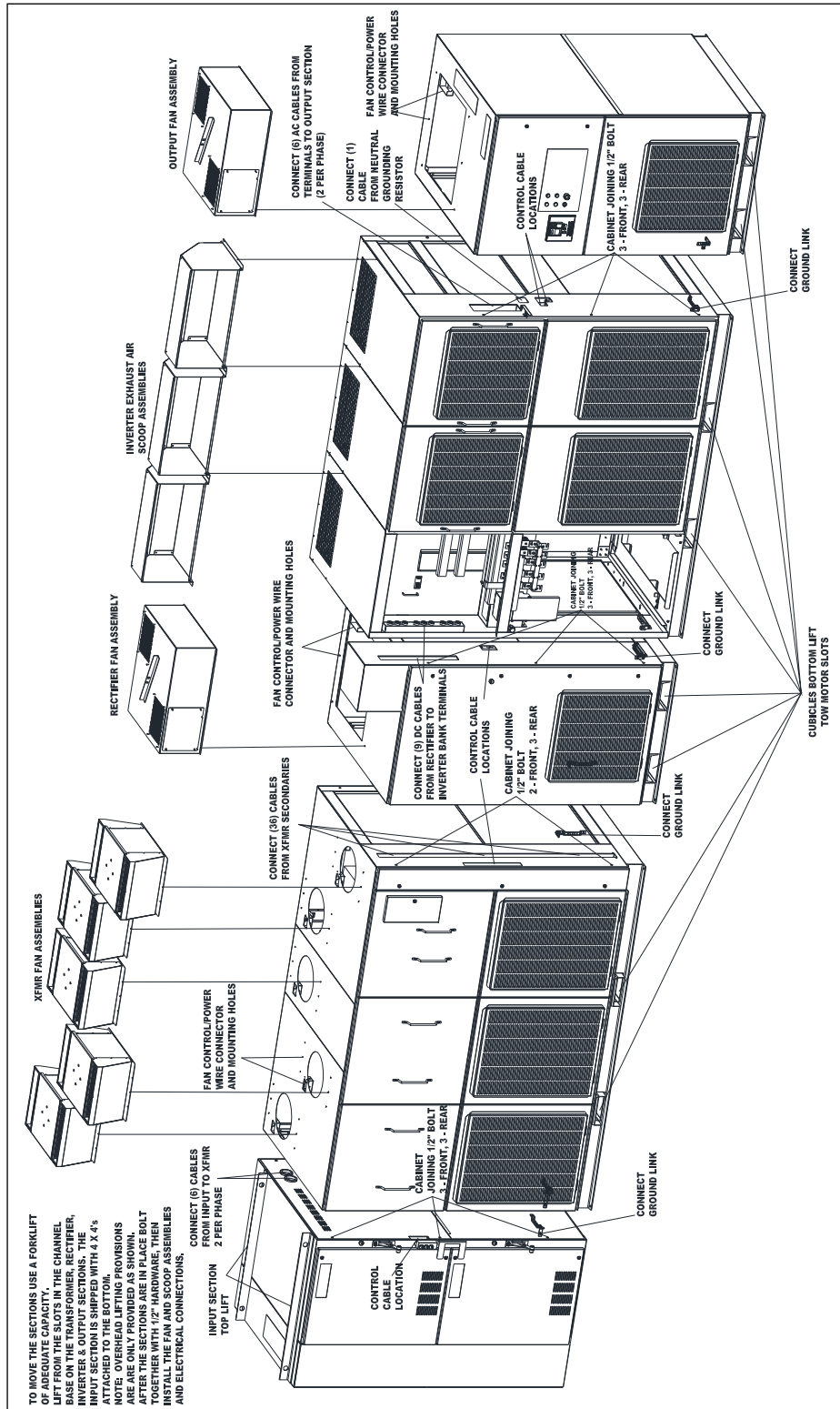
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F7 module lifting and installation

|  |   |
|--|---|
|  | <p><b>POWER MODULE DISCONNECTION</b></p> <p><b>Power Module Disconnection</b></p> <ol style="list-style-type: none"> <li>1. Remove front barrier (four bolts).</li> <li>2. Loosen ten nuts &amp; remove bus link assembly by sliding sideways and off.</li> <li>3. Loosen four bolts, pivot control wiring cover 90° &amp; tighten two bolts connecting cover to duct.</li> <li>4. Disconnect control signal cable &amp; 120VAC supply cable from module.</li> <li>5. Loosen four nuts &amp; move the Front PM stoppers inwards to disengage.</li> </ol> <p><b>WARNINGS</b></p> <p>Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.</p> <p>Improper handling of the fiber optic cables &amp; connectors may cause drive failure due to problems transmitting signals.</p> <p>Take care not to disturb fiber optic cables when handling Power Module.</p> <p>Use Scissor Lift Truck provided for removal &amp; installation of Power Modules.</p>   |
|  | <p><b>POWER MODULE REMOVAL</b></p> <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>1. With the PM Pallet placed on top of the Scissor Lift Truck, align the PM Pallet with the front of cubicle.</li> <li>2. Using the Scissor Lift Truck, raise the PM Pallet not more than 1" above the PM Guide to clear the two Allen bolt heads and then place the PM Pallet on top of the PM Guide so that the Allen Bolts are inserted into the holes of the PM Pallet's rear angle as shown above.</li> <li>3. Roll Power Module onto the PM Pallet until the PM Pallet Latch and PM Latches engage.</li> <li>4. Raise the PM Pallet with the Power Module not more than 1" above the PM Guide to clear the two Allen bolt heads and slowly move the Scissor Lift Truck away from the enclosure and place the PM Pallet on the floor.</li> </ol> <p><b>POWER MODULE REINSTALLATION</b></p> <p><b>Power Module Reinstallation</b></p> <ol style="list-style-type: none"> <li>1. Reverse the procedure followed during disconnection and removal of Power Module.</li> <li>2. Ensure that the Rear PM Stopper is engaged before engaging the Front PM Stoppers.</li> <li>3. Ensure that control signal cable and 120VAC supply cable are properly reconnected.</li> <li>4. Reinstall all hardware previously removed.</li> <li>5. Torque bus link connections (5/16-18 hardware) to 10-15 ft-lbs.</li> </ol> <p>PCS4060P299</p> |

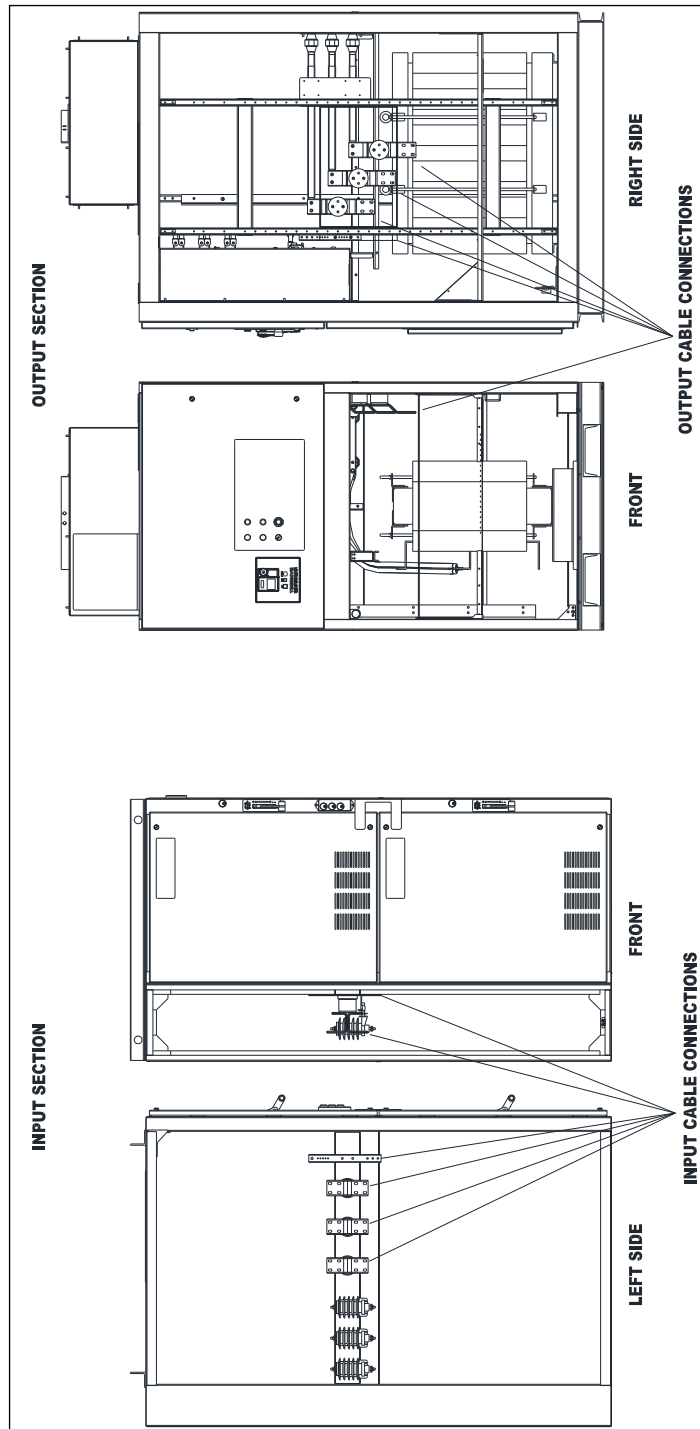
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F7 drive lifting and assembly



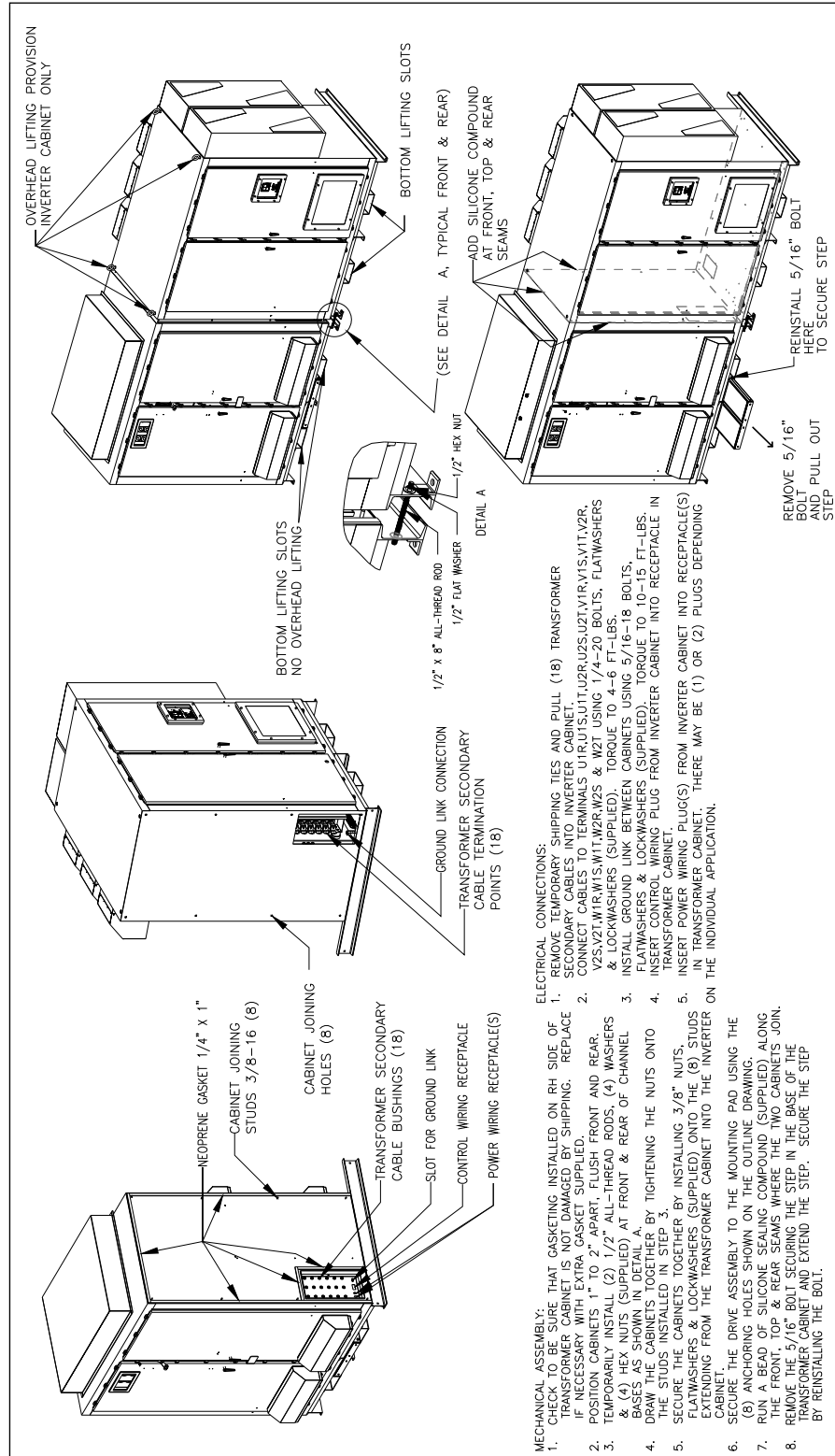
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame F7 drive main terminal locations



## DRIVE INSTALLATION DRAWINGS (cont'd)

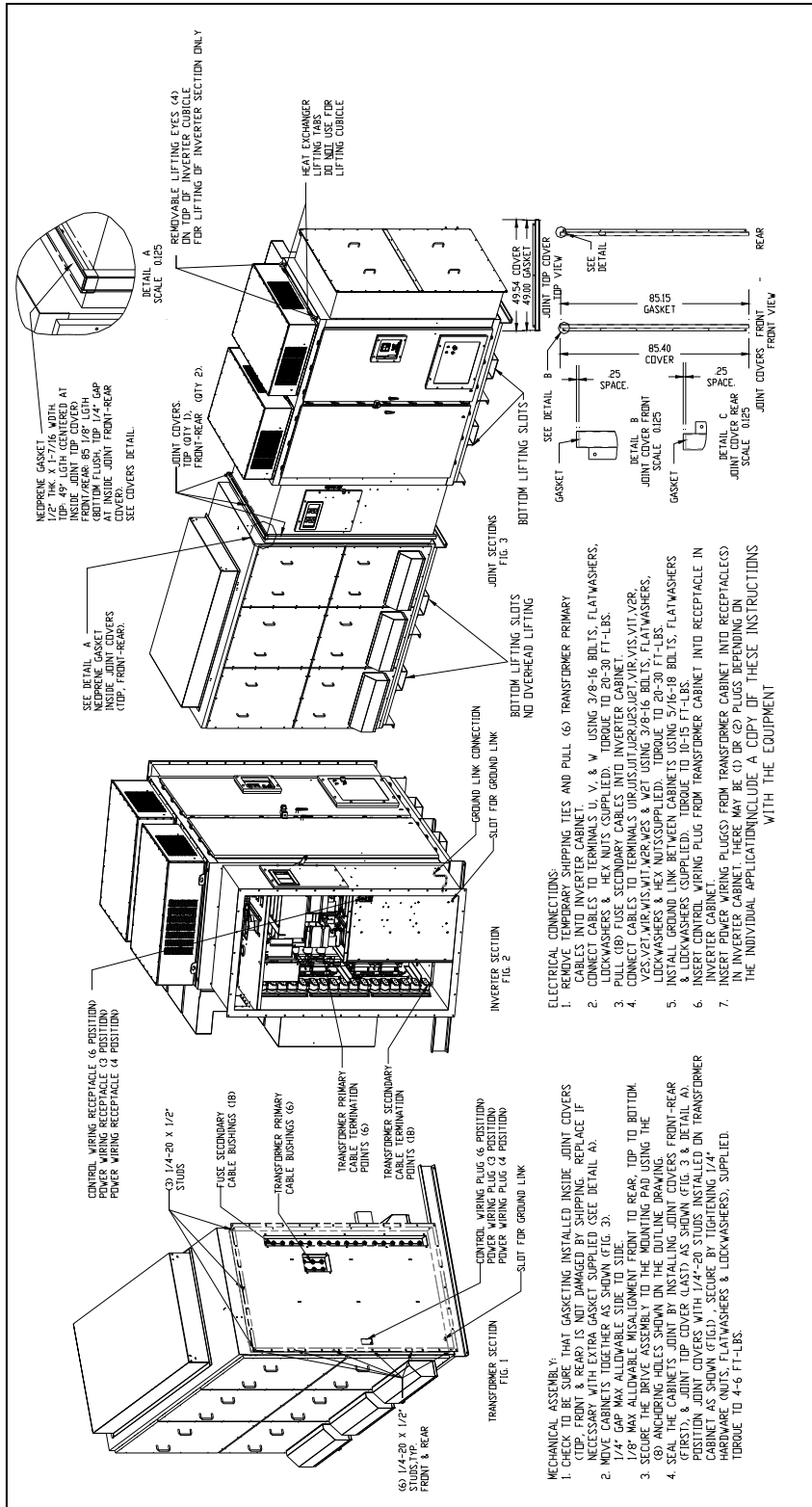
### Frame MTX-15 drive lifting and assembly



- MECHANICAL ASSEMBLY:**
- CHECK TO BE SURE THAT GASKETING INSTALLED ON RH SIDE OF TRANSFORMER CABINET IS NOT DAMAGED BY SHIPPING. REPLACE IF NECESSARY WITH EXTRA GASKET SUPPLIED.
  - POSITION CABINETS 1" TO 2" APART, FLUSH FRONT AND REAR.
  - TEMPORARILY INSTALL (2) 1/2" ALL-THREAD RODS, (4) WASHERS & (4) HEX NUTS (SUPPLIED) AT FRONT & REAR OF CHANNEL BASES AS SHOWN IN DETAIL A.
  - DRAW THE CABINETS TOGETHER BY TIGHTENING THE NUTS ONTO THE STUDS INSTALLED IN STEP 3.
  - SECURE THE CABINETS TOGETHER BY INSTALLING 3/8" NUTS, WASHERS & LOCKWASHERS (SUPPLIED) ONTO THE STUDS EXTENDING FROM THE TRANSFORMER CABINET INTO THE INVERTER CABINET.
  - SECURE THE DRIVE ASSEMBLY TO THE MOUNTING PAD USING THE (8) ANCHORING HOLES SHOWN ON THE OUTLINE DRAWING.
  - RUN A BEAD OF SILICONE SEALING COMPOUND (SUPPLIED) ALONG THE FRONT, TOP & REAR SEAMS WHERE THE TWO CABINETS JOIN.
  - REMOVE THE 5/16" BOLT SECURING THE STEP IN THE BASE OF THE TRANSFORMER CABINET AND EXTEND THE STEP. SECURE THE STEP BY REINSTALLING THE BOLT.
- ELECTRICAL CONNECTIONS:**
- REMOVE TEMPORARY SHIPPING TIES AND PULL (18) TRANSFORMER SECONDARY CABLES INTO INVERTER CABINET.
  - CONNECT CABLES TO TERMINALS U1R,U1S,U1T,U2R,U2S,U2T,V1R,V1S,V1T,V2R,V2S,V2T,W1R,W1S,W1T,W2R,W2S & W2T USING 1/4-20 BOLTS, FLATWASHERS & LOCKWASHERS (SUPPLIED). TORQUE TO 4-6 FT-LBS.
  - INSTALL GROUND LINK BETWEEN CABINETS USING 5/16-18 BOLTS, FLATWASHERS & LOCKWASHERS (SUPPLIED). TORQUE TO 10-15 FT-LBS.
  - INSERT CONTROL WIRING PLUG FROM INVERTER CABINET INTO RECEPTACLE IN TRANSFORMER CABINET.
  - INSERT POWER WIRING PLUG(S) FROM INVERTER CABINET INTO RECEPTACLE(S) IN TRANSFORMER CABINET. THERE MAY BE (1) OR (2) PLUGS DEPENDING ON THE INDIVIDUAL APPLICATION.

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame MTX-30 drive lifting and assembly





## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame MTX2-15 module lifting and installation

**REAR PARTIAL VIEW INVERTER**

Optional Utility Box Location

Chain Bucket

Wireway Tray

Front Barrier Bolt Locations

Lifting Attachment (GCI6825G054)

Optional Overhead, Trolley and Hoist

Control Signal Cable Connection

120VAC Supply Cable Connection

AC Input Cable Connections

Control Wiring Cover

AC Neutral Bus

AC Output Cable Connection

Power Module Mounting Nut Location

Levers

**WARNINGS**  
 Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.  
 Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

**Power Module Disconnection**  
 1. Remove front barrier (four bolts).  
 2. Disconnect six AC input cables and AC output cable.  
 3. Remove AC neutral bus (three bolts).  
 4. Remove control wiring cover (two bolts).  
 5. Disconnect control signal cable and 120VAC supply cable from power module. Insert cables inside the wireway tray to avoid damage.

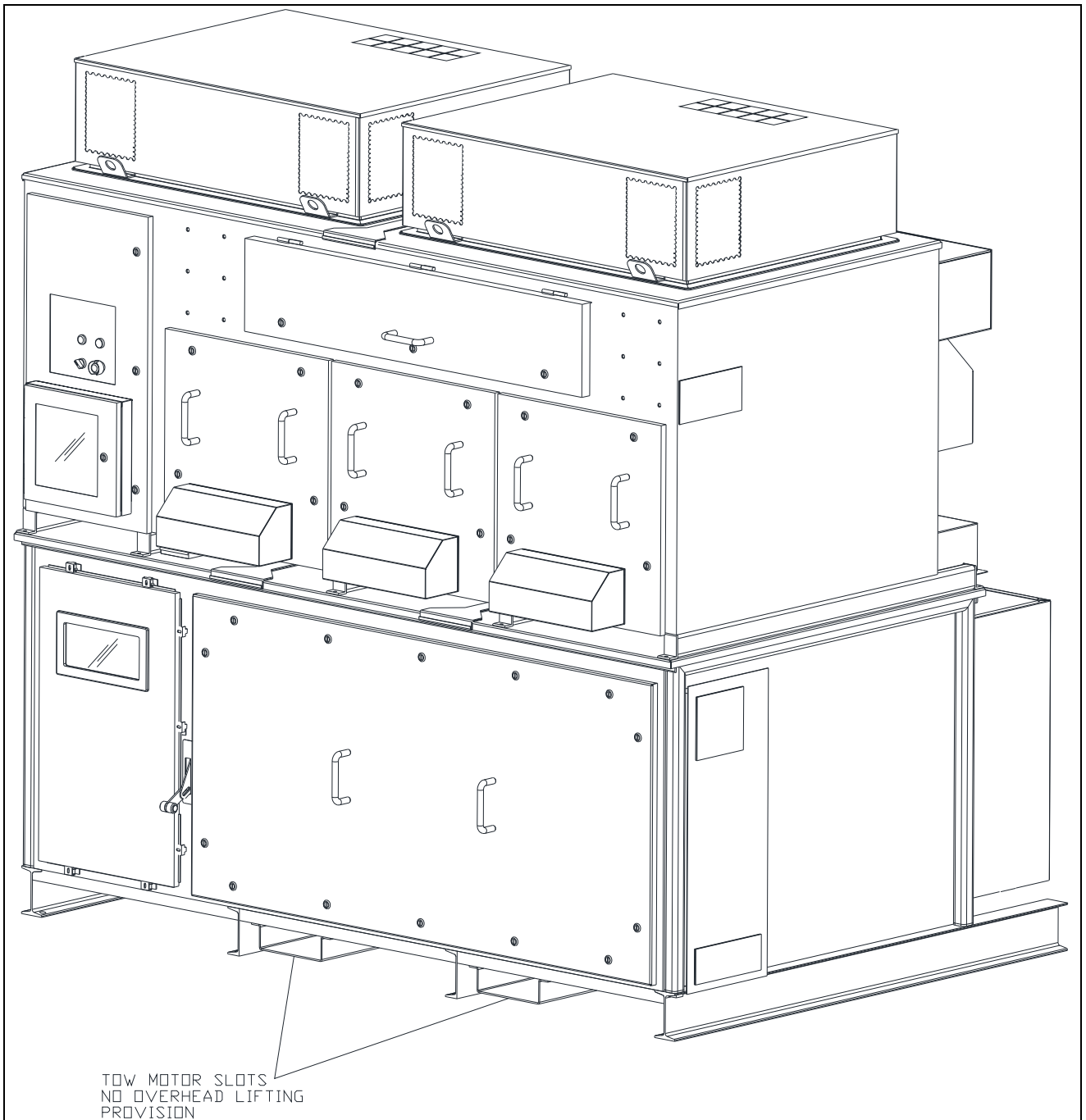
**Power Module Removal**  
 1. Release locking levers then slide power module forward until slides lock.  
 2. Remove six power module mounting nuts.  
 3. Attach lifting attachment (GCI6825G054) on module with 4 bolts.  
 4. If present use overhead lifting attachment with provided trolley, hoist & chain bucket, or use appropriate lifting device.  
 Note: Lifting attachment, trolley, hoist & chain bucket are stored in Utility box located in rear LH side of inverter cubicle.

**Power Module Reinstallation**  
 1. Reverse the procedure followed during disconnection and removal of power module.  
 2. Ensure that control signal cable and 120VAC supply cable are properly reconnected.  
 3. Reinstall all hardware previously removed.  
 4. Torque all electrical connections (5/16-18 hdwr) to 10-15 ft.-lbs.

FC84060P295 REV: 0

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame MTX2-15 drive lifting and assembly



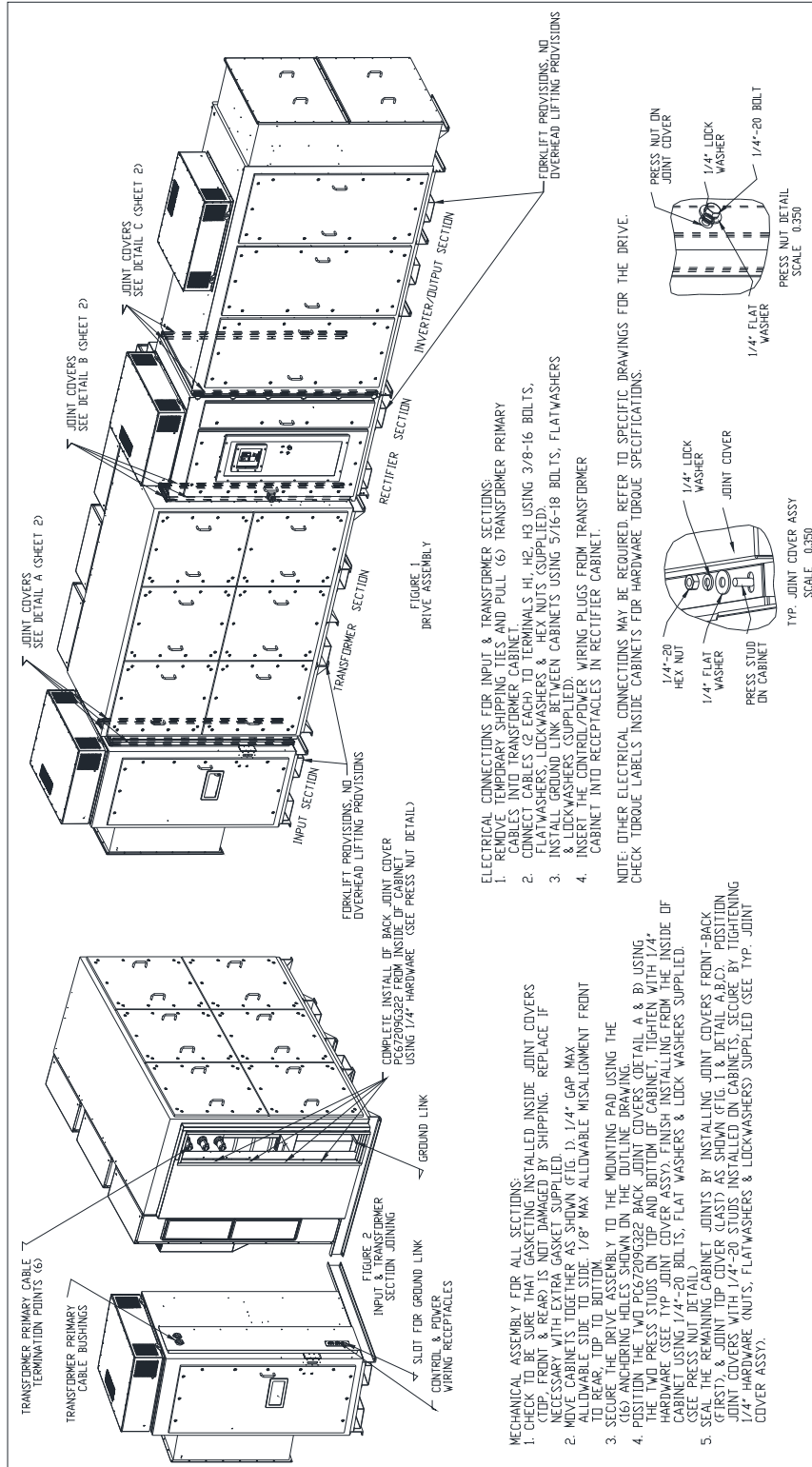
## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame MTX2-60 module lifting and installation

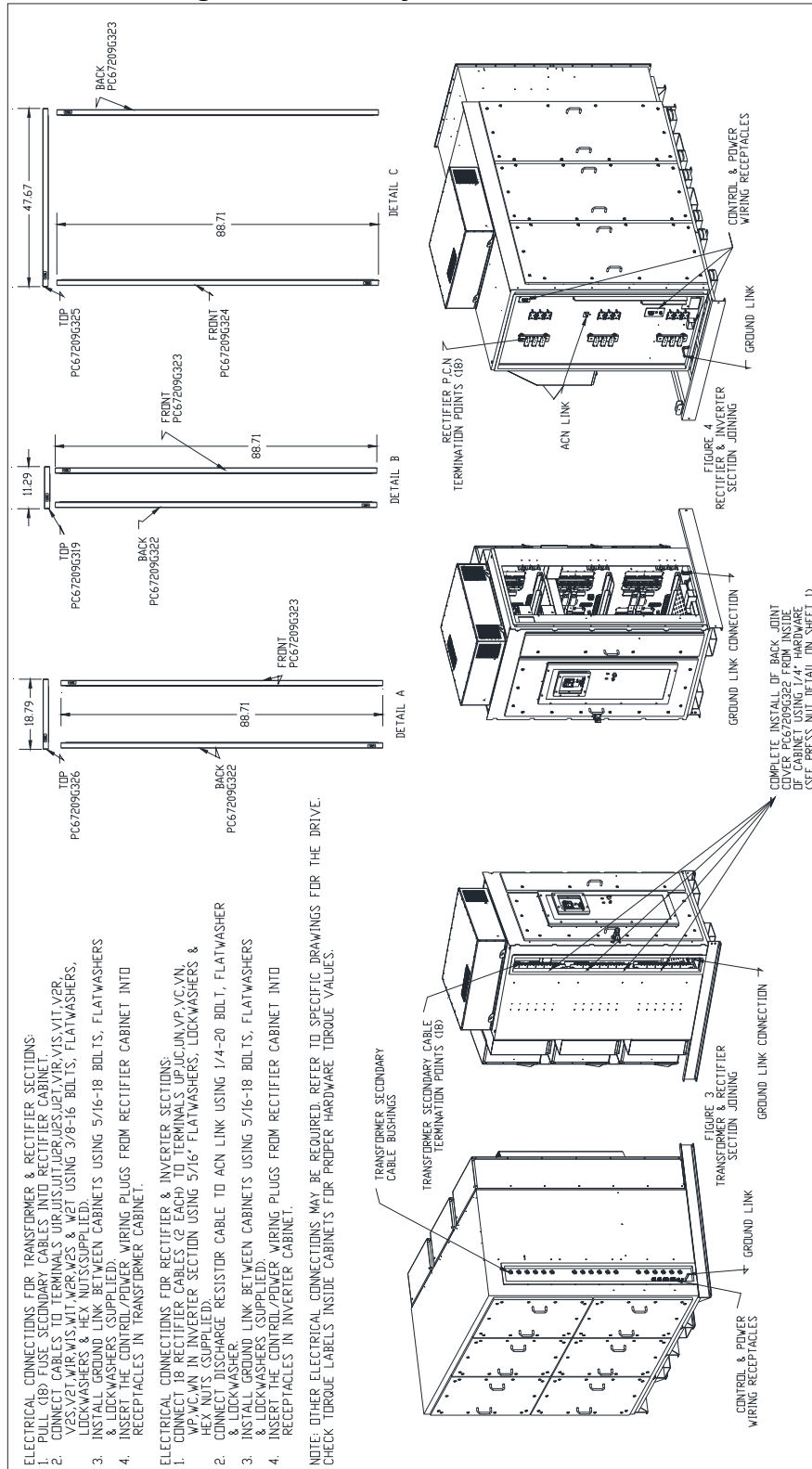
|  |   |
|--|---|
| <p>Lifting Provision (GCI6729G057) To Be Used With Maintenance Cubicle</p> <p>PM FRONT VIEW</p>  | <p><b>Assembly</b><br/>GCI6729G057</p> <p>Insert forklift forks into the rectangular holes of the lifter GCI6729G057. Position the forklift forks on top of the internal plates. Tighten eight bolts to secure the lifter on to the forklift forks. Use a chain to secure the lifter to the forklift frame. See figure above.</p> <p><b>Power Module Removal</b><br/>Carefully slide the lifter into PM forklift provisions. Lift the PM no more than 1/2" away from the tray and remove it.</p> <p>PCS4060P225 REV 0</p>   |
| <p>Lifting Provisions (GCI6729G055/PC67209G379) Not To Be Used With Maintenance Cubicle</p> <p>PC6729G379<br/>CHAIN<br/>CHAIN SLINGS<br/>Racking Latch Rod Head (Four)<br/>AC Neutral Bus Link<br/>PM AC Neutral Bus<br/>AC Neutral Bus Link<br/>Handles<br/>120VAC Supply Cable Connection<br/>AC Connection Assembly<br/>Control Signal Cable Connection<br/>Angles<br/>PM STOPPER BEHIND PM TRAY<br/>Power Module Tray In Lowered Position</p> <p>Rear Enclosure Wall Bracket<br/>Latched Position<br/>Unlatched Position<br/>Latch Bracket<br/>Latch Rod<br/>Power Module Tray In Upright Position<br/>AC Neutral Bus Link, PMU<br/>Horizontal Bracing<br/>Remove Hardware<br/>Loosen Hardware<br/>Control Wiring Cover<br/>AC Terminals Cover</p> | <p><b>Power Module Reinstallation</b></p> <ol style="list-style-type: none"> <li>Reverse the procedure followed during disconnection and removal of power module.</li> <li>Ensure that control signal cable and 120VAC supply cable are properly reconnected.</li> <li>Reinstall all hardware previously removed.</li> <li>Torque all electrical connections (5/16-18 hardware) to 10-15 ft.-lbs.</li> </ol> <p><b>Power Module Removal</b></p> <ol style="list-style-type: none"> <li>Undo and remove two PM Stoppers.</li> <li>Loosen the four racking latch rods to release PM</li> <li>Use an enclosure bracket to pull it out and position it on the PM Tray until the PM comes in contact with the angles.</li> <li>For overhead lifting, connect GCI6729G055 and PC67209G379 by sling chains and secure.</li> <li>Carefully lift PC67209G379 and slide GCI6729G055 onto the Power Module.</li> <li>Lift the PM no more than 1/2" away from the tray and remove it.</li> <li>For front lifting, remove the two angles attached on the tray and refer to the instruction for lifting provision GCI6729G057.</li> </ol> <p><b>Power Module Disconnection</b></p> <ol style="list-style-type: none"> <li>Remove horizontal bracing (four 1/4-20 bolts w/ hardware).</li> <li>Remove AC terminals cover (two 1/4-20 bolts w/ hardware).</li> <li>Release PM tray from lock position and set to lower position.</li> <li>Disconnect AC connection assembly (eight 5/16 - 18 nuts w/ hardware).</li> <li>Swing control wiring cover down (remove two 1/4-20 bolts, and loosen two 1/4-20 bolts).</li> <li>Disconnect and hide control signal cable and 120 VAC supply cable from module.</li> <li>Remove AC neutral bus links connected to PM.</li> </ol> <p><b>WARNINGS</b></p> <ol style="list-style-type: none"> <li>Disconnect power and wait 15 minutes for capacitors are discharged before performing inspection or maintenance.</li> <li>Proper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals.</li> <li>Take care not to disturb fiber optic cables when handling power module.</li> <li>Power Module (PM) approximate weight is 1,100 lbs. Use appropriately rated chain slings.</li> </ol> |

## DRIVE INSTALLATION DRAWINGS (cont'd)

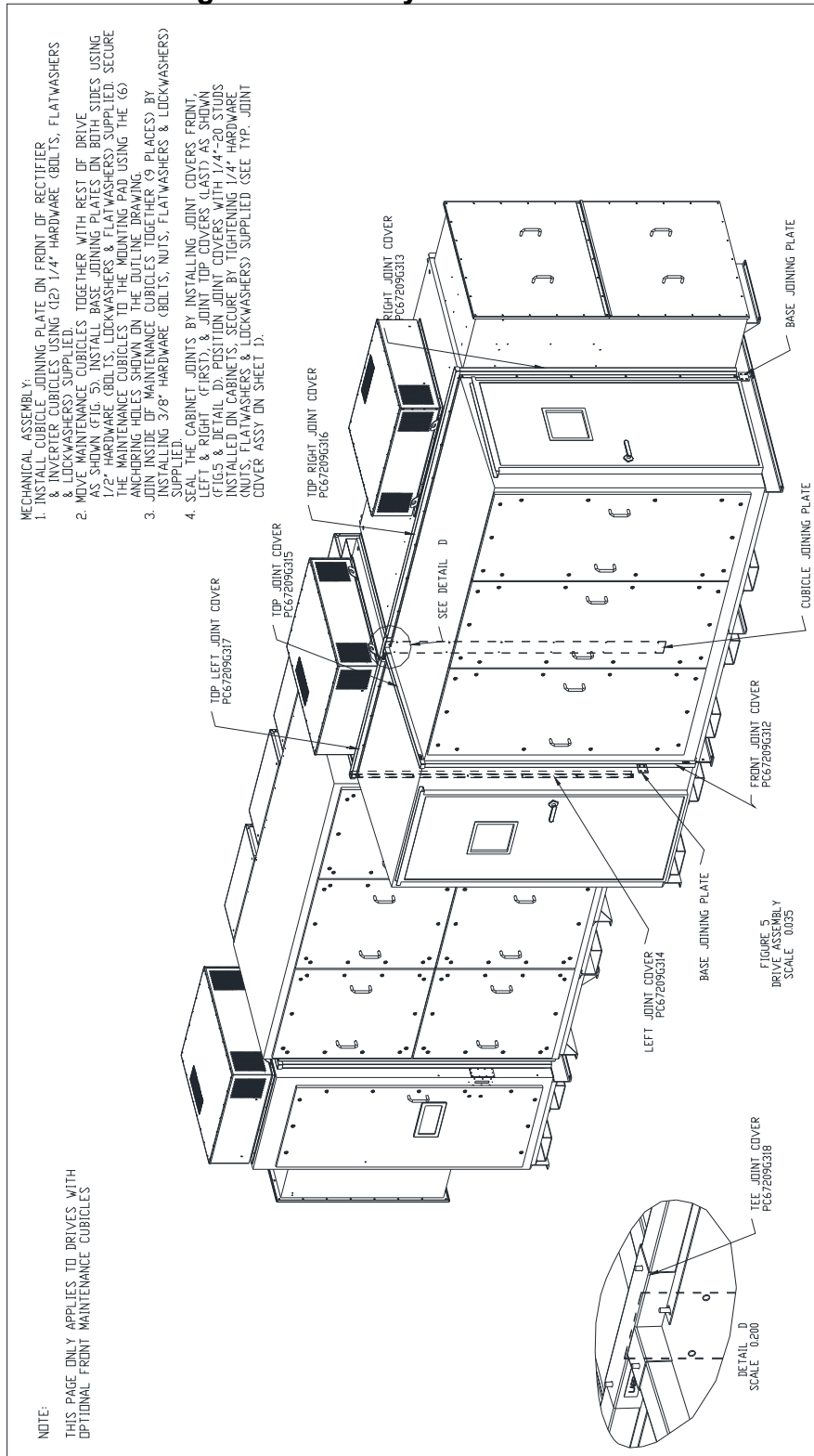
### Frame MTX2-60 drive lifting and assembly



## DRIVE INSTALLATION DRAWINGS (cont'd) Frame MTX2-60 drive lifting and assembly continued



## DRIVE INSTALLATION DRAWINGS (cont'd) Frame MTX2-60 drive lifting and assembly continued



## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A4R module lifting and installation Inverter

**WARNINGS**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GCI6720G055 and a lifting device rated 250 lbs minimum for removal and installation of modules.

**Power Module Removal**

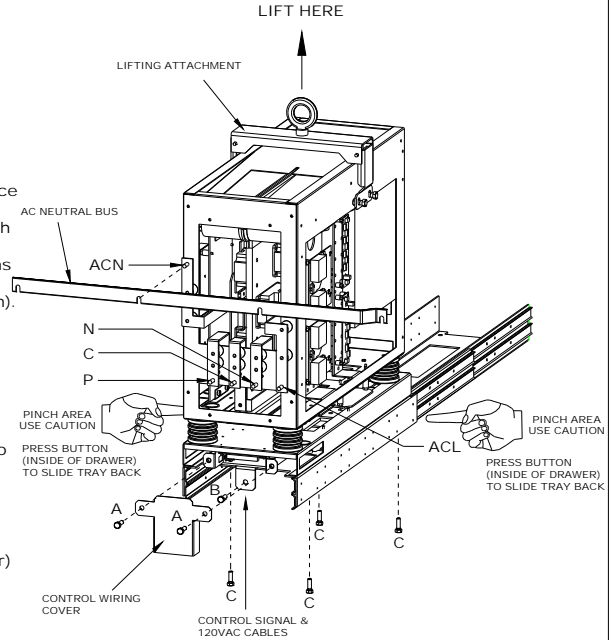
1. Disconnect and remove AC neutral bus.
2. Disconnect power cables ACL, P, C & N.
3. Remove control wiring cover (two "A" bolts)
4. Disconnect control signal cable and 120VAC supply cable from module.
5. Free slide tray by removing bolt "B".
6. Pull slide tray out until slides lock.
7. Remove four "C" bolts which secure module to tray.

**Power Module Removal (cont'd)**

8. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reconnect power cables ACL, P, C & N.
9. Reinstall AC neutral bus.
10. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.



PC94060P086

### Converter

**WARNINGS**

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GCI6720G055 and a lifting device rated 250 lbs minimum for removal and installation of modules.

**Power Module Removal**

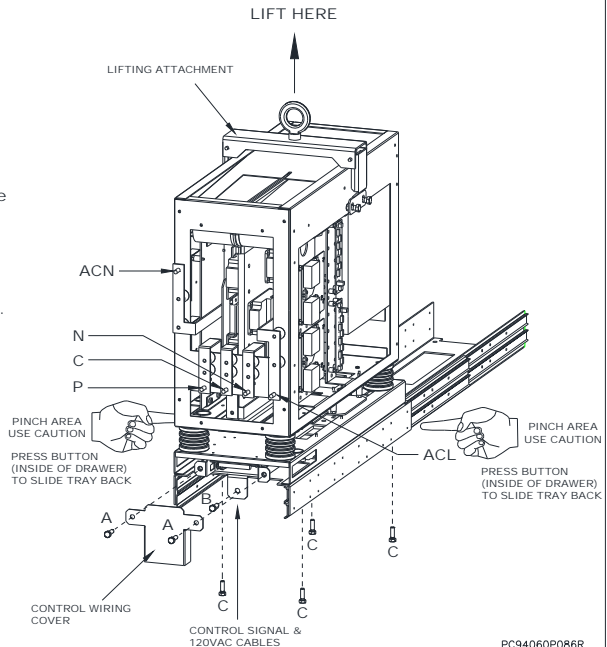
1. Disconnect power cables ACL, P, C, N & ACN.
2. Remove control wiring cover (two "A" bolts)
3. Disconnect control signal cable and 120VAC supply cable from module.
4. Free slide tray by removing bolt "B".
5. Pull slide tray out until slides lock.
6. Remove four "C" bolts which secure module to tray.

**Power Module Removal (cont'd)**

7. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

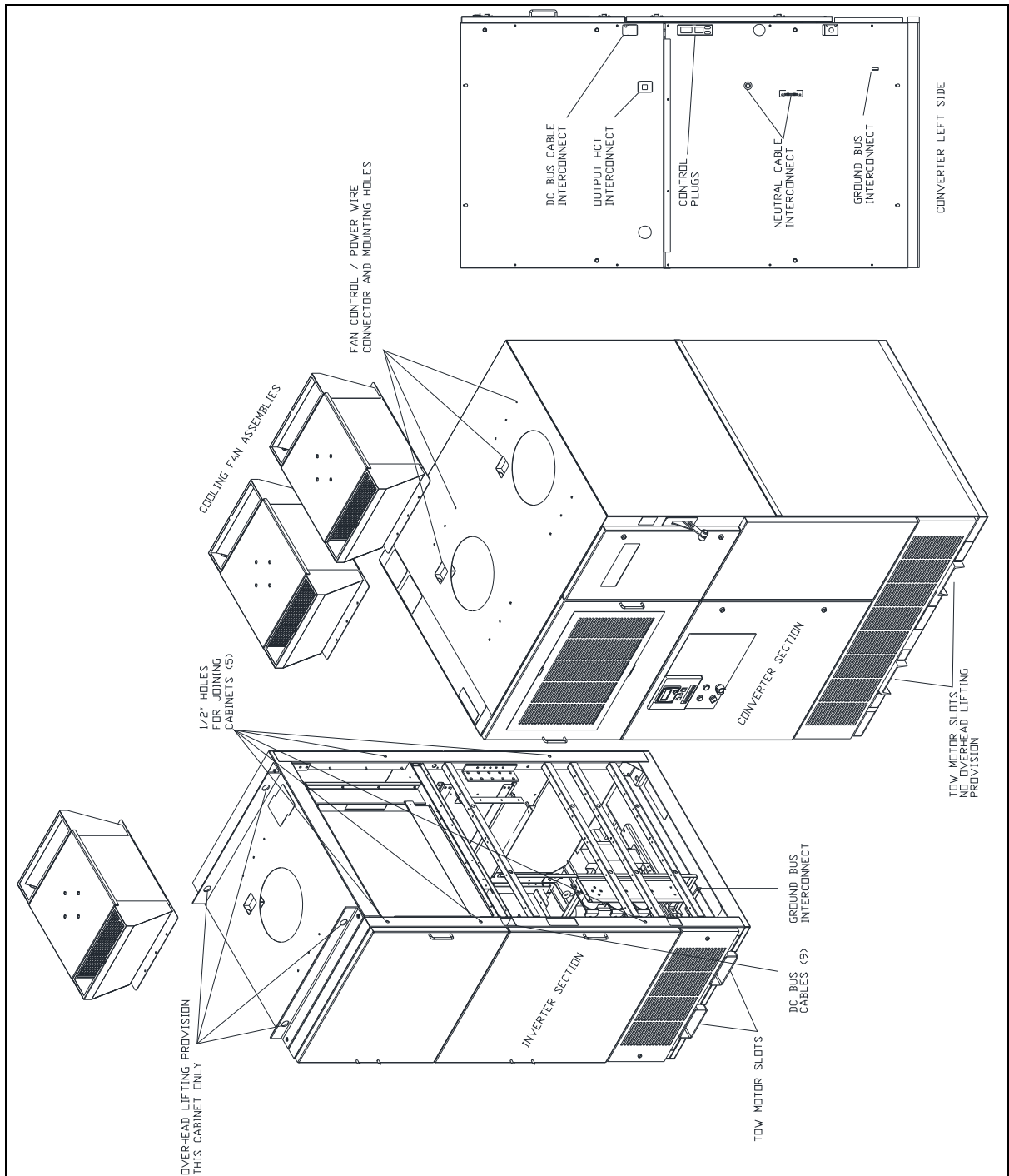
1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reinstall bolt "B" to secure tray in position.
6. Reconnect control signal cable and 120VAC supply cable to module connectors.
7. Reinstall control wiring cover and secure with two "A" bolts.
8. Reconnect power cables ACL, P, C, N & ACN.
9. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.



PC94060P086R

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame A4R drive lifting and assembly





## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B4R module lifting and installation Inverter

**WARNINGS**  
Inverter cabinet is top heavy. Cabinet must be anchored to floor before withdrawing power modules to prevent tipping.

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GC16721G055 and a lifting device rated 350 lbs minimum for removal and installation of modules.

**Power Module Removal**

1. Disconnect and remove AC neutral bus.
2. Disconnect power cables ACL, P, C & N.
3. Remove control wiring cover with two "A" & two "B" bolts
4. Disconnect control signal cable and 120VAC supply cable from module.

**Power Module Removal (cont'd)**

5. Pull slide tray out until slides lock.
6. Remove four "C" bolts which secure module to tray.
7. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reconnect control signal cable and 120VAC supply cable to module connectors.
6. Reinstall control wiring cover and secure with two "A" & two "B" bolts.
7. Reconnect power cables ACL, P, C & N.
8. Reinstall AC neutral bus.
9. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.

### Converter

**WARNINGS**  
Inverter cabinet is top heavy. Cabinet must be anchored to floor before withdrawing power modules to prevent tipping.

Disconnect power and wait 15 minutes to ensure capacitors are discharged before performing inspection or maintenance.

Improper handling of the fiber optic cables and connectors may cause drive failure due to problems transmitting signals. Take care not to disturb fiber optic cables when handling power module.

Use module lifting attachment GC16721G055 and a lifting device rated 350 lbs minimum for removal and installation of modules.

**Power Module Removal**

1. Disconnect power cables ACL, P, C, N & ACN.
2. Remove control wiring cover with two "A" & two "B" bolts
3. Disconnect control signal cable and 120VAC supply cable from module.

**Power Module Removal (cont'd)**

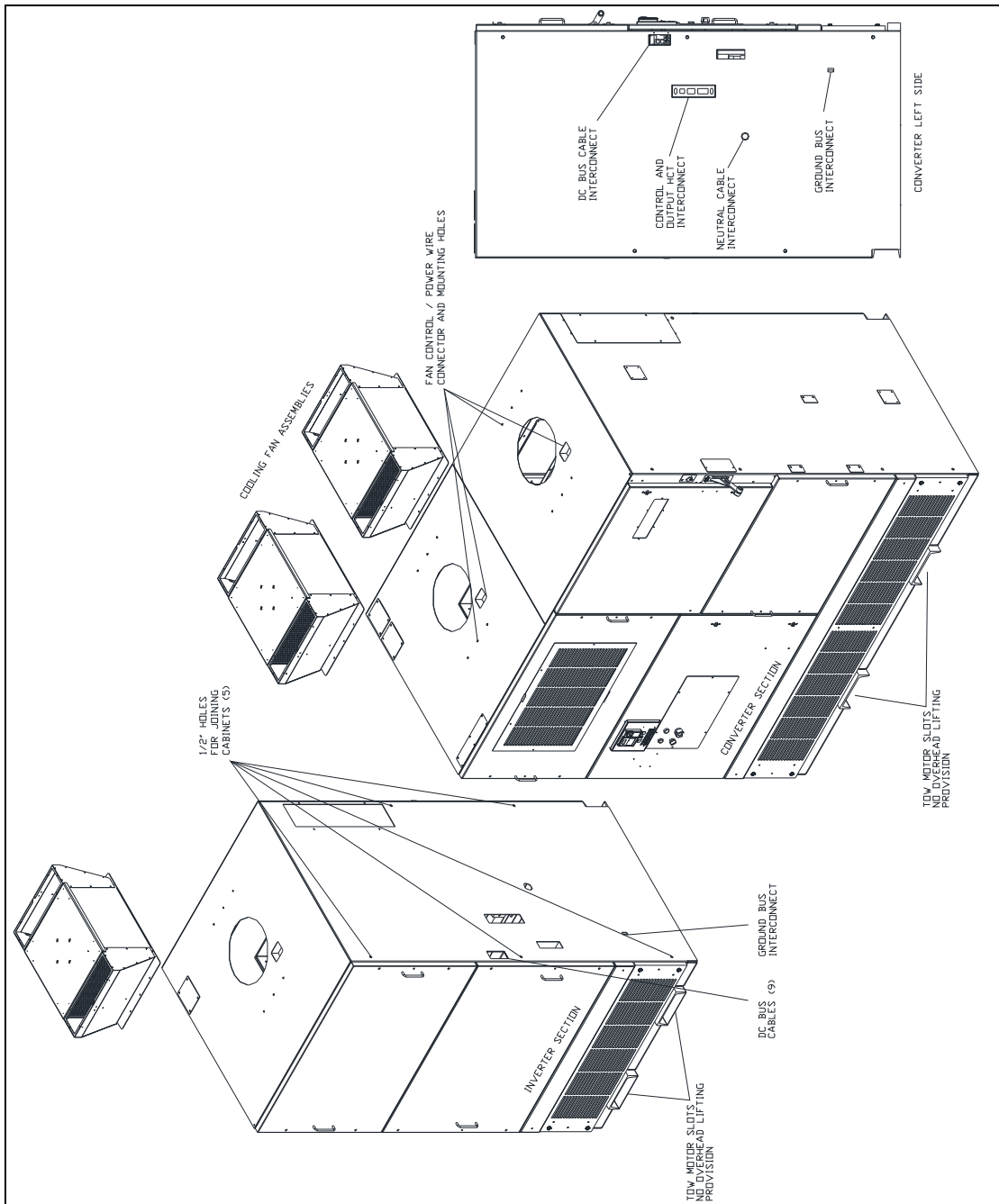
4. Pull slide tray out until slides lock.
5. Remove four "C" bolts which secure module to tray.
6. Using module lifting attachment and lifter, lift module from tray.

**Power Module Installation**

1. Pull slide tray out until slides lock.
2. Using module lifting attachment and lifter, place module on tray.
3. Secure module to tray with four "C" bolts.
4. Press slide release buttons and slide module into compartment (use caution).
5. Reconnect control signal cable and 120VAC supply cable to module connectors.
6. Reinstall control wiring cover and secure with two "A" & two "B" bolts.
7. Reconnect power cables ACL, P, C, N & ACN.
8. Torque all power connections (5/16-18 hdwr) to 10-15 ft-lbs.

## DRIVE INSTALLATION DRAWINGS (cont'd)

### Frame B4R drive lifting and assembly



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# TOSHIBA

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